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CORONA J

PERFORMANCE EVALUATION REPORT

MISSIONS 1043-1 and 1043-2

FTV 1637 J-42

21 JUNE 1968

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on NOV 26 1997

APPROVED

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Manager
Advanced Projects

APPROVED

[REDACTED]
Manager
Program

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FOREWORD

This report details the performance of the payload system during the operational phase of the Program [REDACTED] Flight Test Vehicle 1637.

Lockheed Missiles and Space Company has the responsibility for evaluating payload performance under the Level of Effort and "J" System contracts.

This document is the final payload test and performance evaluation report for Missions 1043-1 and 1043-2 which was launched on August 7 1967.

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INTRODUCTION

This report presents the final performance evaluation of CORONA Mission 1043. The purpose of this report is to define the performance characteristics of the J42 payload system and to evaluate the technical characteristics of the Mission, including analysis of any inflight anomalies.

The payload system was assembled, tested, and certified for flight at the Advanced Projects (A/P) facility of Lockheed Missiles and Space Company (IMSC). A/P also provided flight support, and mission reports to the community. The initial evaluation of the recovered film was made by NPIC personnel at the processing facility. The full Performance Evaluation Team included representatives of IMSC, ITEK Corporation, Eastman Kodak Company, and cognizant government organizations. The P.E.T. meeting took place at NPIC. Off-line evaluation, using engineering photography acquired over the United States, was performed at facilities of individual contractors.

The quantitative data summarized in this report is obtained from diverse organizations. The Diffuse Density measurements and MTF/AM resolution data are produced by the Air Force Special Projects Production Facility. Vehicle attitude readings and frame correlation times are provided by NPIC. The Processing Summary report is published by [REDACTED]

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These quantitative data are used by A/P computer programs to provide processed information allowing correlation of operational photographic conditions with image quality. Analyses are made of image smear components and limiting ground resolution, and also of illumination/exposure, processing components in order to investigate exposure criteria.

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SECTION 1

MISSION SUMMARY

A. MISSION OBJECTIVES

The CORONA/J1 payload J42 was designed and programmed to acquire and return search, cartographic, and reconnaissance photography of selected areas of the earth from orbital altitudes. Two seven-day mission segments were planned, both nominally to return over 5900 panoramic frames of photography, each covering approximately 1725 square nautical miles.

The payload section was a standard J1 configuration consisting of a space structure containing two panoramic cameras and associated control/support equipment, with separate stellar-index cameras and recovery subsystems for each mission segment. Figure 1-1 presents an inboard profile of the J42 configuration.

On-orbit support was provided by AGENA satellite vehicle #1637. These functions included real-time command and telemetry links, electrical power, stored payload program timer, and attitude stabilization and control.

B. MISSION DESCRIPTION

The payload was launched from Vandenburg Air Force Base at 2142.75 Z on 7 August 1967, on THORAD SLV #510. The booster burned to propellant depletion, but failed to attain the required velocity by 254 feet/second. This resulted in the AGENA vehicle also burning to propellant depletion, with 39 feet/second velocity lacking at the end of burn. The resultant orbit was low at perigee,

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apogee, and in period; the parameters were outside the anticipated three-sigma dispersions.

The comparison of planned and actual orbit parameters is tabulated as follows:

ORBITAL PARAMETERSORBIT PARAMETERS AND OAS EFFECTS

<u>Parameter</u>	<u>Predicted</u>	<u>Actuals</u>
Period (Min.)	90.11	89.62
Apogee (N.M.)	204.5	181.33
Perigee (N.M.)	99.4	95.10
Eccentricity	0.0147	0.0121
Inclination (Deg.)	80.00	79.98
Argument of Perigee (Deg.)	163	188

Single OAS rockets were fired on Rev 2, Rev 7, and Rev 19. All telemetry monitors and subsequent orbital parameters confirmed successful operation. The three rockets added velocities of 15.6, 15.2, and 14.4 feet per second, respectively. The nominal orbital period was achieved after the third OAS firing:

OAS ROCKET PERFORMANCE

<u>Parameter</u>	<u>Rev 20 Actuals</u>
Period (N.M.)	90.07
Apogee (N.M.)	197.60
Perigee (N.M.)	102.80
Eccentricity	0.0132
Inclination (Deg.)	79.97
Argument of Perigee (Deg.)	173.07

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Tracking and control support was effected by the Air Force Satellite Control Facility, under central control of the Satellite Test Center at Sunnyvale, California. Tracking and command stations are located at [REDACTED]
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Mission segment 1043-1 consisted of a seven-day operation followed by air recovery of the capsule on 14 August. Mission segment 1043-2 was completed with an air recovery on 22 August, following an eight-day photographic operation.

C. PANORAMIC CAMERAS

The forward camera suffered a loss in image quality due to an erratic scan rate which finally caused complete film pull-out of the rails on Rev 228. All film transport functions ceased on Rev 230.

The aft camera performed satisfactorily throughout the mission and the image quality of the aft material was good and consistent throughout.

D. STELLAR-INDEX CAMERAS

The "A" S/I operated satisfactorily. Flare affected approximately 50 percent of each stellar frame.

The "B" S/I operated normally. Minor fog appeared intermittently throughout the entire mission on the Index camera.

E. RADIATION DOSAGE

Radiation encountered during the mission was well below the levels which would degrade the photography, as indicated by the dosimeter packets.

F. OTHER SUB-SYSTEMS

The clock, instrumentation, pressure make-up, command and thermal control subsystems performed satisfactorily.

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SCHEMATIC INBOARD PROFILE - CORONA J-42 SYSTEM

MISSION 1043

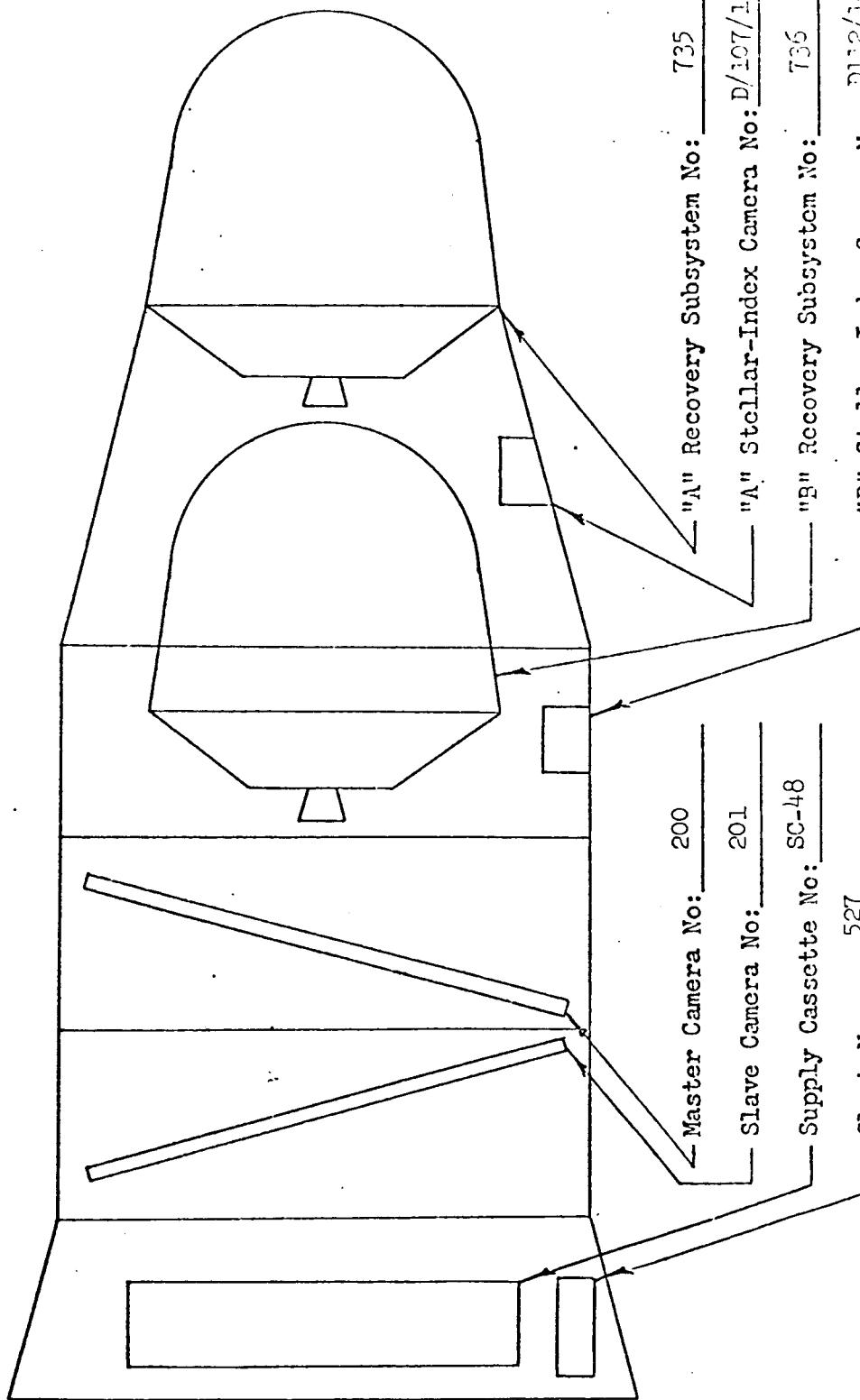


FIGURE 1-1

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MASTER PANORAMIC CAMERA

A. COMPONENT ASSIGNMENT

<u>Component</u>	<u>Serial Number</u>
Main Camera Serial	200
Main Camera Lens	2092435
Input Horizon Camera	286-G6
Input Horizon Camera Lens	E12841
Output Horizon Camera	286-G5
Output Horizon Camera Lens	E12870
Supply Cassette	SC-48

B. CAMERA DATA AND FLIGHT SETTINGS

Panoramic Camera:

Lens	24" f/3.5
Slit Width	0.200 in.
Filter Type	Wratten 23A
Film Type	Eastman 3404

Horizon Cameras:

	<u>Input (Port)</u>	<u>Output (Starboard)</u>
Lens	55 mm f/6.3	55 mm f/6.3
Aperture Setting	f/6.3	f/8.0
Exposure Time	1/100 second	1/100 second
Filter Type	Wratten 25	Wratten 25

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SLAVE PANORAMIC CAMERA

A. COMPONENT ASSIGNMENT

<u>Component</u>	<u>Serial Number</u>
Main Camera Serial	201
Main Camera Lens	2152435
Input Horizon Camera	204-G6
Input Horizon Camera Lens	E12837
Output Horizon Camera	304-G5
Output Horizon Camera Lens	E12862
Supply Cassette	SC-48

B. CAMERA DATA AND FLIGHT SETTINGS

Main Camera:

Lens	24" f/3.5
Slit Width	0.150 in.
Filter Type	Wratten 21
Film Type	Eastman 3404

Horizon Cameras:

	<u>Input (Starboard)</u>	<u>Output (Port)</u>
Lens	55 mm f/6.3	55 mm f/6.3
Aperture Setting	f/8.0	f/6.3
Exposure Time	1/100 second	1/100 second
Filter Type	Wratten 25	Wratten 25

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STELLAR-INDEX CAMERAS

Mission 1043-1

Mission 1043-2

A. Component Assignment

Camera, Assembly No.	D/107	D-112
Index Reseau No.	135	143
Stellar Reseau No.	135	139

B. Camera Data and Settings

Stellar Camera

Lens Type	85 mm f/1.8	85 mm f/1.8
Exposure Time	1 second	2 seconds
Film Type	Eastman 3401	Eastman 3401

Index Camera

Lens Type	38 mm f/4.5	38 mm f/4.5
Exposure Time	1/500 second	1/500 second
Film Type	Eastman 3400	Eastman 3400
Filter Type	Wratten 21	Wratten 21

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SECTION 2

PRE-FLIGHT SYSTEMS TEST

A. ENVIRONMENTAL TESTING

1. Test Objective

As a standard procedure, the J payload systems are subjected to thermal/altitude testing, which simulates on-orbit environment. The purpose is to demonstrate proper electrical and mechanical function under simulated operational conditions. One of the test objectives is to determine the degree of system susceptibility to Corona discharge, which fogs the film and degrades operational photography.

2. Test Summary

The J-42 altitude environmental test was conducted in the HIVOS facility from 13 to 19 October 1966. Performance of the payload system was adequate to demonstrate satisfactory performance, and to define certain problem areas. Problems evident during the test were individually remedied without altitude retesting; these include the pan geometry data recording, "two-pi" corona, cycle rate differences, and miscellaneous minor anomalies. The general appearance of the film was good.

A total of 109 operations were run during the test, including 4 mono operations for each camera; the Master consumed 4584 frames (12125 ft) and the Slave 4474 frames (11835 ft). This does not include the pre-HIVOS PG confidence test or the post-HIVOS exposure check. Chamber pressures ranged as low as 0.7 microns.

Both panoramic cameras evidenced various problems concerning the PG data recording; the lens scan lines and rail hole images on both had occasional abnormalities. In general, PG performance was disappointing, but the lack of specific acceptance criteria made evaluation difficult.

Rail hole images appeared generally adequate, when seen, the Master camera being better. The Master dots were initially fairly light, but diminished in density during the HIVOS test so that detection was very difficult by test end. These dots appeared normal during both the pre-and post-HIVOS tests. This situation is similar to the tests of J-36 and J-38, where acceptable flight data recording resulted.

The Slave data block-side rail showed a variable history, with up to 6 images missing and 20 rated as relatively light or faint. The time trace side images were generally elongated. The Slave rail lamps blinked off shortly after each scan start in the pre-chamber test and the first HIVOS operation because of abraded lamp wiring. This anomaly has not been noted since the wires were replaced after the test.

The Master lens scan lines were noted missing on 9 frames and partially missing on 50 others; six operations were affected. The line near the time trace disappeared into the format edge $2\frac{1}{2}$ inches before scan end. Density and width varied between lines in the HIVOS test; densities ranged from heavy to unacceptably light. Lines on the pre-chamber test could not be evaluated because of high background fog level, those on the post-chamber test appeared much more even.

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The Slave lens scan lines were noted to turn on after scan start on the first frame of 3 operations, and were noted missing on the last frame of 8 others. A moderate density variation occurred both between the lines within a frame, and occasionally for a single line within a frame. The lines were frequently relatively faint, especially during the faster operations. The lines appeared more even in the material from the post-chamber test.

Startup corona occurred with faint to light density on 10 master operations, and with medium density on a single Slave operation. Instrument pressures ranged from 1 to 15 microns. This type and frequency of corona marking is considered acceptable.

Light to medium density two-pi type marking was found on the master film early in the "A" test, at internal pressures of 20 to 26 microns. Twenty frames in five successive operations were marked at 6.3 inch intervals. In all cases, the affected film was well within the supply cassette at the start of camera operation, indicating a gradual potential buildup on the metering roller. While two-pi marking is defined as unacceptable, customer waiver was recommended because of (a) lack of severity of the marking, and (b) the pressure range at which the marks occurred, being too high for no PMU augmentation, and too low with PMU for a sustained flight situation.

The unacceptably slow Slave camera cycle rates were subsequently adjusted. Based upon P/E frame counts, rate differences up to 9% were noted between Master and Slave cameras. There is a possible correlation with the appearance of the Slave time trace and lens scan lines (above) which showed

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irregular movement of the scan arm during several operations, at start-up or at slow rates. This irregularity may also be related to the interlock assemblies, which required modification prior to a successful resolution test.

The binary data recording and block area was adequate on both instruments. All binary bits were observed. The start-of-pass marks, serial numbers, and indices were present. The index bit near the serial numbers of both cameras were heavy and bloomed; lamp attenuation was recommended. Occasional dim serial number, block indices, etc., were noted on the Slave, but minor in effect; it is attributed to variation in voltage supplied the system via HIVOS chamber cabling.

One clock word was missing on the Slave; the block serial number and indices were present. No action was recommended, for this frequency of occurrence.

The horizon camera data recording was adequate. Slave fiducials were good; Master fiducials, while usable, were enlarged and not sharp. Both slave H.O.'s exhibit characteristic minor pressure marks.

The 200 PPS time trace was adequate on both cameras. Extra non-periodic time pips were frequently noted near the center-of-format switch closures and occasionally by the blanking pulses. An extra pip occurred in the Slave blank pulse during the pre-HIVOS test. These anomalies were acceptable, in that it was unlikely that they would cause problems in timing the slit position during post flight analysis.

Very light rail scratches and edge marks were encountered on film from both cameras. The characteristic scan head roller scratches appear at scan start, near the data block, and near the blank pulse. There were

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relatively few discharge marks. The film generally appeared very clean, excepting frequent heavy multiple scratches on the Master, in particular, which were caused by the film processor. These scratches made it difficult to detect any marks made by the camera during the tests. Film retrieval caused much less marking than normal.

There were no Stellar/Index cameras installed for this test. The -3 Programmer functioned properly.

Clock accuracy was satisfactory with a total offset of .072 seconds in five (5) days when compared to IRIG C.

The Pressure Make-Up system operated normally. Average gas consumption was 7.2 PSIA per minute of operate. Internal pressure increased to 45 microns during RMU operates.

The Command System operated properly with the exception of the off command brush for one program. It did not function the first time it was given. However, the second attempt was successful. This problem was traced to a defective Brush 47 switch in the test control console.

Transfer from A to B was accomplished by KZ-38 and all transfer functions occurred normally.

Both recovery sequence of events occurred properly.

The O.S.F.G. operation was satisfactory during the test. One complete O.S.F.G. operation period was run in each of the A and B modes of the test.

B. RESOLUTION TESTS

Resolution and Theodolite testing was performed on 1 November 1966 and 23 November 1966 respectively. Evaluation of the low contrast resolution data of the first test indicated the slave camera (No. 201) did not meet acceptance criteria. Slave camera resolution at the collimator zero

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focus position, 75 lines/mm, was less than the 90 lines/mm required; peak focus occurred 0.002 inches behind the film plane. The master camera was well within specification with peak resolution of 113 lines/mm at the zero position.

A retest of J-42 system resolution was accomplished. Evaluation of low-contrast data indicated that both cameras performed well within acceptance criteria. The camera system had been modified by adjustment of the detent mechanism and the cycle rates. Results of the 2nd thru-focus resolution tests of pan instruments 200 and 201 showed the following characteristics:

Master Pan Instrument No. 200

Maximum high contrast resolution 195 lines/mm at zero focal position.

Maximum low contrast resolution 118 lines/mm at zero focal position.

Slave Instrument No. 201

Maximum high contrast resolution 194 lines/mm at +.001 focal position.

Maximum low contrast resolution 116 lines/mm at +.001 focal position.

The test data for both instruments is shown in Figures 2-1 and 2-2. Both instruments met the system requirements specification.

PREF-FLIGHT DYNAMIC RESOLUTION

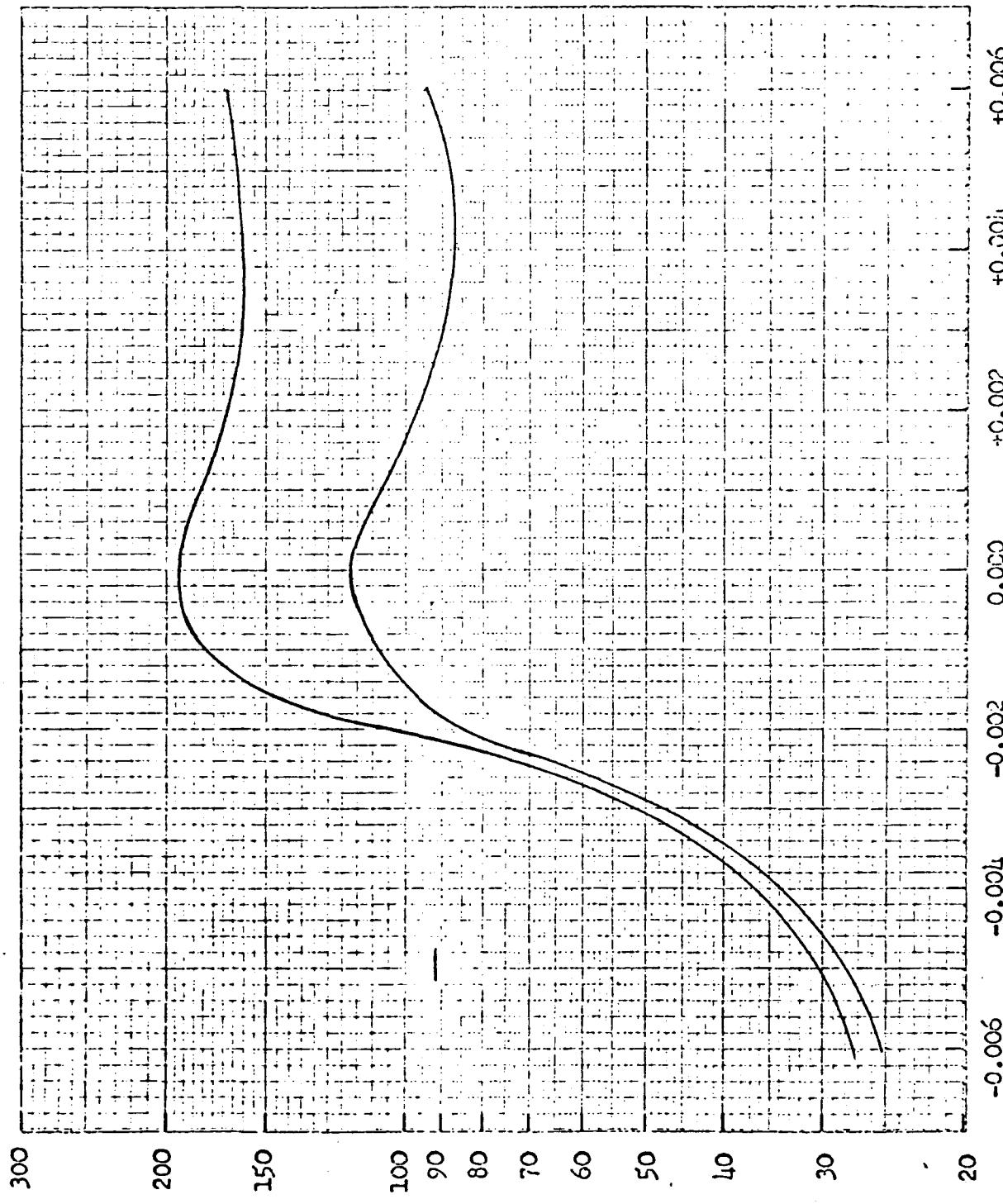


FIGURE 2-1

Camera No: 200

Payload No: J-12

Resolution (l/mm)

High Contrast: 195

Low Contrast: 118

Film Type: 3404

Test Date: 11/29/66

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PRE-FLIGHT DYNAMIC RESOLUTION

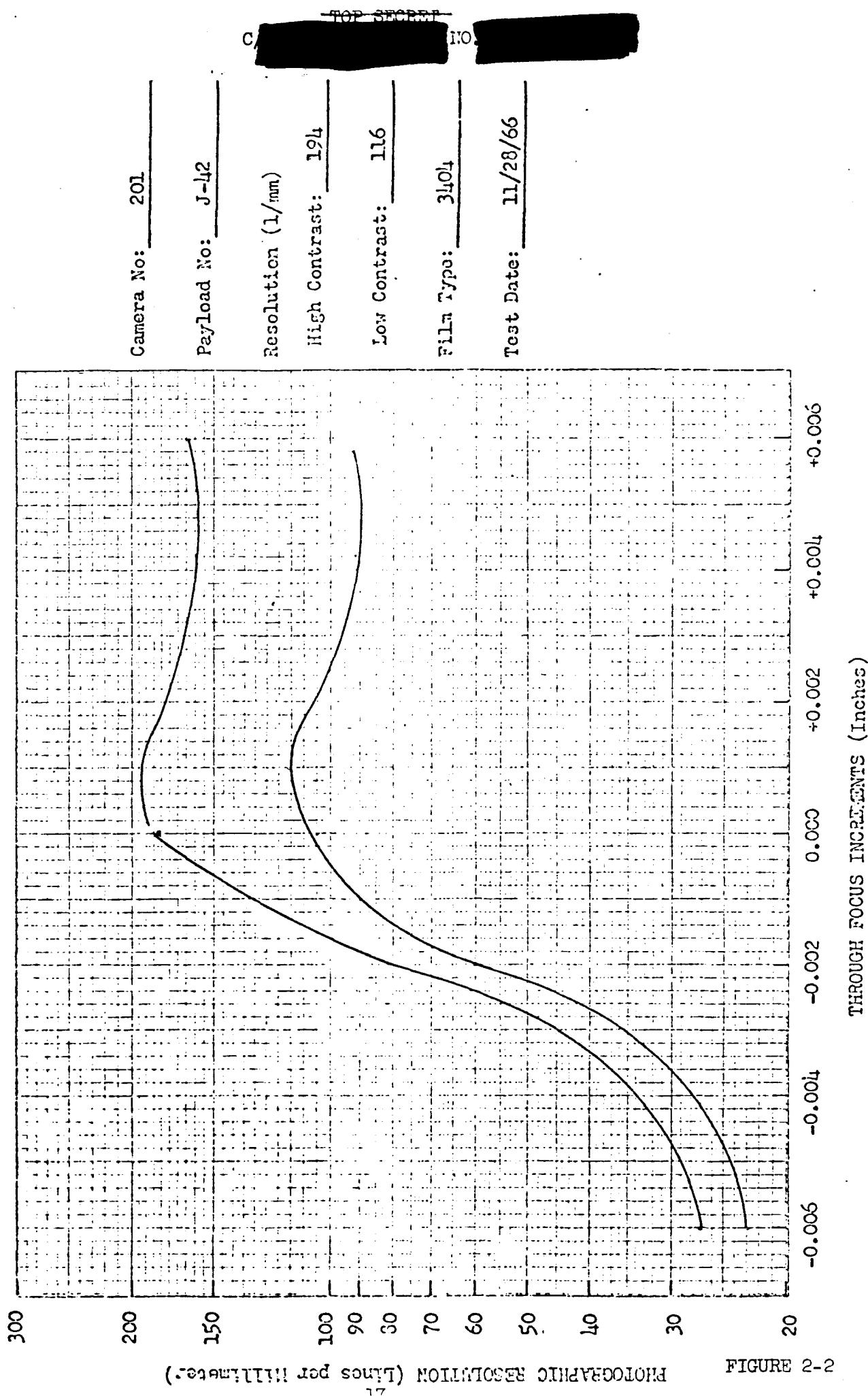


FIGURE 2-2

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C. LIGHT LEAK TEST

The J-42 system was tested for light leaks on 14 November, 1966. Several apparent leaks were identified, the heaviest being from the master input H.O. boot area. Other leaks were from both drum boots, from the slave input H.O. boot, and from the top of the "A" forebody.

The master input H.O. boot leak was located, and repair verified by photomultiplier tests. The other leaks were relatively minor. Because of their relatively low level, photomultiplier verification of repair was considered adequate. Light leakage characteristics of the J-42 system were considered acceptable for flight.

D. FLIGHT READINESS AND CERTIFICATION

The flight readiness test of J-42 (PG-3) system demonstrated the capability of both pan cameras (#200 and #201) to produce excellent-appearing material. Data recording and uniformity of format fogging were considered acceptable by both performance evaluation and customer representatives; no rework or retest was necessary. The H. O. fiducials somewhat bloomed, but acceptable. The only questionable area involved the rail holes, where a relatively large number of unacceptable images were found on instrument #201, nine on the time word rail and three on both rails of instrument 200. However, the unacceptable images were within the then-current P.G. acceptance criteria (less than 10 unacceptable images on any rail, with no opposing pairs).

Evaluation of material from the post-storage test of Stellar/Index cameras D107 and D112 indicated generally good-appearing formats. The "B" index (#112) had a dirt particle entrapped behind the reseau plate,

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which is inaccessible for cleaning. The fiducials on both stellars were somewhat dense, but the intersections were clearly visible.

The primary flight film spools were loaded into the pan supply cassette without incident. Samples from the pan and S/I supply spools indicated proper sensitometric performance. No marks or scratches on any film were noted.

The system was assembled and operated for the pre-flight acceptance run. These operations indicated normal system performance. Tracking appeared proper. No film marking or scratching was noted; operation appeared exceptionally clean.

The J-42 system was accepted for flight. Customer review and final buyoff was concluded on 26 July 1967.

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SECTION 3

FLIGHT OPERATIONS

A. SUMMARY

Launch ascent, and injection events occurred as programmed, with the exception of low terminal THORAD velocity and the resultant orbit dispersion. Inflight operations support proceeded normally at A/P, and the STC, with no major problems encountered.

The panoramic cameras appeared to operate properly (per telemetry data) until the middle of the second mission, when indications of possible master film transport problems appeared. This continued until failure was indicated on the last engineering pass prior to recovery. The slave camera operated satisfactorily throughout the flight.

Both stellar-index cameras, the clock system, the instrumentation system, and the yaw steering control operated properly for the duration of the flight. Some command and control difficulties were experienced; the FMC programmer failed to turn off on Rev 1 and continued to run constantly through Rev 5, operating normally thereafter. Only one short operation was affected. The FMC programmer was not started on Rev 120, because of resetting the orbital timer; one operation was seriously degraded. Real-time commands controlling the dual intermix double-stepped on three occasions during the flight, but the errors were corrected by the flight controllers.

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B. PANORAMIC CAMERA OPERATIONS

The telemetry monitors on the film transport system first indicated possible oscillations in Master film motion during a photographic cycle on Rev 175 and continued to deteriorate through Rev 221. The most notable film motion change occurred between photographic scan portions of succeeding cycles. However, this apparent change in film motion has been present on previous systems in which the camera system performance was not degraded.

The cycle rates on both instruments decreased approximately one and one half percent from Rev 159 through the end of the mission.

The relationship of the Master camera center of format and lens rotation monitors had changed on the last engineering pass at Rev 239. This condition is indicative of a stoppage in the film transport system.

The cut and wrap operation and transfer to the -2 recovery system occurred as programmed utilizing the KIK-ZORRO 38 command (early -1 to -2 switchover) on Rev 104 by the [REDACTED] Tracking Station.

FMC Match

The FMC programmer failed to turn off on Rev 1 and ran continuously until normal turnoff on Rev 5. The probable cause was temporary failure of a cam-driven switch.

The V/h ramp to orbit match was otherwise acceptable throughout the flight except for one occasion. On Rev 120 the orbital timer was reset over the V/h start command. This resulted in the FMC programmer remaining at the bottom of the ramp causing the instruments to operate at a very slow cycle rate. The single operation on Rev 120 experienced a high degree of FMC mismatch because of this problem.

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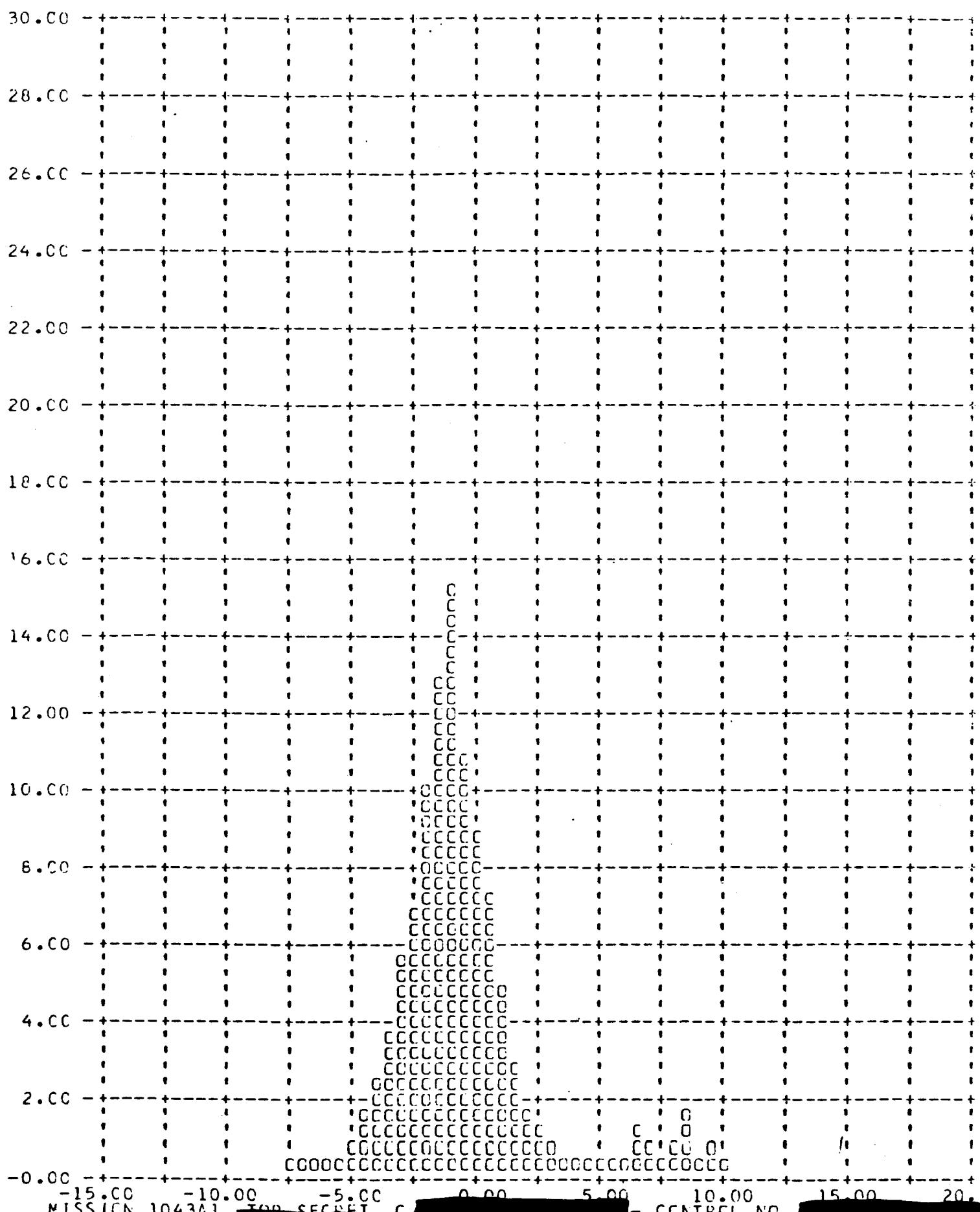
The following settings of RTC 6, 8, and 10 were utilized to obtain the optimum FMC match during the flight. The design of the J-1 ramp programmer limits this optimum FMC match to a nominal band of latitude defining areas of primary interest.

	<u>RTC Commands</u>			<u>Remarks</u>
	<u>6</u>	<u>8</u>	<u>10</u>	
RTC Positions	7	5	6	Launch thru Rev 12
	7	5	9	Rev 13 thru Rev 28
	7	5	10	Rev 29 thru Rev 172
	6	6	10	Rev 173 thru Rev 203
	6	6	11	Rev 204 thru the end of the mission.

The frequency distribution of the V/h errors, Figures 3-1 through 3-4, are computer plotted to show the statistical deviation.

MISSION 1043A1 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED] - FRAMES 1-6 OF EACH CP OMITTED 90 DEGENT = 4.1

Y V/H RATIO ERROR - PERCENT (X) VERSUS FREQUENCY - PERCENT (Y)



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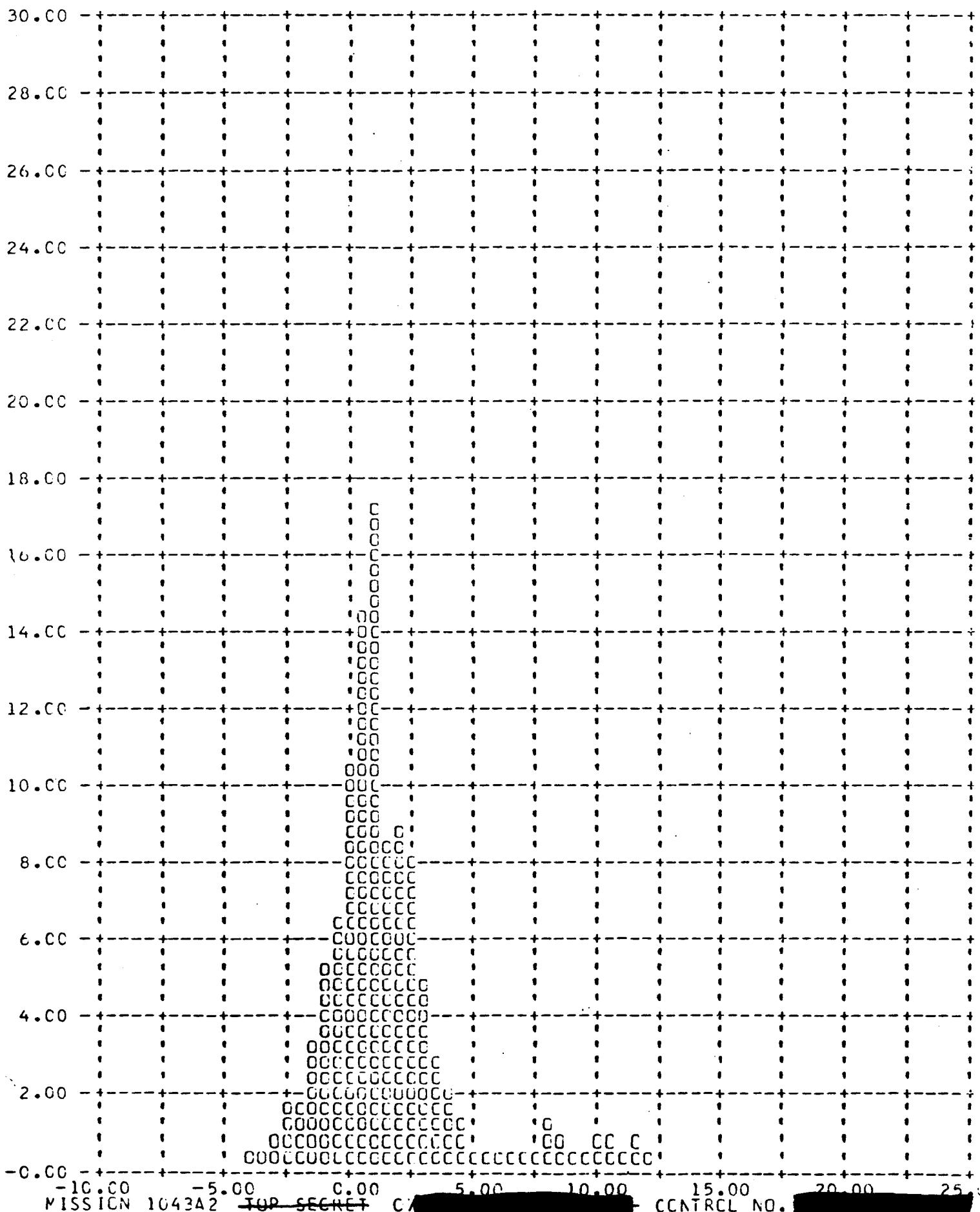
PTC100P

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- CONTROL NO. [REDACTED]
FRAMES 1-6 OF EACH CP CHITTED 90 PERCENT - 20.00

Y V/H RATIO ERROR - PERCENT (X) VERSUS FREQUENCY - PERCENT (Y)

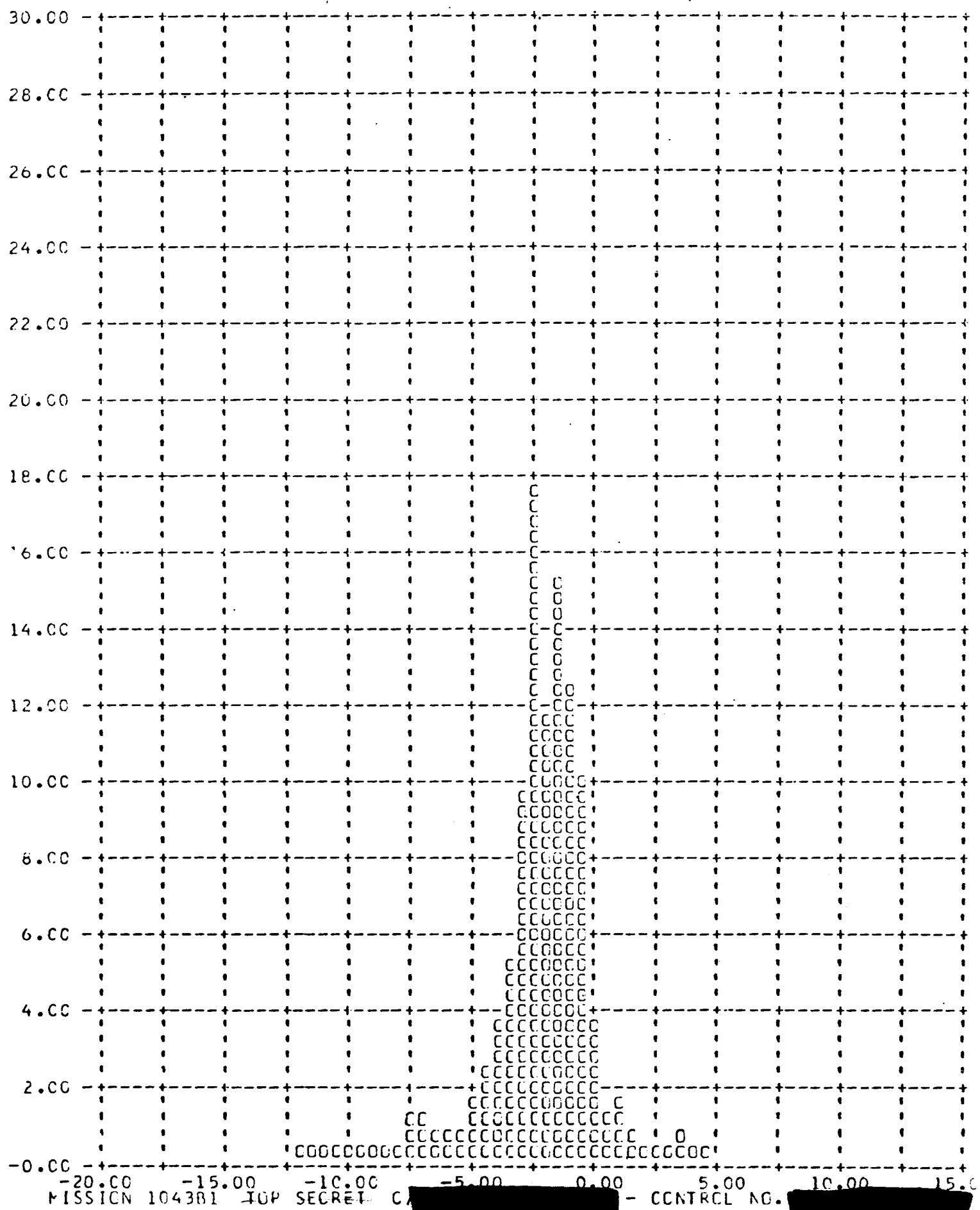
MISSION 1043A2 ~~TOP SECRET~~

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- CONTROL NO. [REDACTED]

MISSION 104381 -~~TOP SECRET~~ C - CONTROL NO. [REDACTED]
FRAMES 1-6 OF EACH CP CRITIED 50 PERCENT 1-20

Y V/H RATIO ERROR - PERCENT (X) VERSUS FREQUENCY - PERCENT (Y)

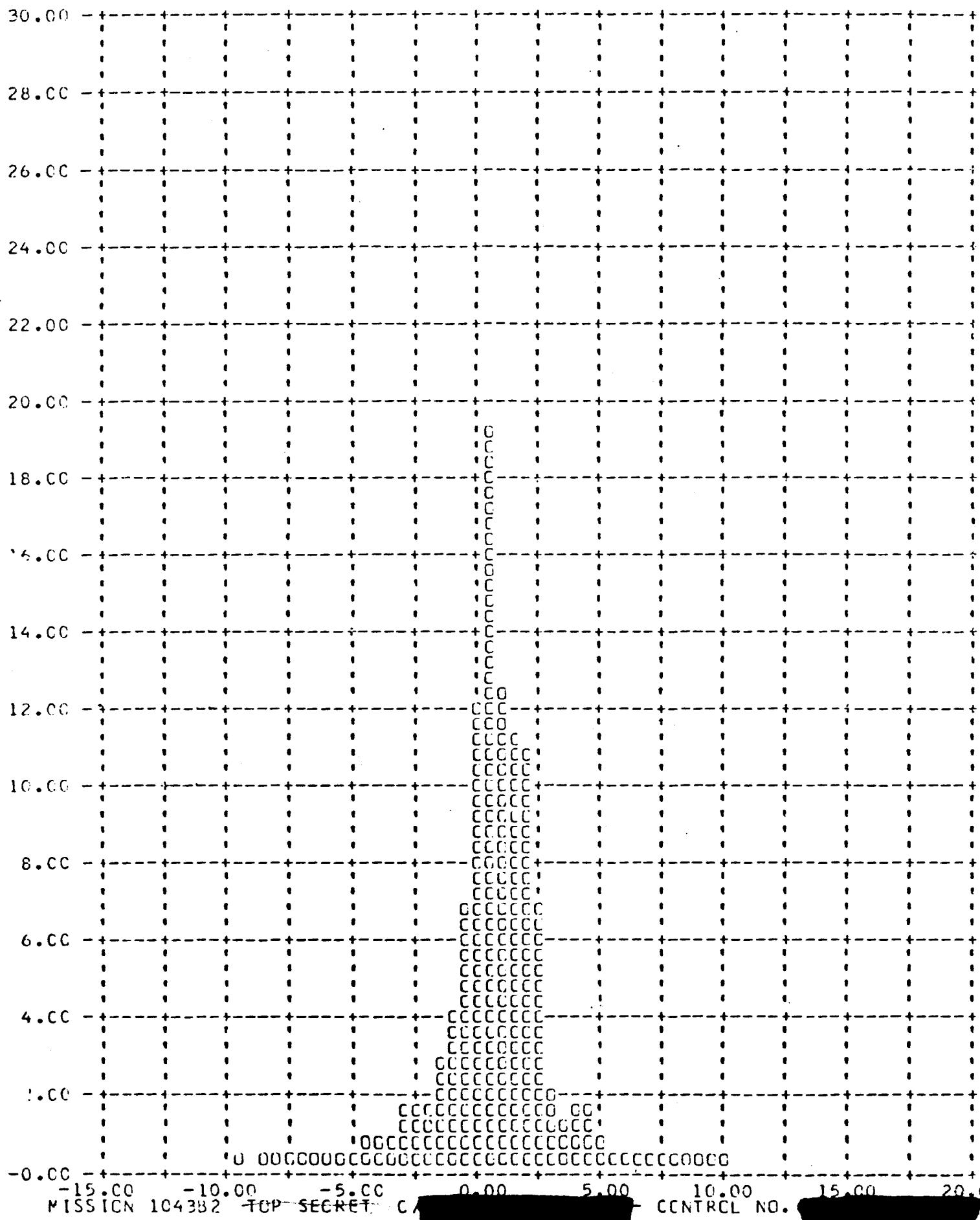


MISSION 104381 -~~TOP SECRET~~ C

- CONTROL NO. [REDACTED]

MISSION 1043B2 -TOP-SECRET- C [REDACTED] - CONTROL NO. [REDACTED]
FRAMES 1-6 OF EACH LP OMITTED 90 percent - 5.0%

Y V/H RATIO ERROR - PERCENT (X) VERSUS FREQUENCY - PERCENT (Y)



MISSION 1043B2 -TOP-SECRET- C [REDACTED]

CONTROL NO. [REDACTED]

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C. STELLAR/INDEX CAMERA OPERATION

Both Stellar/Index cameras operated satisfactorily on all monitored engineering passes. Telemetry data indicated that the programmer, metering functions, and shutter monitors performed satisfactorily.

D. INSTRUMENTATION AND COMMAND SYSTEM PERFORMANCE

The command system performance was satisfactory for both missions. Real time command (RTC) 12 double-stepped on Rev 87 [REDACTED] and RTC 15 double-stepped on Rev 70 [REDACTED] and Rev 198 [REDACTED]. On two of the above occasions the command verification tone dropped out momentarily causing the stepper switch to advance an extra position. The other anomaly could not conclusively be traced to a beacon tone drop-out. All RTC's were recommended to their proper positions prior to acquisition fade, and therefore did not compromise the mission effectiveness. It is assumed that this anomaly was a tracking station problem rather than a command system failure.

This command system had been modified to eliminate the capability of resetting the intermix sequence and the four step counter by commanding RTC 15.

The instrumentation system performed normally throughout the total mission.

E. CLOCK SYSTEM PERFORMANCE

The clock system operation was normal for the duration of the flight. Satisfactory time correlation between the flight clock and [REDACTED] Tracking Station time was obtained. The ratio of clock time to system time was 1.00000014391.

F. PRESSURE MAKE-UP SYSTEM PERFORMANCE

The pressure make-up system performance was normal throughout the flight. Average gas consumption was approximately 9.2 PSI/min for the 255 minutes of total operate time. The system had a surplus of 340 PSIA at the end of the flight.

G. THERMAL ENVIRONMENT

The thermal control pattern on this payload system was modified prior to launch to produce a nominal thermal environment of $70^{\circ} \pm 10^{\circ}$ F.

Temperature data from [REDACTED] acquisitions are included in Tables 3-1 through 3-4. The average instrument temperatures ranged from a high of 68° F and 65° F and a low of 57° F and 54° F on the Master and Slave instruments respectively. Internal temperatures for complete orbits are included in Tables 3-5 and 3-6.

H. RECOVERY SYSTEM

The 1043 first recovery capsule was successfully recovered by air-catch on Rev 113 at 1643 PDT on 14 August. Capsule impact was close to the predicted point. All re-entry events appeared normal and occurred within one second of the predictions.

	<u>Latitude</u>	<u>Longitude</u>
Predicted	$25^{\circ} 00' N$	$158^{\circ} 48' W$
Actual	$24^{\circ} 54' N$	$158^{\circ} 18' W$

The second recovery capsule was successfully recovered by air-catch on Rev 240 at 1451 PDT on 22 August. All re-entry events appeared normal and occurred within one second of the predictions. Capsule impact was approximately 23 N.M. north of the predicted point.

C [REDACTED] NO. [REDACTED]

	<u>Latitude</u>	<u>Longitude</u>
Predicted	22° 26.5' N	149° 19.1' W
Actual	22° 50.8' N	149° 15.0' W

I. RADIATION DOSAGE

Each recovery system flown on a Corona mission contains a sealed packet of Eastman Type 3401 and Royal X Pan emulsions to determine the total radiation received at the take-up cassette. Both film types have been irradiated by IMSC at various levels and the base plus fog densities recorded after controlled processing.

Following recovery the film dosimeter packets are removed and processed at A/P with a pre-flight sample of the same film type and sensitometric control film. The resulting base-plus fog density measurement of the dosimeter strips is used to ascertain the total radiation level. The table below presents the base plus fog readings for the dosimeter strips and the radiation level equivalents.

<u>Emulsion</u>	<u>Mission 1043-1</u>		<u>Mission 1043-2</u>	
	<u>B + F Density</u>	<u>Radiation</u>	<u>B + F Density</u>	<u>Radiation</u>
Type 3401	0.17	0.6 R	0.21	0.9 R
Royal X Pan	0.22	0.3 R	0.29	0.6 R

These levels are below that which will degrade the photography.

REF ID: A65100
 REQUESTED BY: [REDACTED]
 DATE: [REDACTED]

VENUE: 1637

SENSOR

CREDITS ACCRUED

NUMBER/NAME	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
(A)	173	36	64	33	52	23	45	22	45	23	42	22	42	42	42	42	42	42	42	
1	101	5	-1	3	-4	-4	-4	-1	-4	3	-4	3	-4	3	-4	3	-4	3	6	
2	166	0	10	-1	10	-10	0	-7	6	-3	3	-7	3	-7	3	-7	3	-7	3	
3	167	45	45	42	43	32	45	33	42	33	42	33	42	33	42	33	42	33	42	
4	170	53	53	51	54	42	45	45	45	48	44	45	45	45	45	45	45	45	45	
5	139	50	76	64	63	34	57	51	50	51	44	53	44	53	44	53	44	53	44	
6	106	41	50	30	47	31	44	31	41	35	33	31	36	31	36	31	36	31	36	
7	21	37	12	34	69	24	63	30	60	30	25	27	12	27	12	27	12	27	12	
8	131	56	50	53	54	54	54	52	54	56	54	53	54	55	54	55	54	55	54	
9	132	52	42	45	42	42	45	45	45	42	45	45	42	45	45	42	45	45	42	
10	129	45	45	58	55	55	55	55	52	55	45	45	45	45	45	45	45	45	45	
11	102	40	40	22	45	49	35	43	45	43	43	43	43	43	43	43	43	43	43	
12	58	53	53	62	62	62	74	74	74	74	74	74	74	74	74	74	74	74	74	
13	59	53	53	62	62	62	74	74	74	74	74	74	74	74	74	74	74	74	74	
14	54	53	75	64	76	75	73	76	69	72	73	73	73	73	73	73	73	73	73	
15	58	53	62	62	62	62	74	74	74	74	74	74	74	74	74	74	74	74	74	
16	59	53	62	62	62	62	74	74	74	74	74	74	74	74	74	74	74	74	74	
17	40	47	60	65	62	60	62	60	50	65	65	65	65	65	65	65	65	65	65	
18	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	
19	(45.4)	69	43	35	35	35	33	32	35	32	35	32	35	32	35	32	35	32	35	
20	(45.4)	68	55	45	49	47	47	47	45	45	45	45	45	45	45	45	45	45	45	
21	68	45	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42	
22	63	47	43	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42	

Printed on "A" to "B"
 Check

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
1 (45.4)	69	43	35	35	35	33	32	35	32	35	32	35	32	35	32	35	32	35	32
2 (45.4)	68	55	45	49	47	47	47	45	45	45	45	45	45	45	45	45	45	45	45
3	68	45	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42
4	63	47	43	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42

[REDACTED]

TOP SECRET

PASTGRID — J-12

MARCH 1627

TERMINOLOGY

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CRAFTS ACCORDING

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-1

CEMETE A SERV

TABLE 3-3

DATA FILE MTA
TRANSMISSION SUMMARY
10000000 - PAGE

PAYOUT J-62

VEHICLE UC37

CHARGE

CREDITS ACQUIRED

Line No.	111	120	127	136	143	152	160	175	183	191	199	207	215	223	232	239
1	56	54	50	54	49	52	49	51	49	52	50	51	52	53	52	54
2	65	64	59	64	61	62	63	62	62	61	62	60	63	60	61	61
3	65	62	59	62	60	56	55	55	54	54	55	54	55	55	55	56
4	66	64	60	65	65	66	65	65	65	65	64	65	65	65	65	65
5	65	62	60	64	61	62	62	63	62	62	61	62	61	62	62	62
6	65	64	61	64	61	61	60	60	60	60	60	60	60	60	60	60
7	65	64	61	64	61	62	62	62	62	62	62	62	62	62	62	62
8	65	66	62	66	61	62	62	61	60	60	60	60	60	60	60	60
9	65	63	59	61	61	56	55	55	53	57	55	56	56	56	56	56
10	61	62	58	63	63	56	52	55	52	53	50	51	52	51	51	51
11	62	63	56	62	62	55	61	55	60	60	59	59	59	59	59	59
12	61	59	56	59	56	52	53	52	50	53	51	53	52	52	52	52
13	61	63	63	63	60	56	55	55	52	55	55	55	55	55	55	55
Avg. Tug-in Tug-out	60	59	54	56	52	54	52	52	51	52	50	51	51	51	51	51

Line No.	111	120	127	136	143	152	160	175	183	191	199	207	215	223	232	239
1	60	59	55	55	54	52	52	50	51	52	50	52	52	52	51	51
2	60	56	52	51	50	49	49	49	49	49	49	49	49	49	49	49
3	61	59	52	52	51	51	51	51	51	51	51	51	51	51	51	51
4	62	61	55	53	53	52	52	51	51	51	51	51	51	51	51	51
5	61	59	55	53	53	56	53	53	52	55	54	54	54	54	54	54
6	60	55	51	53	52	51	51	50	50	51	50	51	51	51	51	51
7	65	62	50	60	56	56	56	56	56	56	56	56	56	56	56	56
8	61	55	51	51	49	49	49	47	47	46	45	45	45	45	45	45
9	62	61	55	53	53	57	52	52	50	55	52	52	52	52	52	52
10	61	60	55	55	54	57	54	56	53	57	55	55	55	55	55	55
11	60	56	52	55	51	55	51	52	50	51	51	51	51	51	51	51
12	60	56	52	56	50	50	50	52	53	53	49	50	50	50	50	50
13	57	53	49	51	48	48	48	47	47	47	47	47	47	47	47	47
Avg. Tug-in Tug-out	59	54	50	52	51	51	50	50	50	51	50	50	50	50	50	50
Total	60	59	55	55	54	52	52	50	51	52	50	52	52	52	52	52

TABLE 3-4

ORBITAL C. ENTRANCES

J-H2

CREDIT 39

CREATN SEGMENT	#3	#4	#5	#6	#7	#8	#9	#10	#11	#12	#13	#14	#15	#16	#17
QUADRANT-DEG	157	175	277	260	240	220	301	321	341	360	377	476	458	439	420
Instrument No. 1															
SENSOR 03	62	62	63	61	60	59	59	59	59	59	59	59	59	59	59
04	73	74	74	73	72	70	70	70	70	70	70	70	70	70	70
05	72	73	73	73	72	71	70	70	70	70	70	70	70	70	70
06	74	74	74	73	72	72	72	72	72	72	72	72	72	72	72
07	73	73	73	73	73	73	72	72	72	72	72	72	72	72	72
08	75	75	75	75	75	74	73	72	71	72	71	71	71	71	71
09	75	75	75	75	75	74	74	72	71	72	71	71	71	71	71
10	73	75	75	76	76	76	76	76	76	76	76	76	76	76	76
11	73	73	73	71	71	71	71	71	71	71	71	71	71	71	71
12	71	71	71	71	70	70	69	69	68	68	68	67	67	67	67
13	70	70	70	70	70	69	69	68	68	67	67	67	67	67	67
Instrument No. 2															
SENSOR 03	70	71	71	71	70	70	69	68	68	68	68	68	68	68	68
04	73	73	73	73	72	72	70	69	69	67	67	66	67	67	67
05	69	69	68	68	68	67	69	67	67	63	63	63	62	62	62
06	63	65	63	65	65	63	62	62	62	62	62	62	62	62	62
07	70	69	69	69	69	69	68	66	66	65	65	65	65	65	65
08	69	67	67	67	67	67	66	65	65	64	64	64	63	63	63
09	65	66	66	66	66	65	65	64	64	63	63	63	62	62	62
10	72	73	73	72	72	71	71	71	71	71	71	71	71	71	71
11	60	60	60	60	60	60	60	60	60	60	60	60	60	60	60

TABLE 3-5

ORBITAL MANEUVERS

J-42

ORBIT 167

CRUZIT SEGMENT	QUADRANT-DEG	Instrument No. 1	Instrument No. 2	ORBIT 167
#1	139	52	49	#10 #11 #12 #13 #14 #15 #16 #17
#2	158	61	51	50 51 52 53 54 55 56 57
#3	176	60	50	50 51 52 53 54 55 56 57
#4	277	59	49	49 50 51 52 53 54 55 56
01	239	58	48	48 49 50 51 52 53 54 55
02	259	57	47	47 48 49 50 51 52 53 54
03	219	56	46	46 47 48 49 50 51 52 53
04	302	55	45	45 46 47 48 49 50 51 52
05	322	54	44	44 45 46 47 48 49 50 51
06	342	53	43	43 44 45 46 47 48 49 50
07	361	52	42	42 43 44 45 46 47 48 49
08	377	51	41	41 42 43 44 45 46 47 48
09	396	50	40	40 41 42 43 44 45 46 47
10	415	49	39	39 40 41 42 43 44 45 46
11	434	48	38	38 39 40 41 42 43 44 45
12	453	47	37	37 38 39 40 41 42 43 44
13	472	46	36	36 37 38 39 40 41 42 43
14	491	45	35	35 36 37 38 39 40 41 42
15	510	44	34	34 35 36 37 38 39 40 41
16	529	43	33	33 34 35 36 37 38 39 40
17	548	42	32	32 33 34 35 36 37 38 39
18	567	41	31	31 32 33 34 35 36 37 38
19	586	40	30	30 31 32 33 34 35 36 37
20	605	39	29	29 30 31 32 33 34 35 36
21	624	38	28	28 29 30 31 32 33 34 35
22	643	37	27	27 28 29 30 31 32 33 34
23	662	36	26	26 27 28 29 30 31 32 33
24	681	35	25	25 26 27 28 29 30 31 32
25	700	34	24	24 25 26 27 28 29 30 31
26	719	33	23	23 24 25 26 27 28 29 30
27	738	32	22	22 23 24 25 26 27 28 29
28	757	31	21	21 22 23 24 25 26 27 28
29	776	30	20	20 21 22 23 24 25 26 27
30	795	29	19	19 20 21 22 23 24 25 26
31	814	28	18	18 19 20 21 22 23 24 25
32	833	27	17	17 18 19 20 21 22 23 24
33	852	26	16	16 17 18 19 20 21 22 23
34	871	25	15	15 16 17 18 19 20 21 22
35	890	24	14	14 15 16 17 18 19 20 21
36	909	23	13	13 14 15 16 17 18 19 20
37	928	22	12	12 13 14 15 16 17 18 19
38	947	21	11	11 12 13 14 15 16 17 18
39	966	20	10	10 11 12 13 14 15 16 17
40	985	19	9	9 10 11 12 13 14 15 16
41	1004	18	8	8 9 10 11 12 13 14 15
42	1023	17	7	7 8 9 10 11 12 13 14
43	1042	16	6	6 7 8 9 10 11 12 13
44	1061	15	5	5 6 7 8 9 10 11 12
45	1080	14	4	4 5 6 7 8 9 10 11
46	1099	13	3	3 4 5 6 7 8 9 10
47	1118	12	2	2 3 4 5 6 7 8 9
48	1137	11	1	1 2 3 4 5 6 7 8
49	1156	10		
50	1175	9		
51	1194	8		
52	1213	7		
53	1232	6		
54	1251	5		
55	1270	4		
56	1289	3		
57	1308	2		
58	1327	1		
59	1346			

TABLE 3-6

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SECTION 4

PHOTOGRAPHIC PERFORMANCE

A. GENERAL

A total of 11,306 titled panoramic frames (30,489 feet) were returned from both mission segments, along with 928 stellar and index frames (109 and 218 feet, respectively). Master photography was missing for the last ten operations because of a camera transport failure.* The last 200 feet of recovered master film was severely degraded during operations with the film pulled out of the support nails.*

	Stellar/Index		Fwd Pan			Aft Pan		
	Frames	Feet	Frames	Feet	No Ops	Frames	Feet	No Ops
Preflight				331			339	
First Mission	443	54/111	2838	7474	84	2888	7609	84
Second Mission	485	55/107	2553	6737	79	3027	7999	89
TOTAL	928	109/218	5391	14542	163	5915	15947	173
* Missing	0	0/8	533	1405	10	0	0	0

The panoramic image quality was good and comparable to recent missions, prior to the occurrence of system malfunctions. The aft-looking camera performed satisfactorily throughout the mission and image quality was consistent throughout. A MIP of 85 was assigned both missions, using the aft-looking record. Material returned from the forward-looking camera was good and consistent until operations on Rev 61, after which the quality deteriorated with increasingly erratic scan rate. The master quality was considered slightly

C

No.

lower in sharpness than that of the aft record, by visual comparison at 10x to 60x magnification of the original negative. This arises from the added effect of haze light in the forward-looking unit, and from the wider slit.

The good image quality was obtained when atmospheric conditions were favorable. There was, however, a prevalence of adverse conditions, with additional degradation attributed to surface winds and blowing sand in some heavily-targeted areas.

Both stellar-index cameras operated properly during the mission segment.

Rail hole imagery deteriorated throughout the mission culminating in a 75% loss. This loss, caused by emulsion bits filling the rail holes, was not considered deleterious because the system was not flown as a Pan Geometry mission. The lens scan lines were programmed on only for selected stateside engineering passes.

B. MASTER CAMERA PERFORMANCE EVALUATION

Performance characteristics of the master camera changed during flight operations, terminating in failure of the transport mechanism. Performance was normal prior to Rev 61, where a slowing of scan rate during the last third of the format was noted on three frames. This became generally apparent by Rev 68. The retardation effect gradually progressed until approximately Rev 159, where scan rate errors over 50% were common at the end of the formats, causing a significant loss of image quality. This was not noted on telemetry, since the camera responded with a speedup after the scan end, yielding a net cycle period close to nominal. Variations in all telemetered parameters were within the envelope describing normal operation.

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This condition persisted for ten days of operation, until Rev 228, frame 119. The next frame, 120, pulled from the rails. Photographic quality was severely degraded, although there were some usable areas of the formats. Operation continued for 80 cycles until the transport system failed completely. The last material returned was six inches of Rev 230, Frame 13.

Exhaustive investigation by A/P and ITEK specialists did not disclose the specific failure mode. The general conclusion was that a mechanical malfunction occurred in the oscillating mechanism of the instrument which was manifested in the cyclic and progressive slowdown of velocity during scan. Film tensions gradually increased so that the material eventually pulled from the rails, with subsequent complete failure of the transport mechanism.

Another problem encountered on master unit photography was the appearance of a defocused stripe along one edge of all formats. The filter apparently distorted in flight so that one edge curled away from the slit and acted as a cylindrical lens, distorting the imagery and modifying exposure in the affected area.

An additional problem, of lesser significance, was encountered in reading the binary time words. The mask which provided the image for both serial number and time word index dot was canted so that the dot was misaligned with the inner row of binary bits, confusing the automatic reader.

Auxillary data recording, as horizon camera imagery and fiducials,

C

NO.

binary time word, serial number, start of pass mark, 200 PPS time trace, blanking pulse, and S/I slur pulse was operational throughout the mission, until pass 228. Although extensive effort had been directed towards elimination of light leaks, typical minor drum leaks were evident at the beginning of many operations, causing very minor degradation.

C. SLAVE CAMERA PERFORMANCE EVALUATION

Performance characteristics of the slave camera remained stable throughout the mission; good photography was attained. The MIP-85 frames for both mission segments were from this camera.

Several minor anomalies were observed, the more prevalent of which were intermittent light minus-density streaks noted during operations on seven revs. Foreign particles apparently were entrapped in the lens stove, between the fifth lens element and the field flattener. Occasionally, one or more temporarily adhered to the field flattener and moved with it during photographic scan.

Additional anomalies included the time trace missing for a few inches on the startup frame of two operations, and minor edge static on material from three operations. These anomalies are common, and not degrading. A periodic minus density spot along the format center of one operation is believed to be pressure marks caused by particles of foreign material (probably scraped emulsion) on a metering roller. A similar problem in reading the time word was encountered as on the master camera record, for the same cause.

Auxillary data recording, as H.O. imagery and fiducials, binary time word, serial number, start of pass mark, 200 PPS time trace, and blanking pulse was operational throughout the mission. Minor light leaks at the drum were apparent at the beginning of many operations, causing very minor

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degradation.

D. STELLAR-INDEX EVALUATION

1. Index photography for the first mission is good, and comparable to that obtained from other recent missions. No significant anomalies occurred.

Stellar photography shows approximately fifty percent of each format affected by flare. Fifteen to twenty stellar images are visible in each frame; many frames have slightly elongated images, indicating slight attitude perturbations during exposure.

2. Index photographic quality for the second mission was good, and compared favorably with recent missions. Several minute minus-density spots, probably caused by foreign particles adhering to the reseau, are imaged on each frame. Minor edge fog appeared intermittently throughout the record. Heavy fog patterns were noted on the first two frames.

The stellar photography shows a normal area of each format affected by flare. Twenty to twenty-five stellar images are visible in each frame, with no major attitude perturbations noted. A small minus-density spot, probably caused by foreign particles adhering to the reseau plate, is imaged on each frame. Some fogging affects formats from the latter few operations of the mission.

E. OBSERVED DATA

Detailed evaluation of selected original negative, and of the stateside engineering materials available at A/P, was undertaken in an attempt to determine the extent of information reduction caused by the Master camera malfunction.

Atmospherics played an important role, for this mission, in terms of terrain information content. Content over the Z.I. was degraded to some extent.

C

NO.

during portions of most passes, with few exceptions. Several operations were performed over controlled range network resolution targets, both fixed and mobile, several of which were obscured by clouds or rendered marginal by haze.

In general, ground resolution of the aft-looking camera was equal with the forward-looking, (scan component) or one group better, throughout the mission. However, the FMC component of the forward looking unit was usually an additional group lower than in the scan direction. The best indicated ground target resolution was 11 feet, but this was not believed to represent mission photography during the better operations - those less affected by atmospheric conditions. Considerable image distortion is evident in some areas, probably as a result of thermal gradients and/or local surface air currents.

Effects of the Master camera scan problem are evident near the end scan area of the format. The apparent information content drops off significantly, relative to the format center area. Smear is noted in higher-contrast imagery in the affected area near the end of the mission. In general, however, the scan rate anomaly did not severely degrade the forward looking photography, especially when viewed stereoscopically. In conjunction with the aft looking coverage, there was not a serious information loss, until the failure on the last day of the mission.

F. PERFORMANCE MEASUREMENTS

The photography acquired by both panoramic cameras during Missions 1043-1 and 1043-2 received a MIP rating of 85. A summary is tabulated below of the MTF/AM resolution values measured by AFSPPF and reported in cycles/mm. The

C [REDACTED] NO. [REDACTED]

microdensitometer slit used was 1 micron by 80 microns.

<u>Mission</u>	<u>Camera</u>	<u>Cycles/mm</u>	<u>Avg.</u>	<u>Ground Resolution</u>
1043-1	FWD	65	65	15.3 Feet
1043-2	FWD	65		
1043-1	AFT	67	71	16.0 Feet
1043-2	AFT	75		

Edge scan analysis of random scene edges verifies that the Slave Camera provided better ground resolution than the Master camera. Values from both cameras were similar to those obtained by Mission 1039. Due to the large scale of this photography, the mobile CORN edge targets could not be traced using AFSPFF standard techniques.

The details of the measurement and computing techniques, targets measured and target locations are fully reported in the evaluation report published by AFSPFF and are not included in this report. These values were determined by using the "Interim MTF/ADM Program" technique.

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SECTION 5

PANORAMIC CAMERA EXPOSURE

The slits, filters and launch window for the panoramic cameras were chosen so as to place nominal exposure between the Eastman full and intermediate processing curves. A 0.200 inch slit/Wratten 23A combination was selected for the forward looking unit, and a 0.150 inch slit/Wratten 21 combination for the aft-looking unit, with a recommended launch window between 21⁴⁵Z and 22⁴⁵Z. Establishment of 21⁴⁵Z (13⁴⁵ PST) as the early cutoff was done because of possible flare off the stellar baffles late in the mission. Actual launch was 21⁴²Z.

The slit/filter combinations were typical of recent summer flights. Considerations in their choice included maximization of northern coverage, minimizing exposure time for IMC tolerance and coverage at lower latitudes with high scene illuminance, and maximization of scene contrast. Frequency distributions of solar elevations and directions actually encountered during photographic operations are shown in Figures 5-1 thru 5-4. Nominal exposure of the cameras, based on actual orbit parameters at the start, middle, and end of the mission are shown as a function of latitude in Figure 5-5 thru 5-10. Generally, exposure was well within the tolerances which produce acceptable photography.

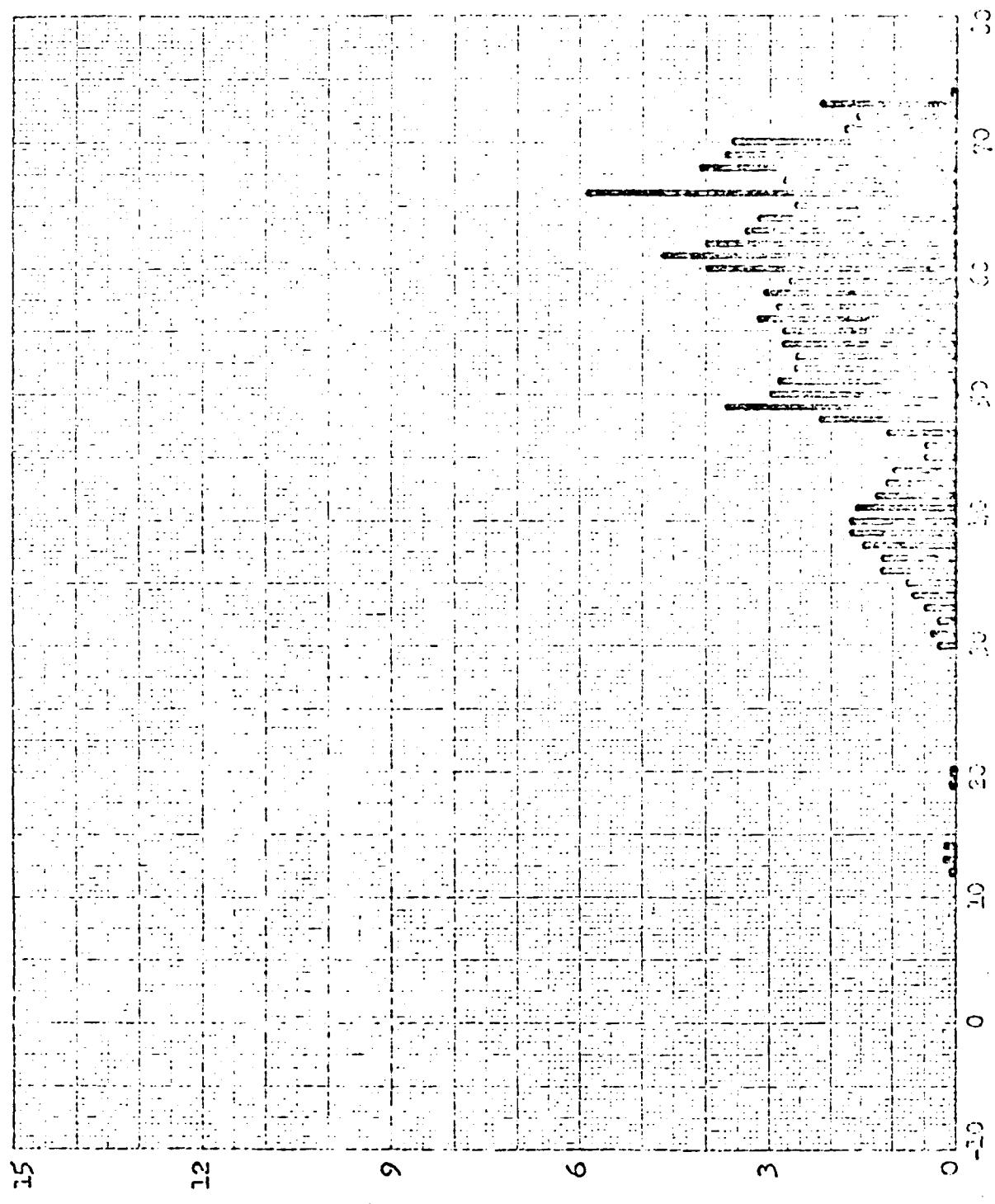
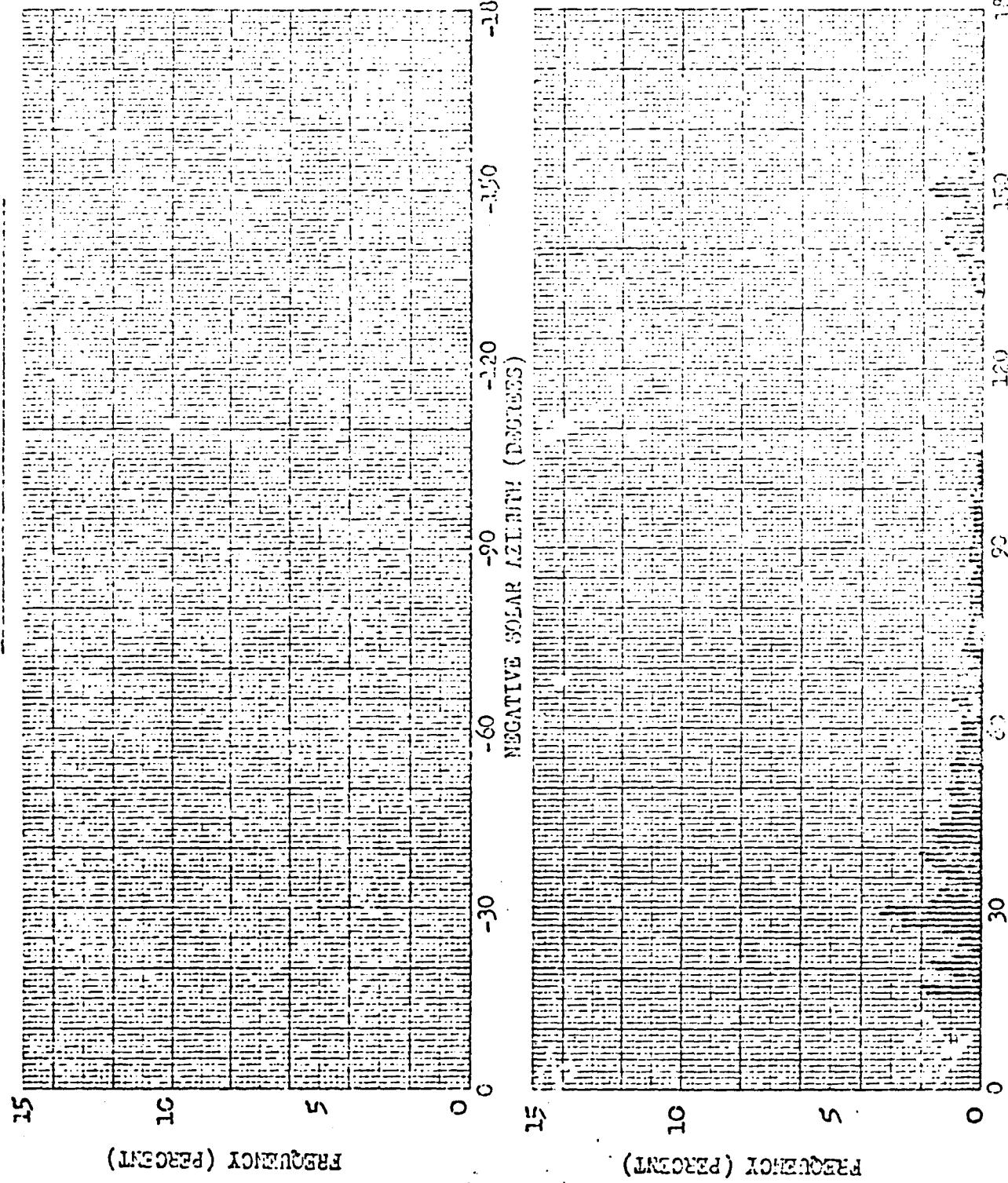
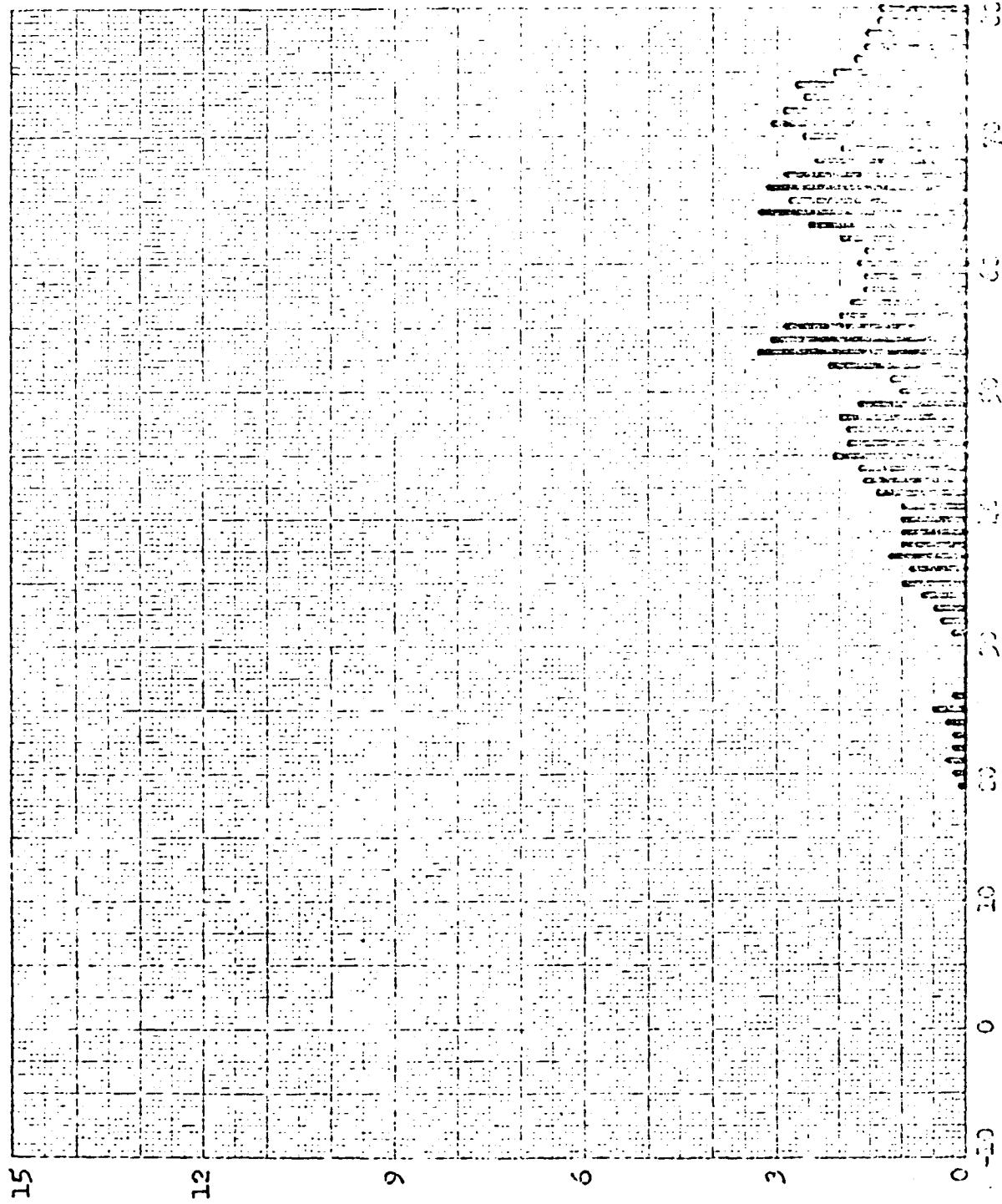


FIGURE 5-1

SOLAR AZIMUTH FREQUENCY DISTRIBUTION



SO-42 MISSION PLACEMENT DISTRIBUTION

Mission No: 1043-2Payload No: J-42Camera No: 200Launch Date: 8/14/67Launch Time: 2144 ZInclination: 80°

(METERS)

TOP SECRET C

CN

SOLAR AZIMUTH FREQUENCY DISTRIBUTION

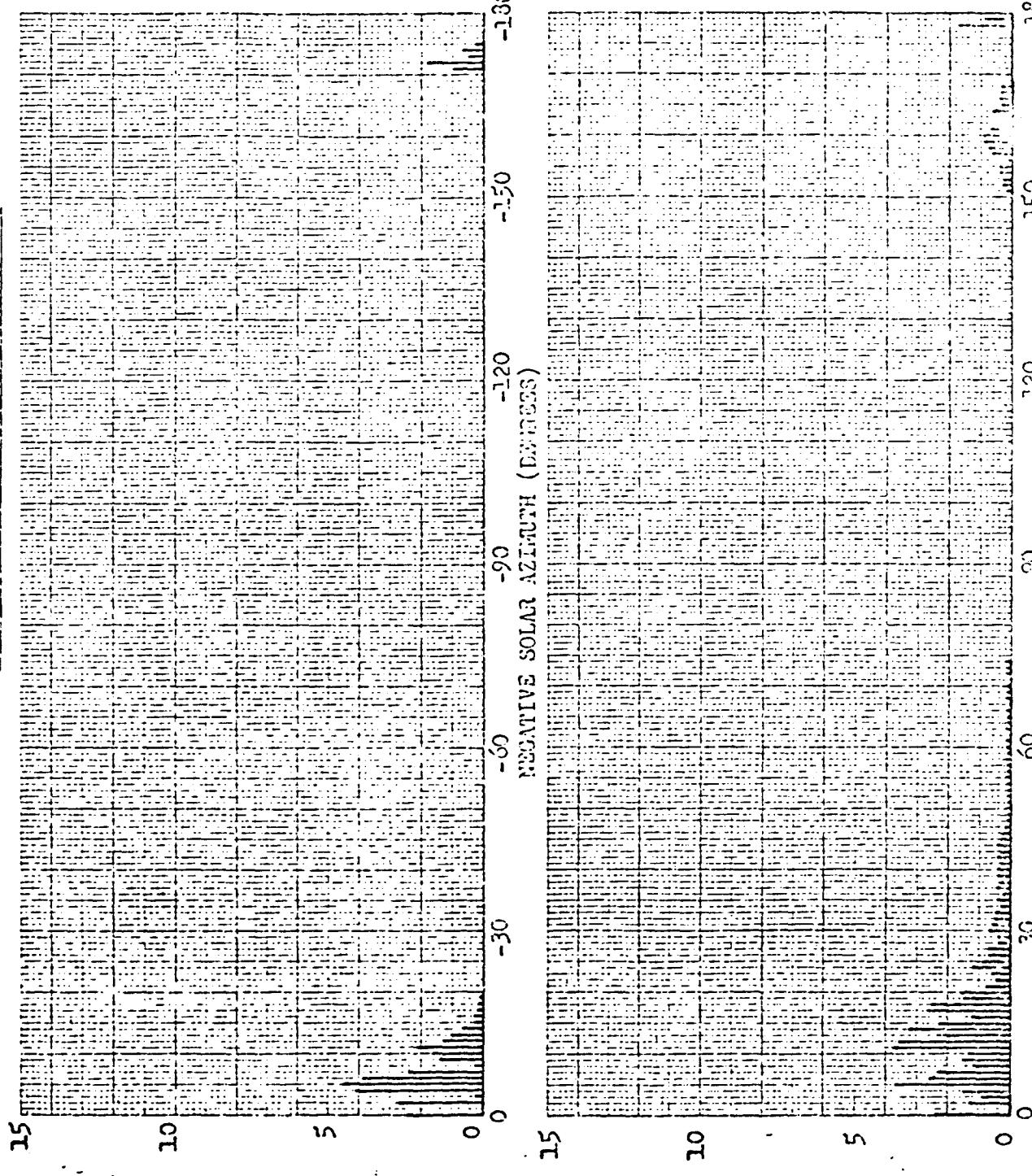


FIGURE 5-4

TOP SECRET C

180

150

(SECRET) EJECTA EMISSION
TEST

60

30

0

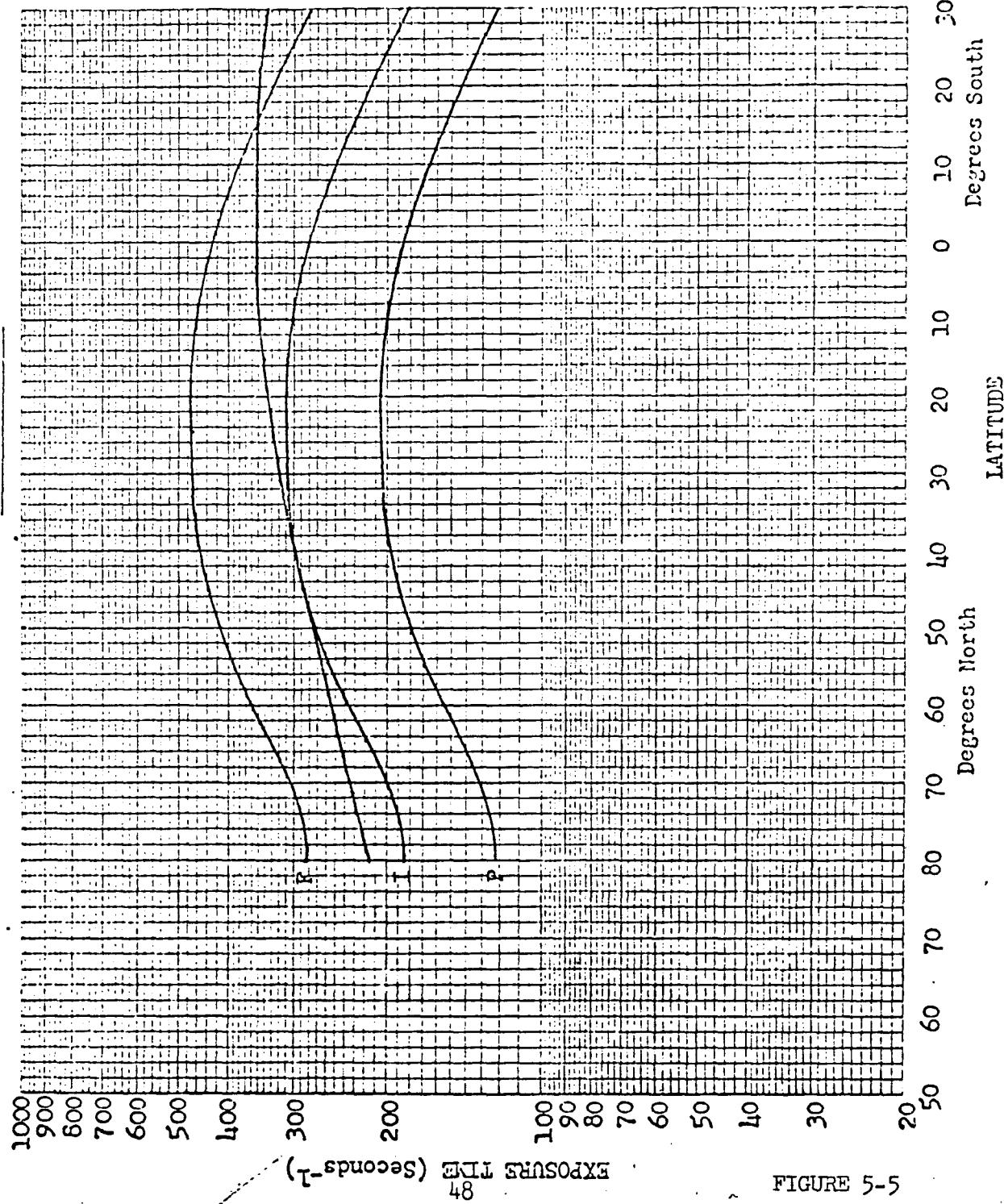
Mission No: 1043Payload No: J-12Camera No: 200Pass No: 1Launch Date: 8/7/67Launch Time: 2144ZSlit Width: .200Filter Type: Kratten 23AFilm Type: 3404EXPOSURE POINTS

FIGURE 5-5

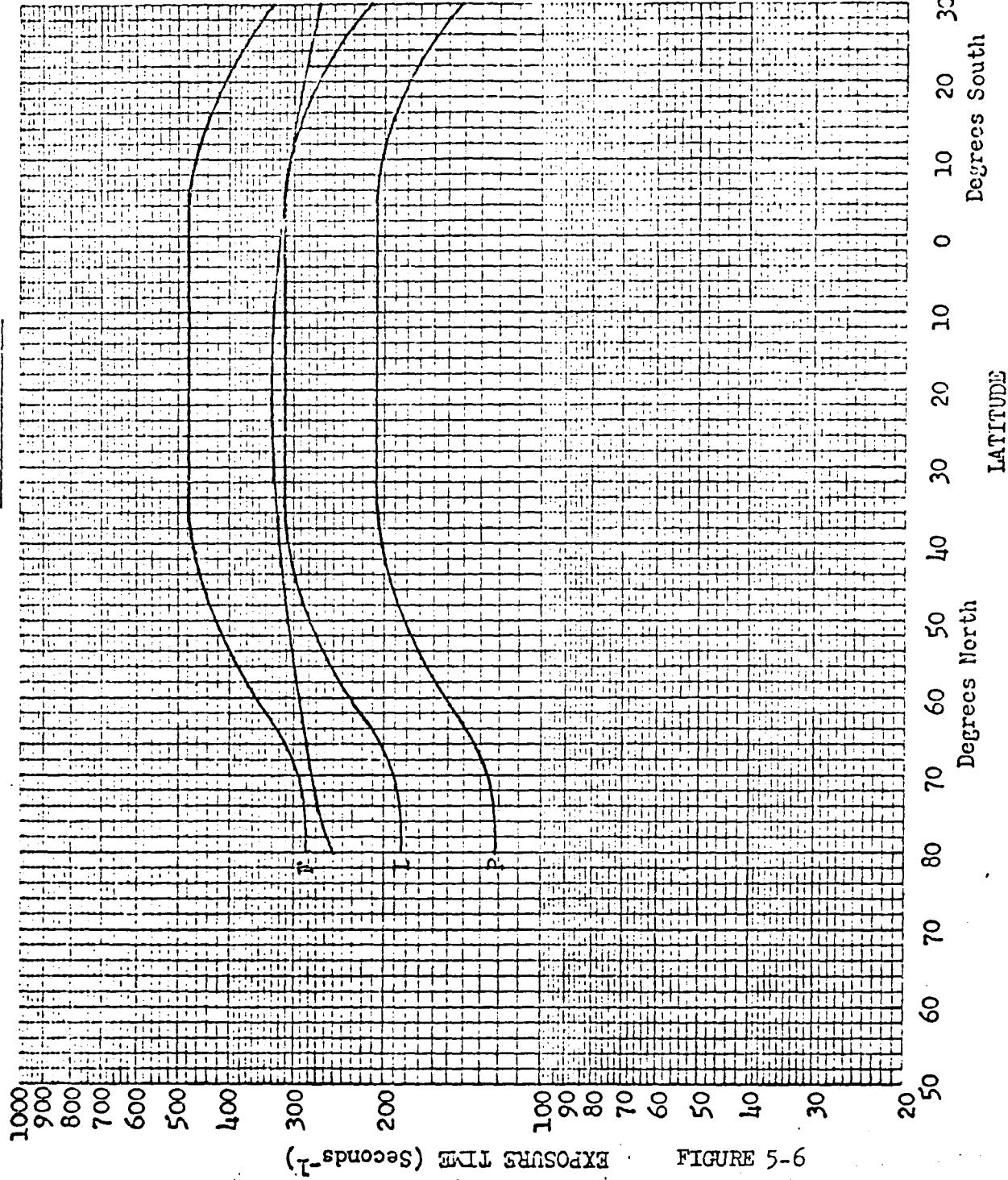
EXPOSURE POINTS

FIGURE 5-6

~~TOP SECRET C~~

Mission No: 1013

Payload No: J-42

Camera No: 200

Pass No: 240

Launch Date: 6/7/67

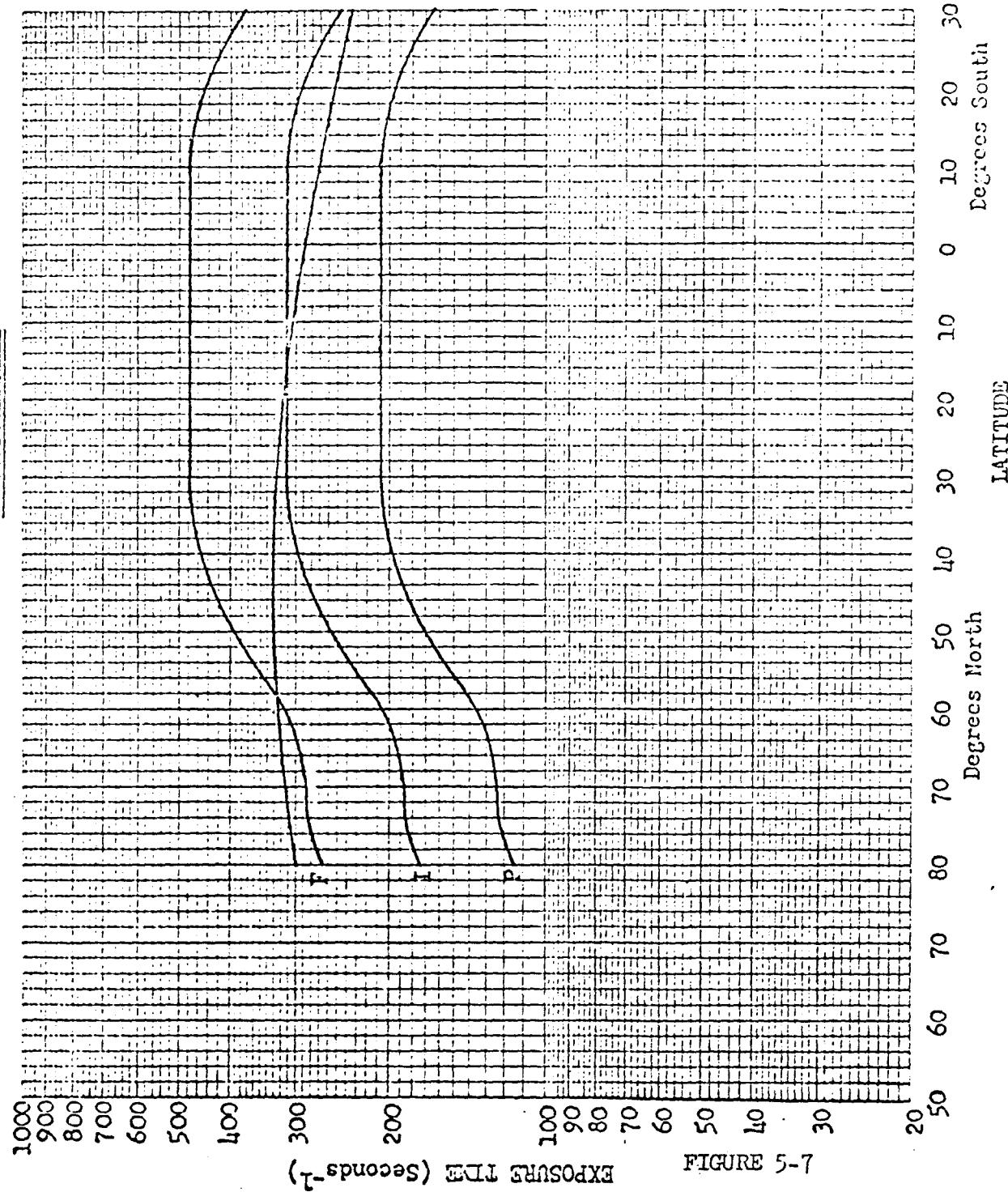
Launch Time: 2144 Z

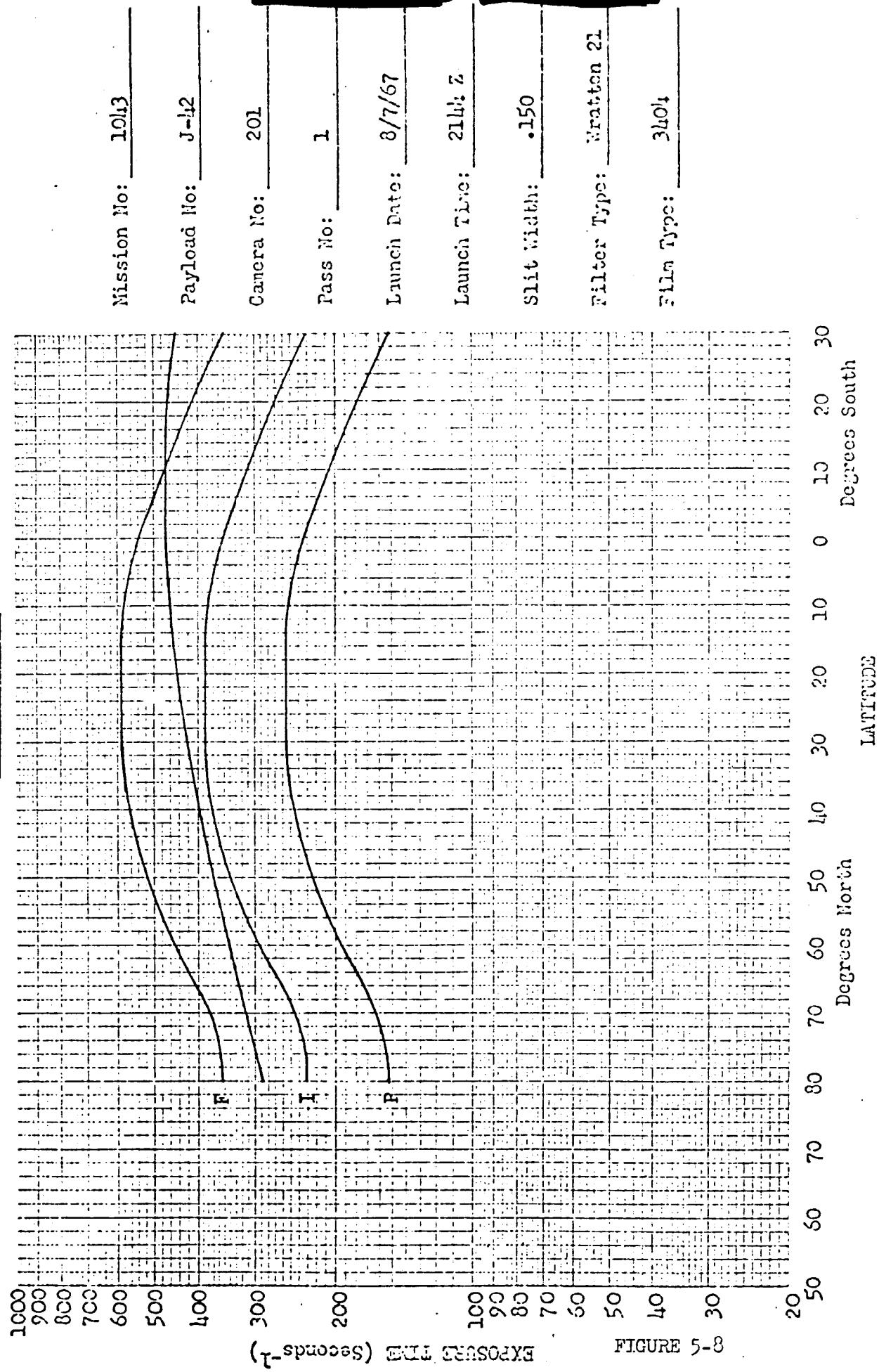
Slit width: .200

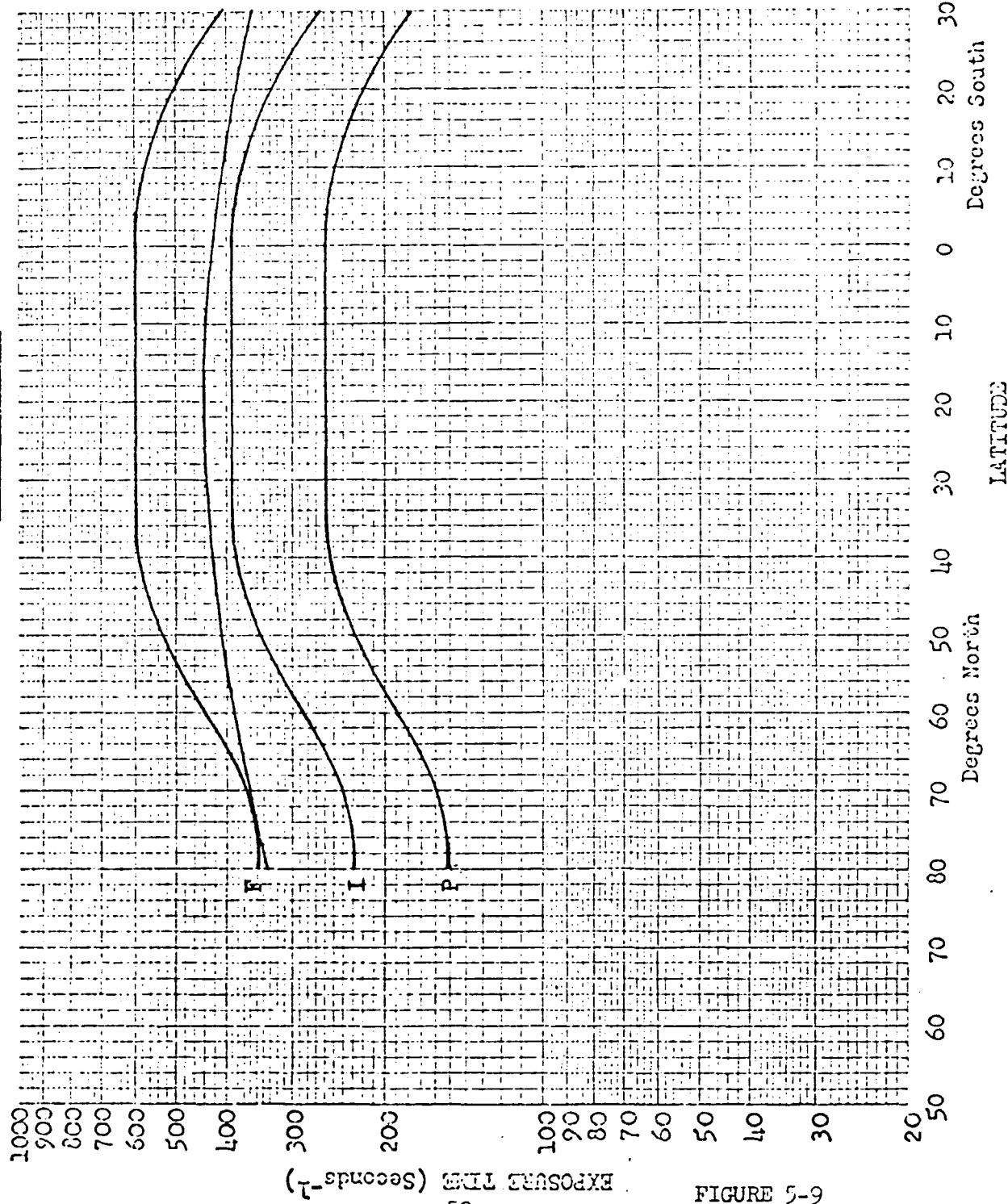
Filter Type: Vibration 23A

Film No: 3401

EXPOSURE POINTS



EXPOSURE POINTS

EXPOSURE POINTS

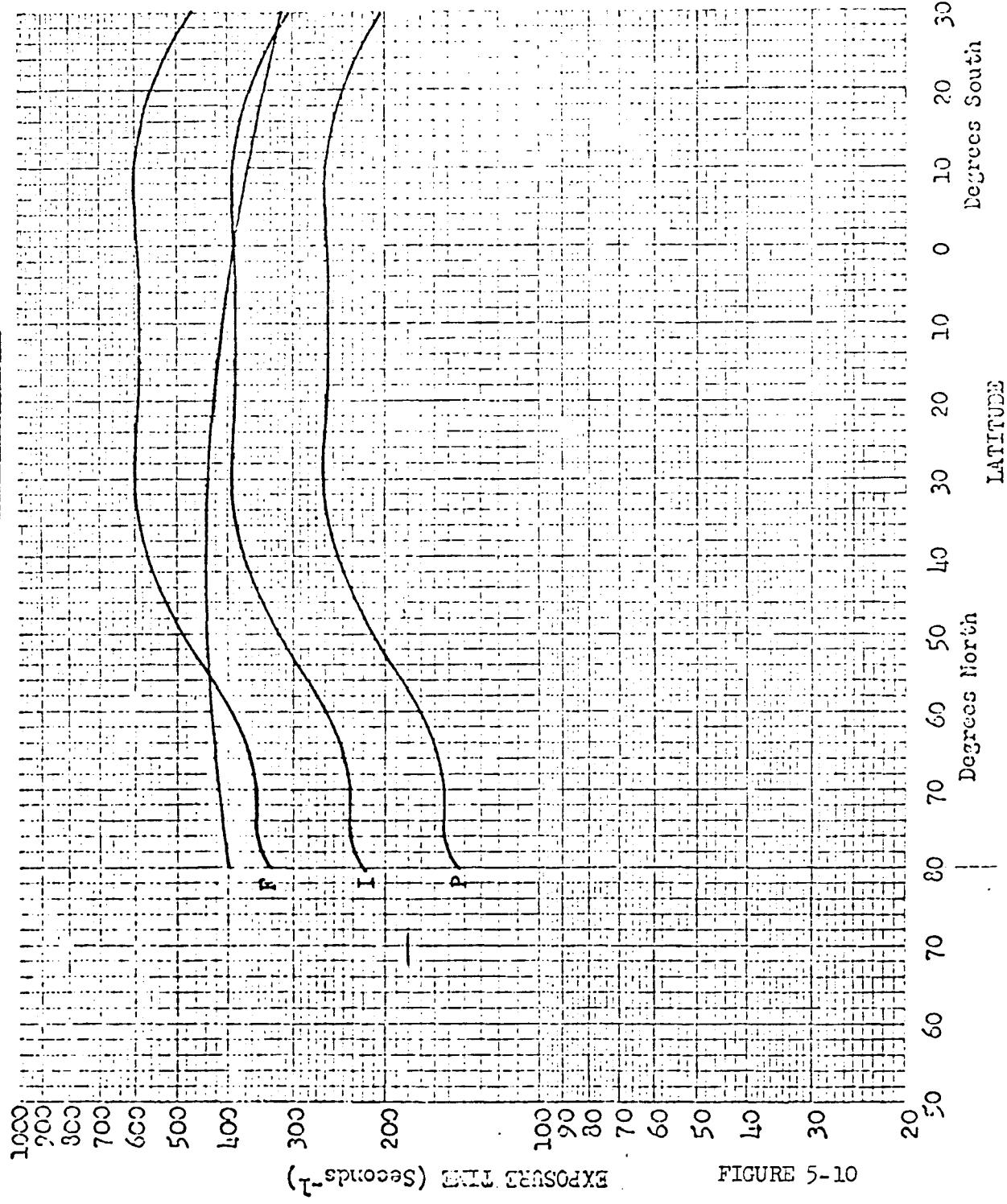
EXPOSURE POINTS

FIGURE 5-10

C/ [REDACTED] NO. [REDACTED]

SECTION 6

DIFFUSE DENSITY MEASUREMENTS

The diffuse density measurements made by AFSPFF were processed by computer at A/P to permit analysis of the density ranges encountered at the three processing levels. A study of sorting techniques has shown that no absolute method is available to separate the density values. The sorting technique selected uses arbitrary base-plus-fog density values where measurements up to 0.09 density are considered as having received Primary processing, 0.10 to 0.17 as Intermediate, and above 0.17 density as Full. The percentage of original negative that was processed at each level, based on the computer sort, is tabulated below with the predicted and reported processing percentages.

<u>Mission</u>	<u>Camera</u>		<u>Primary</u>	<u>Intermediate</u>	<u>Full</u>	<u>Transition</u>
1043-1	FWD	Predicted	0	20	80	-
		Reported	6	14	68	12
		Computed	4	26	70	-
1043-1	AFT	Predicted	0	3	97	-
		Reported	6	8	74	12
		Computed	2	27	71	1
1043-2	FWD	Predicted	1	19	80	-
		Reported	2	11	73	14
		Computed	1	39	60	-
1043-2	AFT	Predicted	0	7	93	-
		Reported	5	16	63	16
		Computed	1	37	62	-

C/ [REDACTED] NO. [REDACTED]

A summary of the processing and exposure analysis is shown in Table 6-1. The terrain D-Min criteria (range) for proper exposure and processing is 0.40 to 0.90 density units. The area measured for D-Min is selected subjectively and is not necessarily the absolute D-Min in the photography.

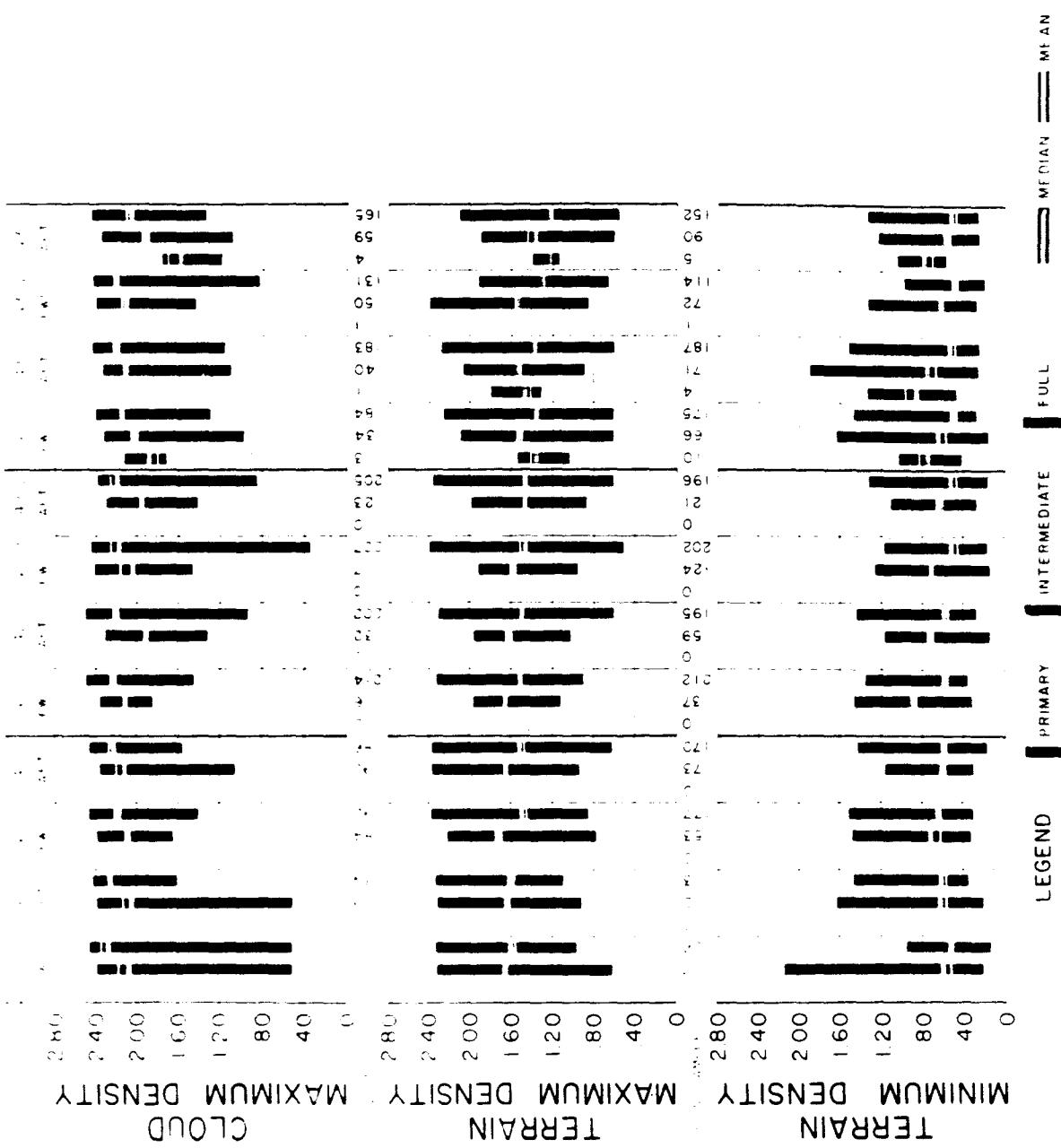
A density range chart, Figure 6-1, is included in this report. Data prior to mission 1041 is included in the A/P final reports for Missions 1031 and 1040.

These charts are produced from the same density measurements previously mentioned in this section. The computer produced the mean, median and range figures for the various processing levels used. The chart includes the number of frames (samples) in which the density measurements were made. These measurements are made on approximately every tenth frame throughout the mission.

MISSION 1043-1			INSTR - FWD			1/9/68			PROCESSING AND EXPOSURE ANALYSIS		
PROCESS LEVEL	SAMPLE SIZE	UNDER EXPOSED	UNDER PROCESSED	UNDER EXPOSED	UNDER PROCESSED	CORRECT EXP&PRUC	OVER PROCESSED	OVER PROCESSED	OVER EXPOSED	OVER EXPOSED	
PRIMARY	10	0 PC	0 PC	90 PC	0 PC	0 PC	10 PC	10 PC	10 PC	10 PC	
INTERMEDIATE	66	2 PC	15 PC	65 PC	15 PC	15 PC	3 PC	3 PC	3 PC	3 PC	
FULL	175	28 PC	0 PC	67 PC	0 PC	67 PC	0 PC	0 PC	0 PC	0 PC	
ALL LEVELS	251	20 PC	4 PC	67 PC	8 PC	67 PC	1 PC	1 PC	1 PC	1 PC	
MISSION 1043-1			INSTR - AFT			1/9/68			PROCESSING AND EXPOSURE ANALYSIS		
PROCESS LEVEL	SAMPLE SIZE	UNDER EXPOSED	UNDER PROCESSED	UNDER EXPOSED	UNDER PROCESSED	CORRECT EXP&PRUC	OVER PROCESSED	OVER PROCESSED	OVER EXPOSED	OVER EXPOSED	
PRIMARY	4	0 PC	0 PC	50 PC	0 PC	0 PC	50 PC	50 PC	50 PC	50 PC	
INTERMEDIATE	71	0 PC	7 PC	69 PC	19 PC	19 PC	6 PC	6 PC	6 PC	6 PC	
FULL	187	23 PC	0 PC	73 PC	4 PC	73 PC	0 PC	0 PC	0 PC	0 PC	
ALL LEVELS	262	16 PC	2 PC	71 PC	8 PC	71 PC	2 PC	2 PC	2 PC	2 PC	
MISSION 1043-2			INSTR - FWD			1/9/68			PROCESSING AND EXPOSURE ANALYSIS		
PROCESS LEVEL	SAMPLE SIZE	UNDER EXPOSED	UNDER PROCESSED	UNDER EXPOSED	UNDER PROCESSED	CORRECT EXP&PRUC	OVER PROCESSED	OVER PROCESSED	OVER EXPOSED	OVER EXPOSED	
PRIMARY	1	0 PC	0 PC	100 PC	0 PC	0 PC	0 PC	0 PC	0 PC	0 PC	
INTERMEDIATE	72	0 PC	14 PC	72 PC	14 PC	72 PC	0 PC	0 PC	0 PC	0 PC	
FULL	114	35 PC	9 PC	62 PC	2 PC	62 PC	0 PC	0 PC	0 PC	0 PC	
ALL LEVELS	187	21 PC	5 PC	66 PC	7 PC	66 PC	7 PC	7 PC	7 PC	7 PC	
MISSION 1043-2			INSTR - AFT			1/9/68			PROCESSING AND EXPOSURE ANALYSIS		
PROCESS LEVEL	SAMPLE SIZE	UNDER EXPOSED	UNDER PROCESSED	UNDER EXPOSED	UNDER PROCESSED	CORRECT EXP&PRUC	OVER PROCESSED	OVER PROCESSED	OVER EXPOSED	OVER EXPOSED	
PRIMARY	5	0 PC	0 PC	60 PC	0 PC	60 PC	4 PC	4 PC	4 PC	4 PC	
INTERMEDIATE	90	0 PC	29 PC	60 PC	11 PC	60 PC	11 PC	11 PC	11 PC	11 PC	
FULL	152	29 PC	7 PC	67 PC	4 PC	67 PC	4 PC	4 PC	4 PC	4 PC	
ALL LEVELS	247	18 PC	11 PC	64 PC	6 PC	64 PC	6 PC	6 PC	6 PC	6 PC	
MISSION 1043-2			INSTR - FWD			1/9/68			PROCESSING AND EXPOSURE ANALYSIS		
PROCESS LEVEL	BASE & FLG	UNDER EXPOSED	UNDER PROCESSED	UNDER EXPOSED	UNDER PROCESSED	CORRECT EXP&PRUC	OVER PROCESSED	OVER PROCESSED	OVER EXPOSED	OVER EXPOSED	
PRIMARY	0.01-0.09	C.01-C.13	0.14-0.39	0.40-0.90	----	----	----	----	0.91 AND UP	0.91 AND UP	
INTERMEDIATE	0.10-0.17	C.C1-C.20	0.21-0.39	0.40-0.90	----	----	----	----	1.35 AND UP	1.35 AND UP	
FULL	0.18 AND UP	C.C1-C.39	----	0.40-0.90	----	----	----	----	1.70 AND UP	1.70 AND UP	

TABLE 6-1

J MISSION DENSITY RANGES



C/

NO.

SECTION 7

VEHICLE ATTITUDE

The vehicle attitude errors for both Mission 1043-1 and 1043-2 were derived from the reduction of the Stellar camera photography. This attitude data is supplied to A/P by NPIC.

The attitude errors for each frame and the attitude control rates are calculated at the A/P computer facility. The computer also plots the frequency distribution of the rates and errors. Figures 7-1 through 7-6 show these distributions for Mission 1043-1 and Figures 7-7 through 7-12 for Mission 1043-2.

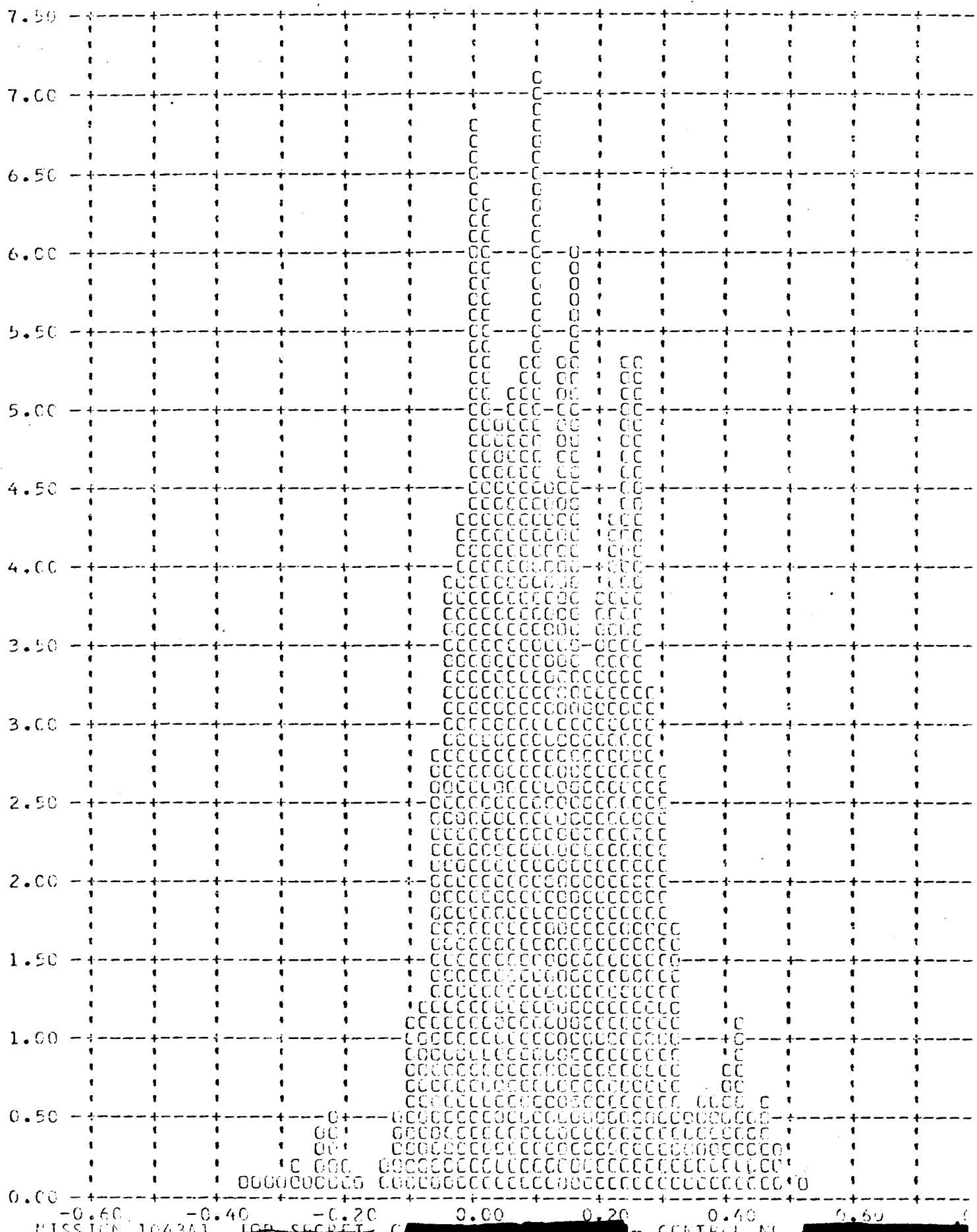
The summary table below lists the maximum attitude errors and rates that were experienced during 90% of the FWD camera photographic operations, excluding the first six frames of each operation, and the total range of the errors and rates.

<u>Value</u>	Mission 1043-1		Mission 1043-2	
	<u>90%</u>	<u>Range</u>	<u>90%</u>	<u>Range</u>
Pitch Error ($^{\circ}$)	0.28	-0.36 to +0.52	0.30	-0.19 to +0.50
Roll Error ($^{\circ}$)	0.23	-0.32 to +0.40	0.34	-0.50 to +0.26
Yaw Error ($^{\circ}$)	3.11	-3.20 to +0.40	2.73	-2.95 to +0.40
Pitch Rate ($^{\circ}/\text{hr.}$)	23.87	-38 to +60	29.16	-34 to +72
Roll Rate ($^{\circ}/\text{hr.}$)	22.03	-90 to +55	31.58	-90 to +65
Yaw Rate ($^{\circ}/\text{hr.}$)	41.54	-96 to +15	47.91	-98 to +38

The performance of the attitude control system is comparable to the control systems used on recent missions. The panoramic photography was not degraded by the attitude control system.

MISSION 1043A1 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED] -
FRAMES 1-6 LF EACH CP OMITTED 90 PERCENT = 0..

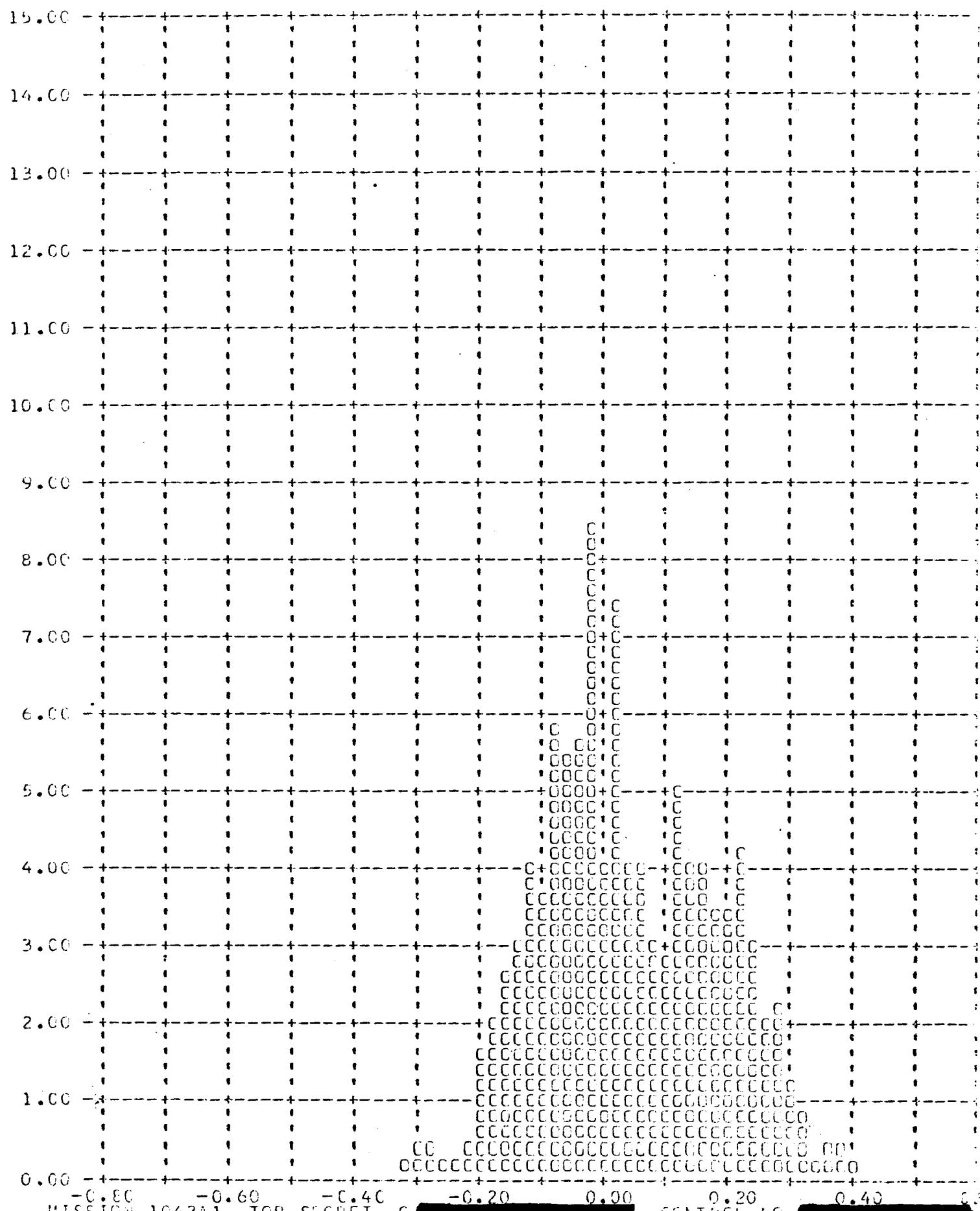
Y PITCH ANGLE ERROR - DEGREES (X) VERSUS FREQUENCY - PERCENT (Y)



MISSION 1043A1 ~~TOP SECRET~~ C

MISSION 1043A1 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED] - FRAMES 1-8 OF EACH UP CYCLED 90 PERCENT = 0.

Y ROLL ANGLE ERROR - DEGREES (X) VERSUS FREQUENCY - PERCENT (Y)



MISSION 1043A1 ~~TOP SECRET~~ C

- CONTROL NO. [REDACTED]

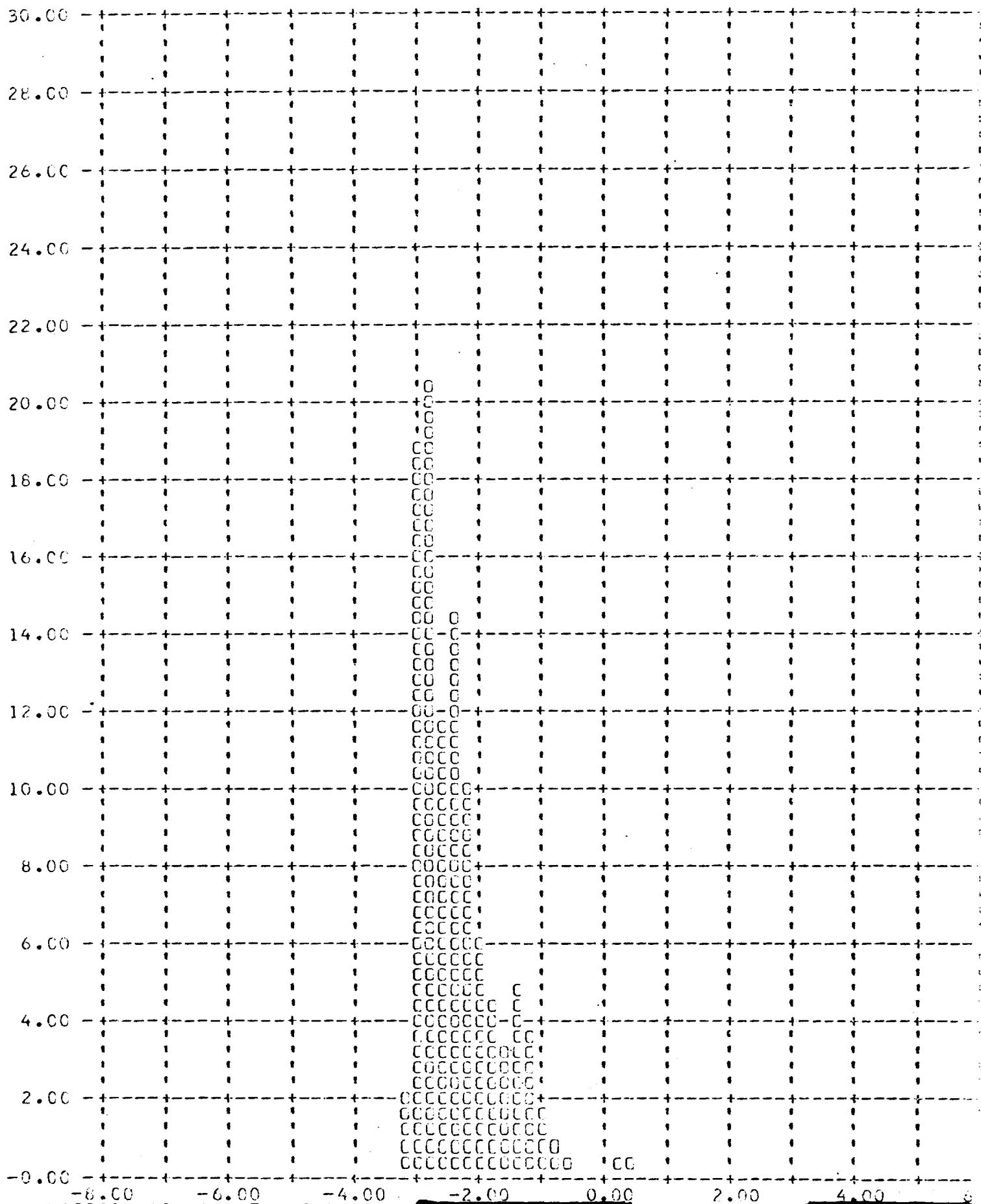
MISSION 1043A1 TOP SECRET

C

CONTROL NO.

FRAMES 1-6 OF EACH EP OMITTED 90 PERCENT - 4.0

Y YAW ANGLE ERROR - DEGREES (X) VERSUS FREQUENCY - PERCENT (Y)

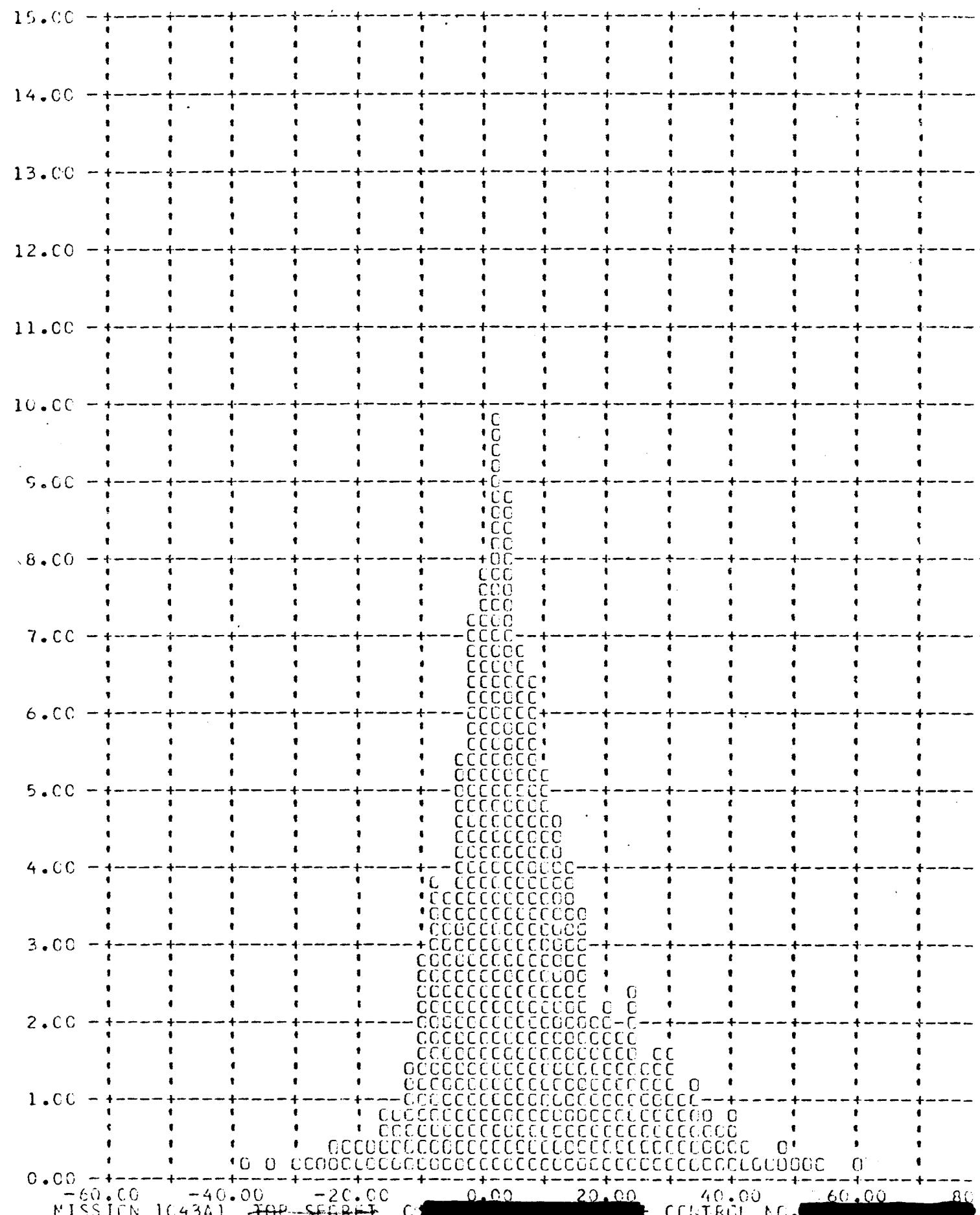


MISSION 1043A1 TOP SECRET C

CONTROL NO.

MISSION 1043A1 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED] -
FRAMES 1-6 OF EACH LP CHNITED 90 PERCENT = 23.1

Y PITCH RATE ERROR - DEG/HOUR (X) VERSUS FREQUENCY - PERCENT (Y)

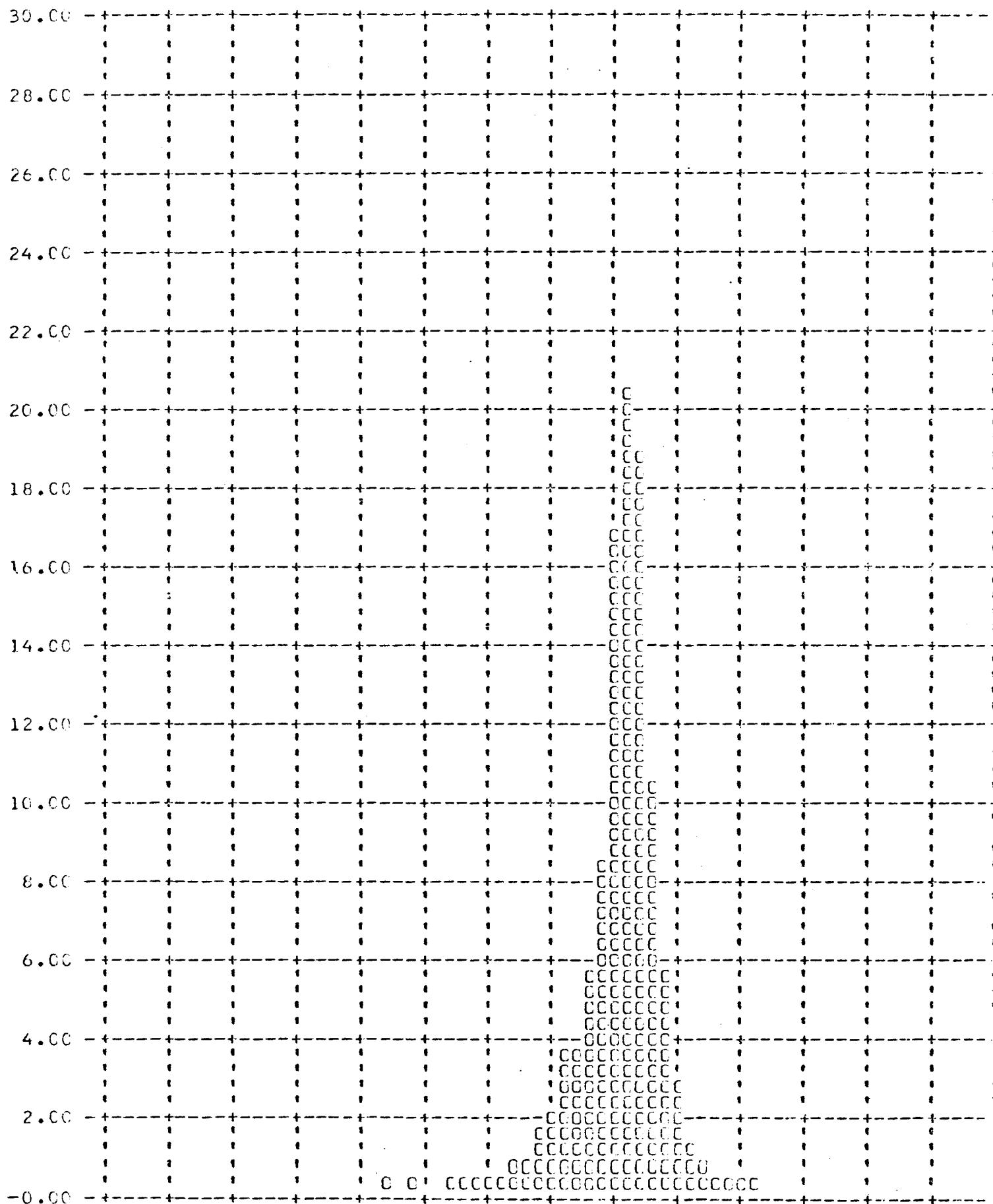


MISSION 1043A1 ~~TOP SECRET~~ C

CENTRAL NO. [REDACTED]

MISSION 1043A1 - ~~TOP SECRET~~ C - CONTROL NO. [REDACTED] - FRAMES 1-6 OF EACH CP OMITTED 90 PERCENT = 22%

Y ROLL RATE ERROR - DEG/HOUR (X) VERSUS FREQUENCY - PERCENT (Y)



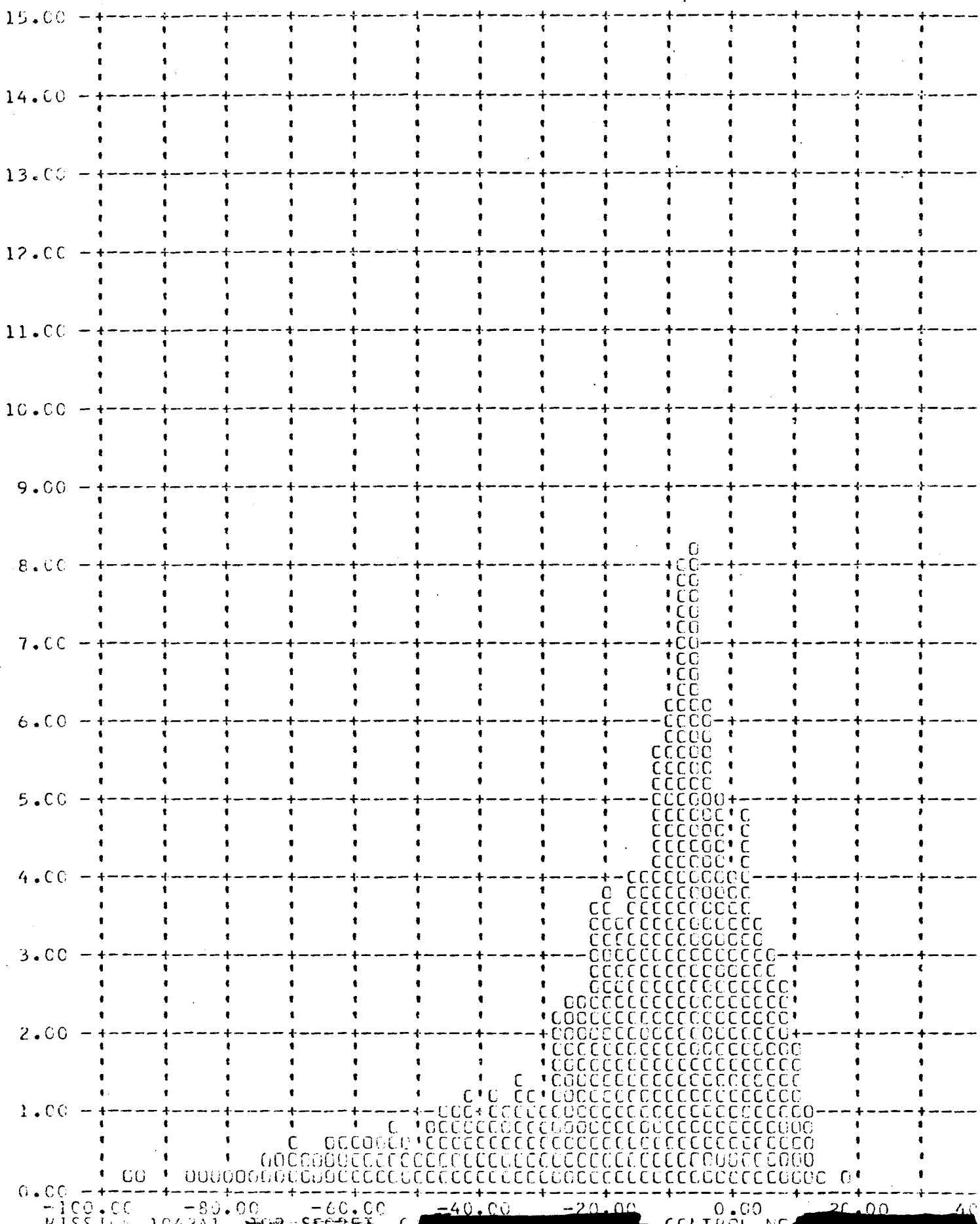
MISSION 1043A1 - ~~TOP SECRET~~ C

- CONTROL NO. [REDACTED]

MISSION 1043A1 ~~TOP SECRET~~

- CONTROL NO. [REDACTED] -
FRAMES 1-6 OF EACH UP CYCLED 90 PERCENT = 41.5

Y YAW RATE ERROR - DEG/HOUR (X) VERSUS FREQUENCY - PERCENT (Y)

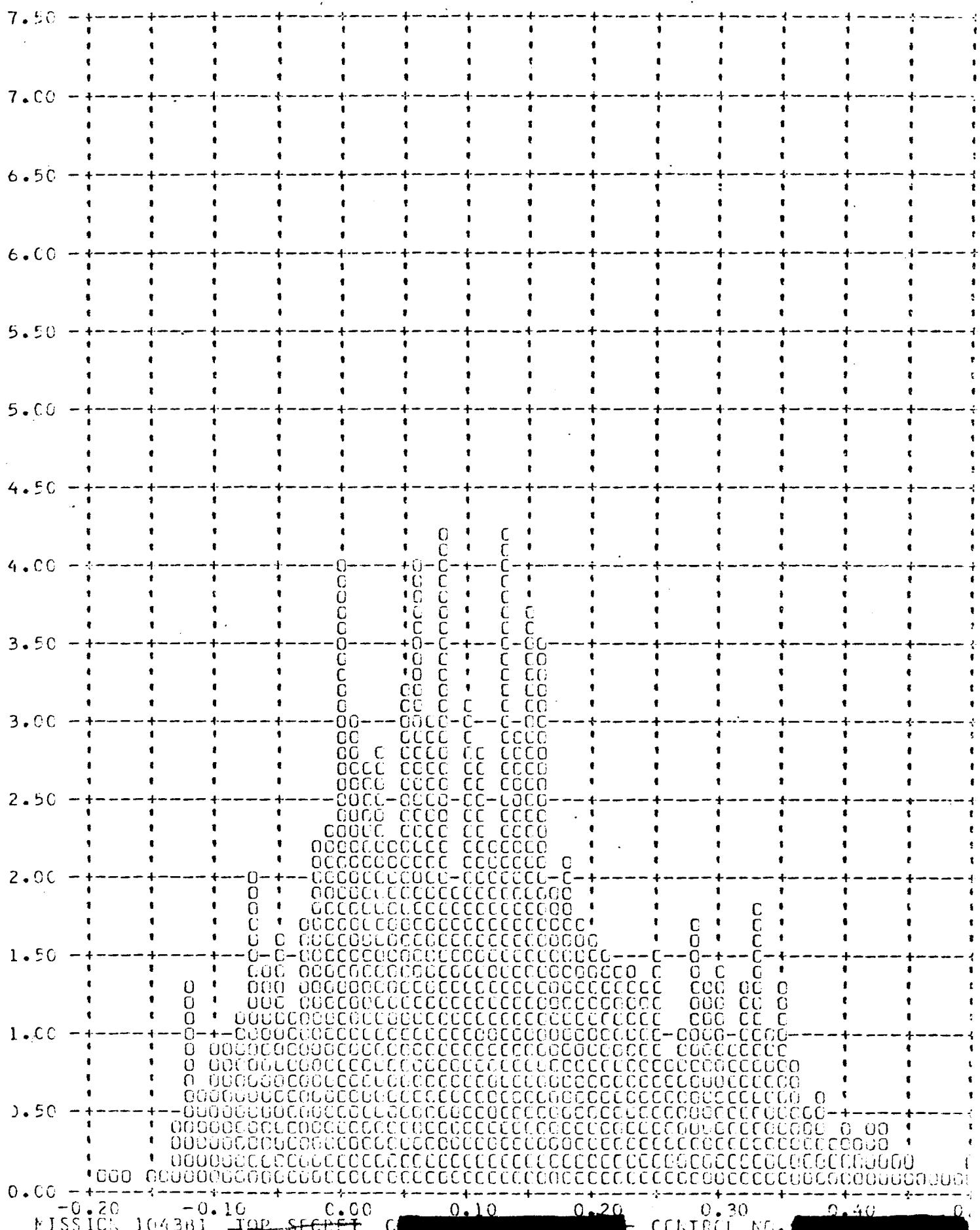


MISSION 1043A1 ~~TOP SECRET~~ C [REDACTED]

- CONTROL NO. [REDACTED]

MISSION 1043B1 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED] -
FRAMES 1-6 OF EACH OF CRITLED 90 PERCENT # 0.0

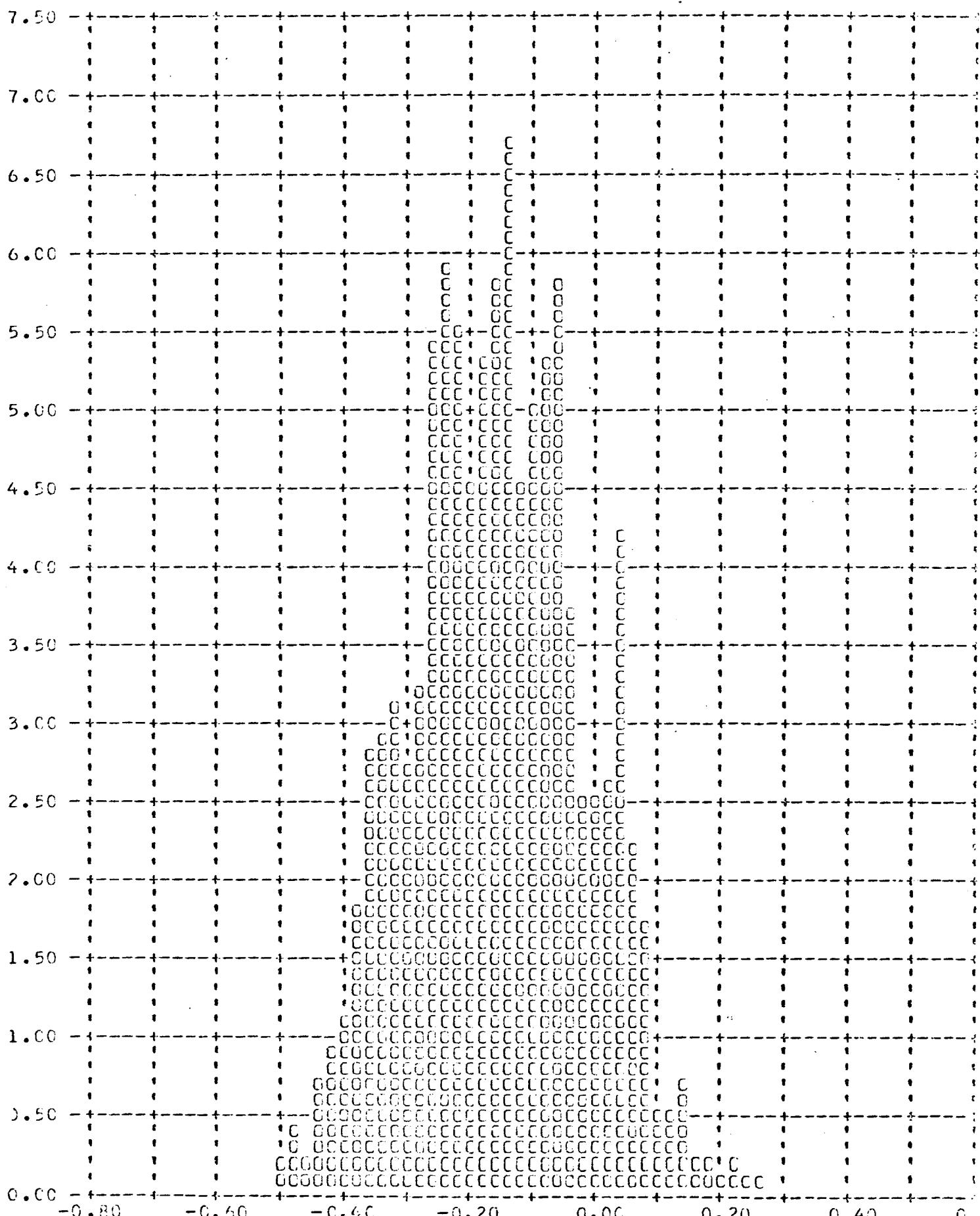
Y PITCH ANGLE ERROR - DEGREES (X) VERSUS FREQUENCY - PERCENT (Y)



MISSION 1043B1 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED]

MISSION 1043B1 ~~TOP SECRET~~ C [REDACTED] CONTROL NO. [REDACTED]
FRAMES 1-6 OF EACH UP OMITTED 90 PERCENT = 0.1

Y ROLL ANGLE ERROR - DEGREES (X) VERSUS FREQUENCY - PERCENT (Y)



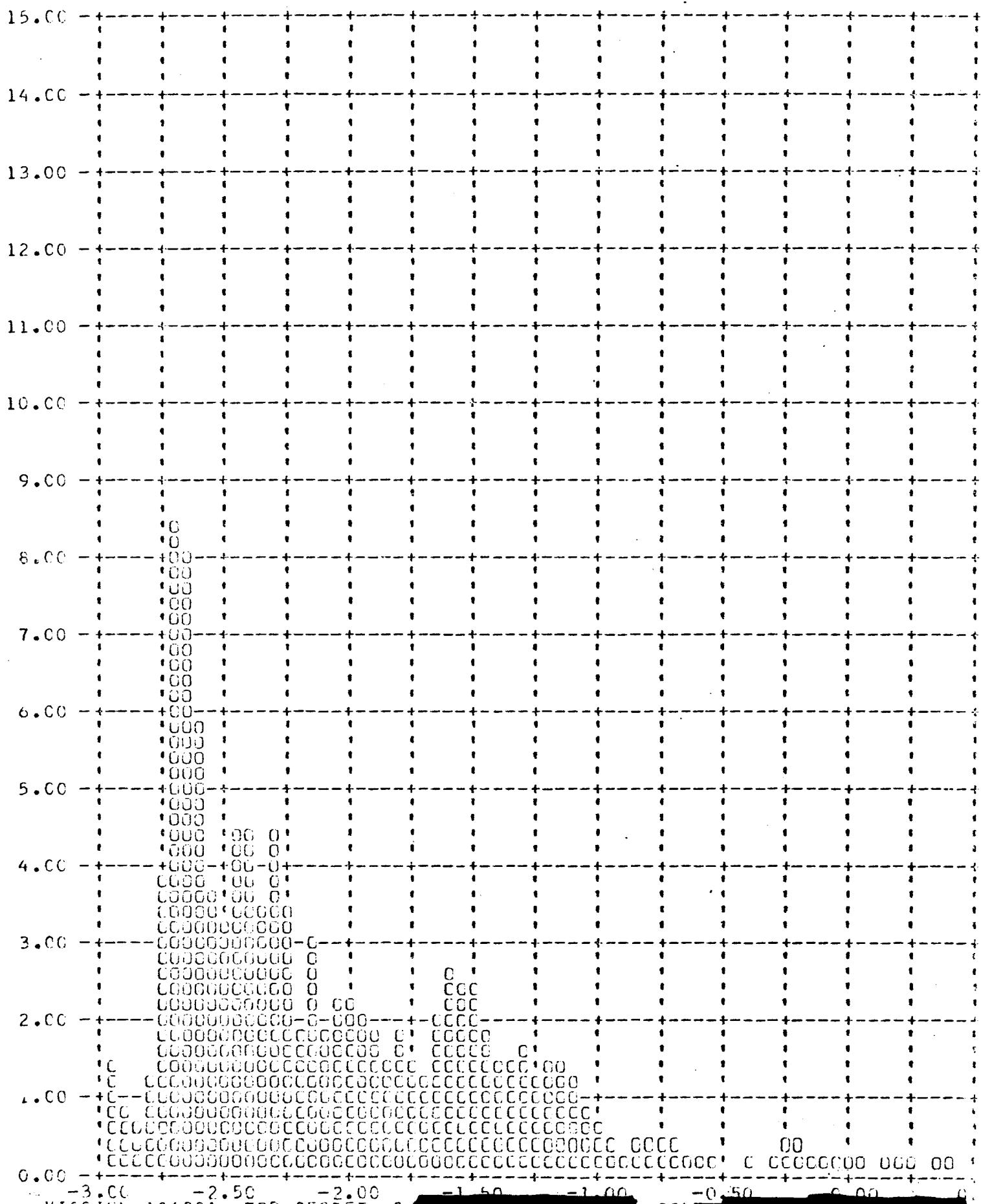
MISSION 1043B1 ~~TOP SECRET~~ C [REDACTED]

CONTROL NO. [REDACTED]

RECORDED 5/29

MISSION 104381 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED]
FRAMES 1-6 OF EACH CP OMITTED 90 PERCENT = 2.7

Y YAW ANGLE ERROR - DEGREES (X) VERSUS FREQUENCY - PERCENT (Y)

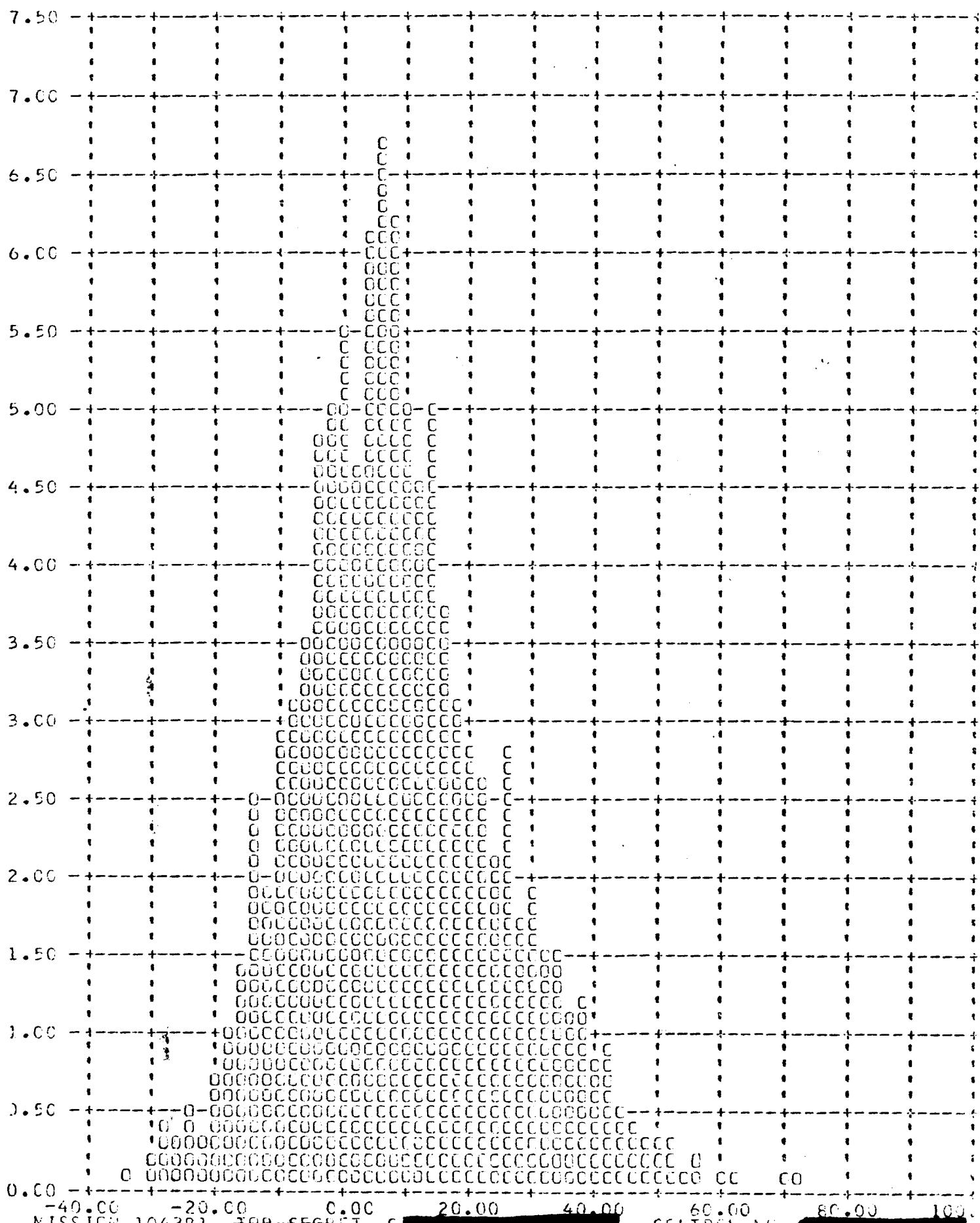


MISSION 104381 ~~TOP SECRET~~ C

CCN

MISSION 1043B1 ~~TOP SECRET~~ C [REDACTED] - CONTROL NO. [REDACTED]
FRAMES 1-6 OF EACH LP COMPUTED 90 PERCENT = 29.1

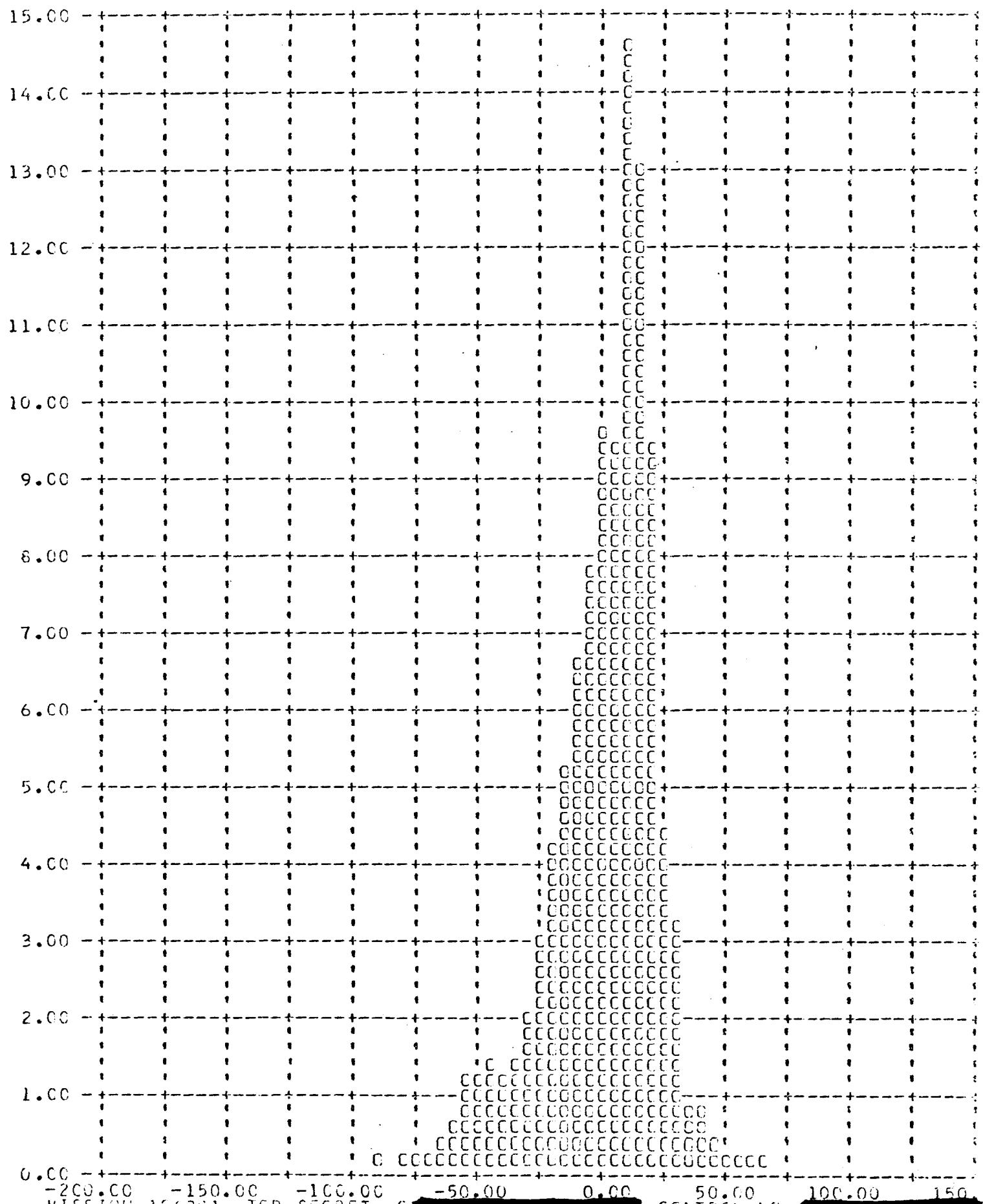
Y PITCH RATE ERROR - DEG/HCLR (X) VERSUS FREQUENCY - PERCENT (Y)



MISSION 1043B1 ~~TOP SECRET~~ C [REDACTED] - CONTROL NO. [REDACTED]

MISSION 1043B1 - ~~TOP SECRET~~ C - CONTROL NO. [REDACTED] -
FRAMES 1-6 OF EACH CP OMITTED 90 PERCENT = 31.5

Y ROLL RATE ERROR - DEG/HOUR (X) VERSUS FREQUENCY - PERCENT (Y)

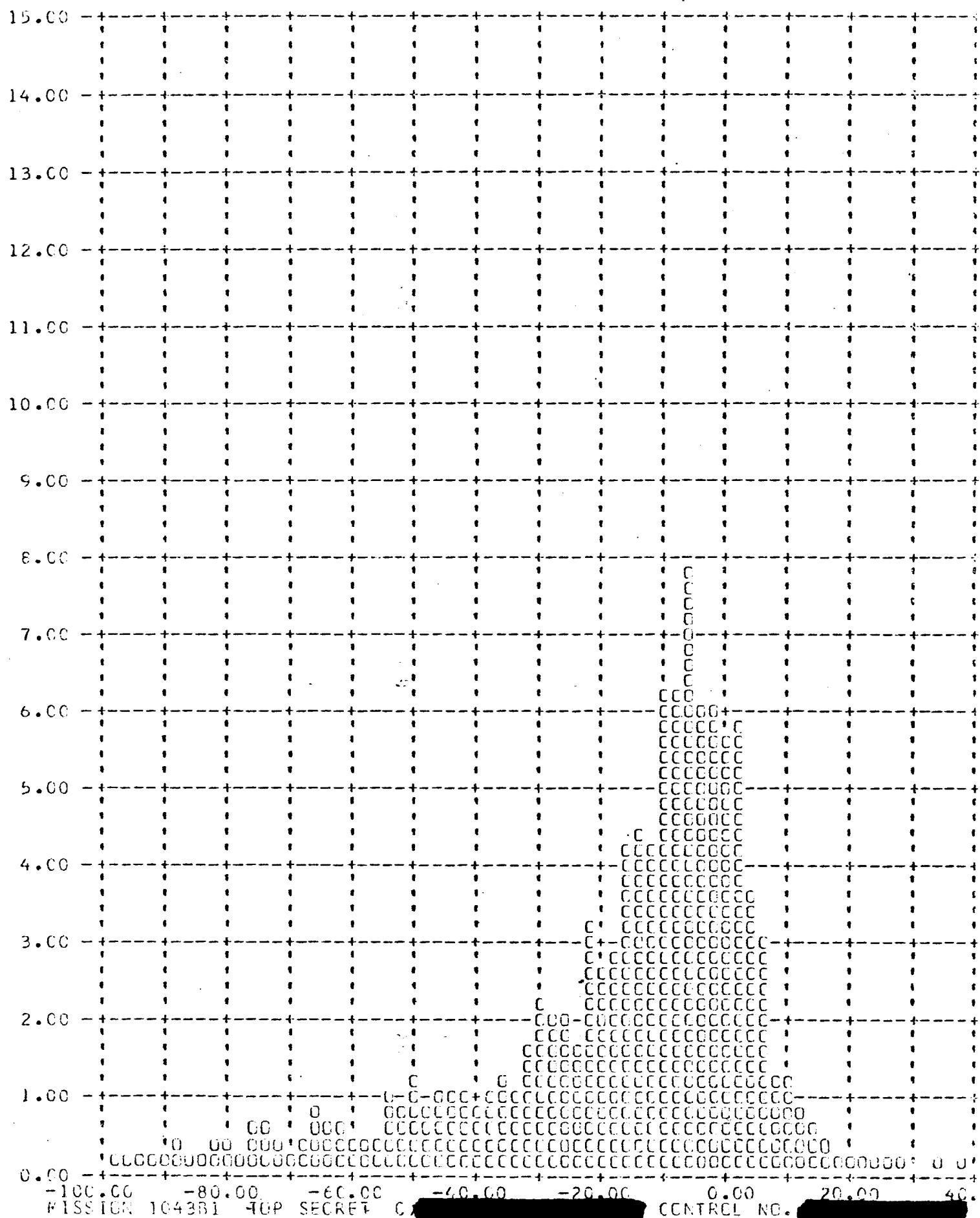


-200.00 -150.00 -100.00 -50.00 0.00 50.00 100.00 150.
MISSION 1043B1 ~~TOP SECRET~~ C [REDACTED]

CONTROL NO. [REDACTED]

MISSION 1043B1 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED] - FRAMES 1-6 OF EACH LP COMMITTED 90 PERCENT = 47.5

Y YAW RATE ERROR - DEG/HOUR (X) VERSUS FREQUENCY - PERCENT (Y)



MISSION 1043B1 ~~TOP SECRET~~ C

CONTROL NO. [REDACTED]

SECTION 8

IMAGE SMEAR ANALYSIS

The frame correlation tape supplied to A/P by NPIC contains the binary time word of each frame of photography. A computer program has been assembled at A/P which calculates the exposure time of each frame and compares the camera cycle rate with the ephemeris to calculate the FMC mismatch (Section 3), which is then combined with the vehicle attitude error and rate values of each frame and the crab error caused by earth rotation at the latitude of each frame. The program outputs the total along-track and cross-track IMC error and the limit of ground resolution that can be acquired by a camera regardless of focal length and system capabilities.

The computer rejects the first six frames of all operations as the FMC large error induced by camera start-up is not representative of the overall system operations. The frequency distribution of the FMC errors and resolution limits are computer plotted and are shown in Figures 8-1 through 8-12.

The summary table 8-1 presents the maximum FMC ratio errors and resolution limits that existed during 90% of the photographic operations, and the total range of values during all operations that were computed.

Because of the abnormal nonlinearity of scan rate to cycle rate for the forward camera, it is difficult to extrapolate actual photographic quality from these data.

MISSION 1043

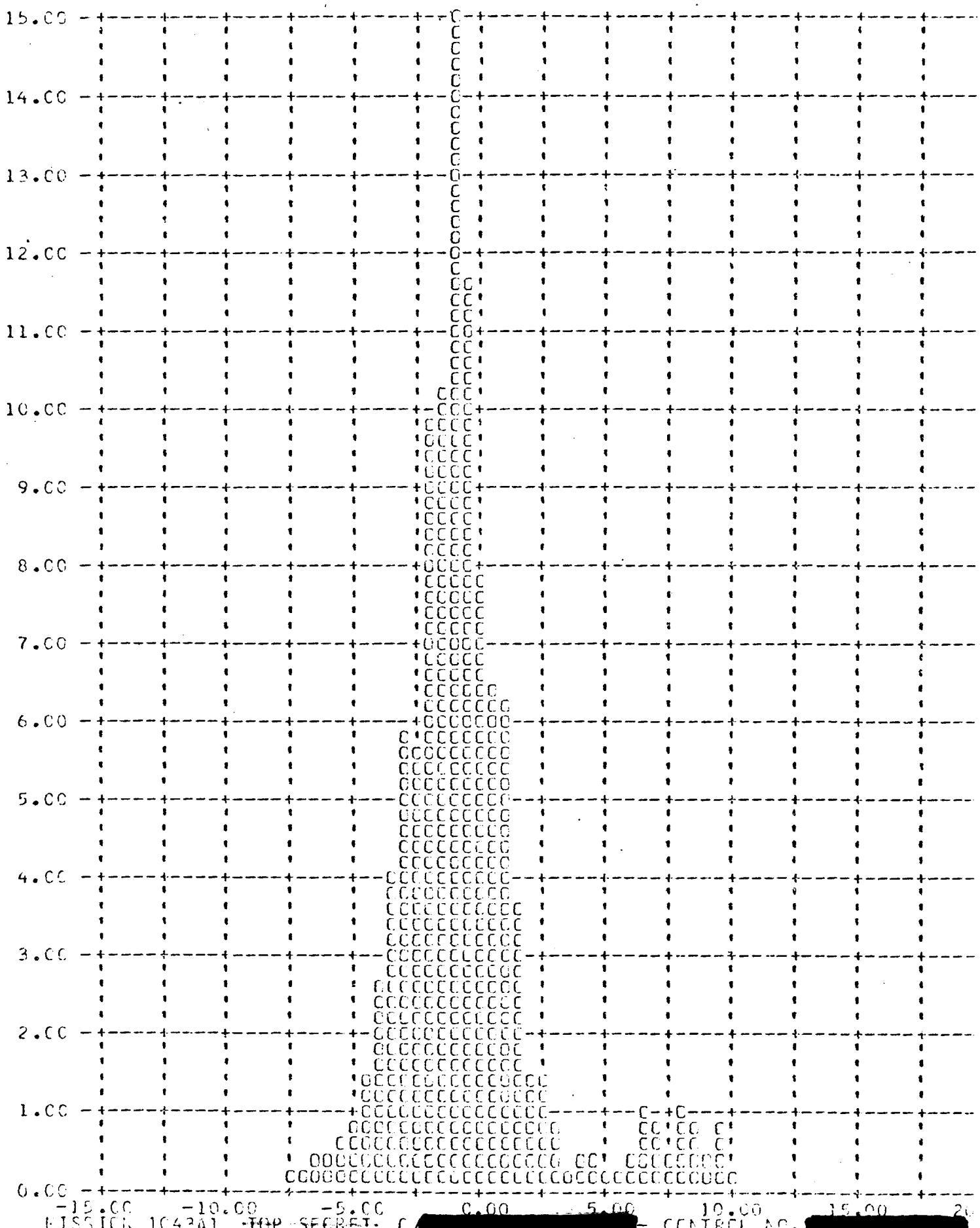
FMC ERROR AND RESOLUTION LIMITS

<u>Value</u>	<u>Units</u>	MISSION 1043-1			MISSION 1043-2		
		<u>Camera</u>	<u>90%</u>	<u>Range</u>	<u>90%</u>	<u>Range</u>	
FMC Error	FWD	4.21	-7.5 to +10.0	4.44	-12.0 to +4.0		
	AFT	3.26	-4.5 to +12.0	3.21	-10.0 to +9.5		
Along-Track Resolution Limit	FWD	5.41	0.2 to 12.2	5.29	+0.2 to +17.5		
	AFT	2.77	0.2 to 10.2	2.77	+0.2 to +10.2		
Cross-Track Resolution Limit	FWD	1.51	0.2 to 4.4	2.22	+0.2 to + 4.0		
	AFT	0.82	0.2 to 4.0	0.92	0.2 to + 2.30		

TABLE 8-1

MISSION 1043A1 ~~TOP SECRET~~ C - CENTREL NO. [REDACTED] - FRAMES 1-6 OF EACH UP OMITTED SO PERCENT = 4.

Y INC, ERROR -- PERCENT (X) VERSUS FREQUENCY -- PERCENT (Y)



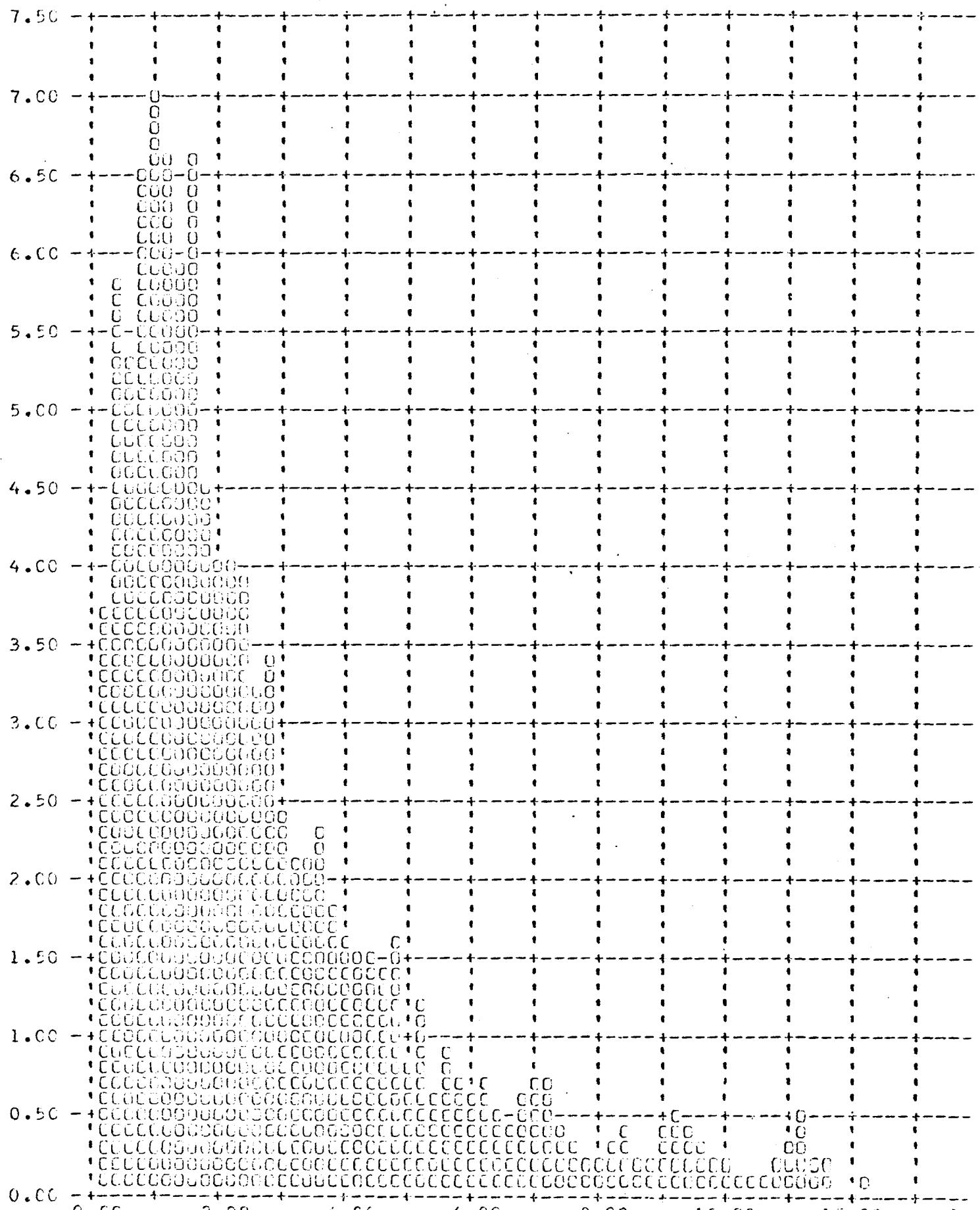
MISSION 1043A1 ~~TOP SECRET~~ C

CENTREL NO. [REDACTED]

RECORDED 5/13

MISSION 1043A1 -TOP SECRET C - CONTROL NO. [REDACTED]
FRAMES 1-6 OF EACH CP OMITTED 90 PERCENT = 5.

Y ALONG TRACK RESOLUTION LIMIT - FEET (X) VERSUS FREQUENCY - PERCENT (%)

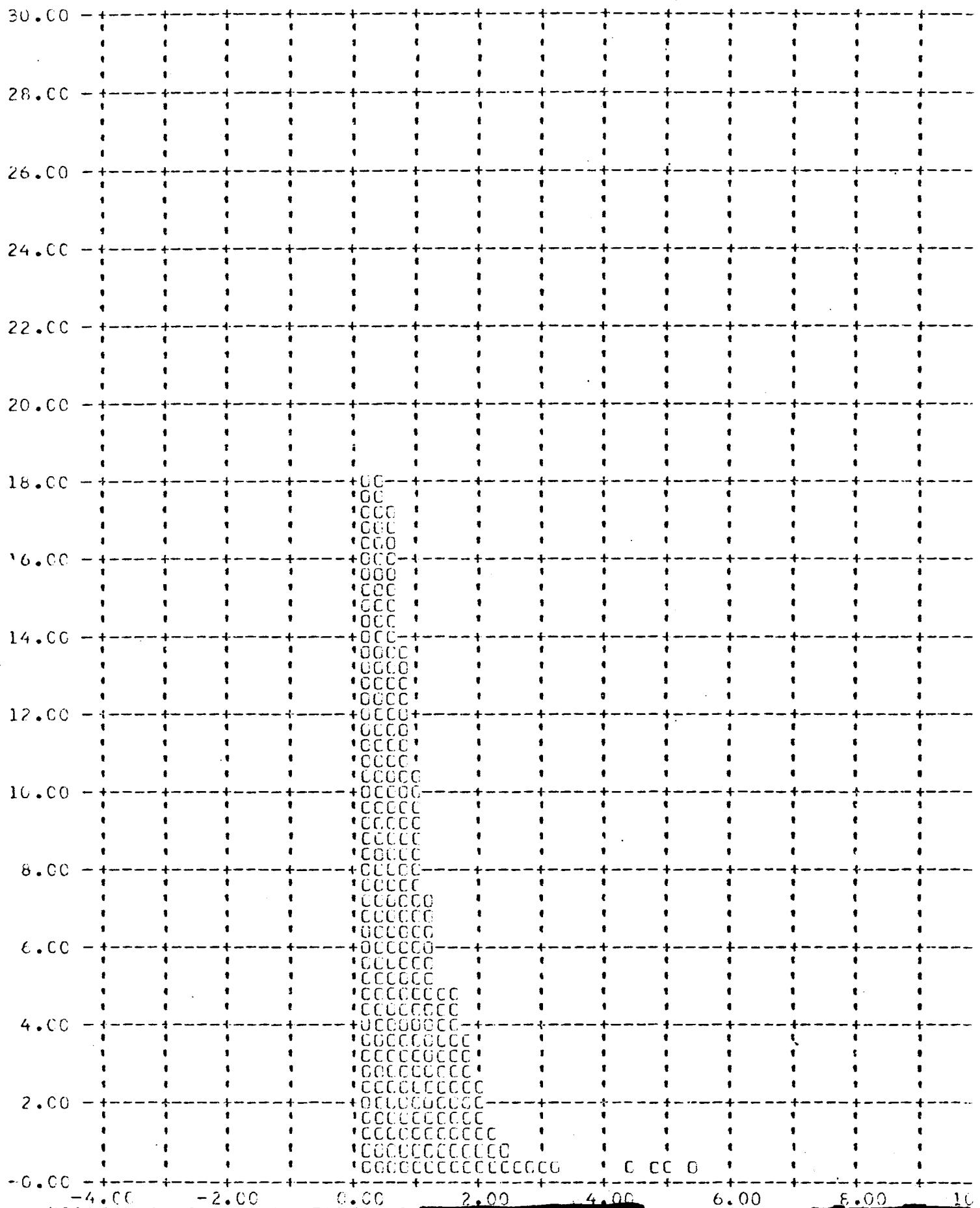


MISSION 1043A1 -TOP SECRET C

- CONTROL NO. [REDACTED]

MISSION 1043A1 ~~TOP SECRET~~ C CONTROL NO. [REDACTED] FRAMES 1-6 OF EACH CP OMITTED 90 PERCENT = 1.

Y CROSS TRACK RESOLUTION LIMIT - FEET (X) VERSUS FREQUENCY - PERCENT (



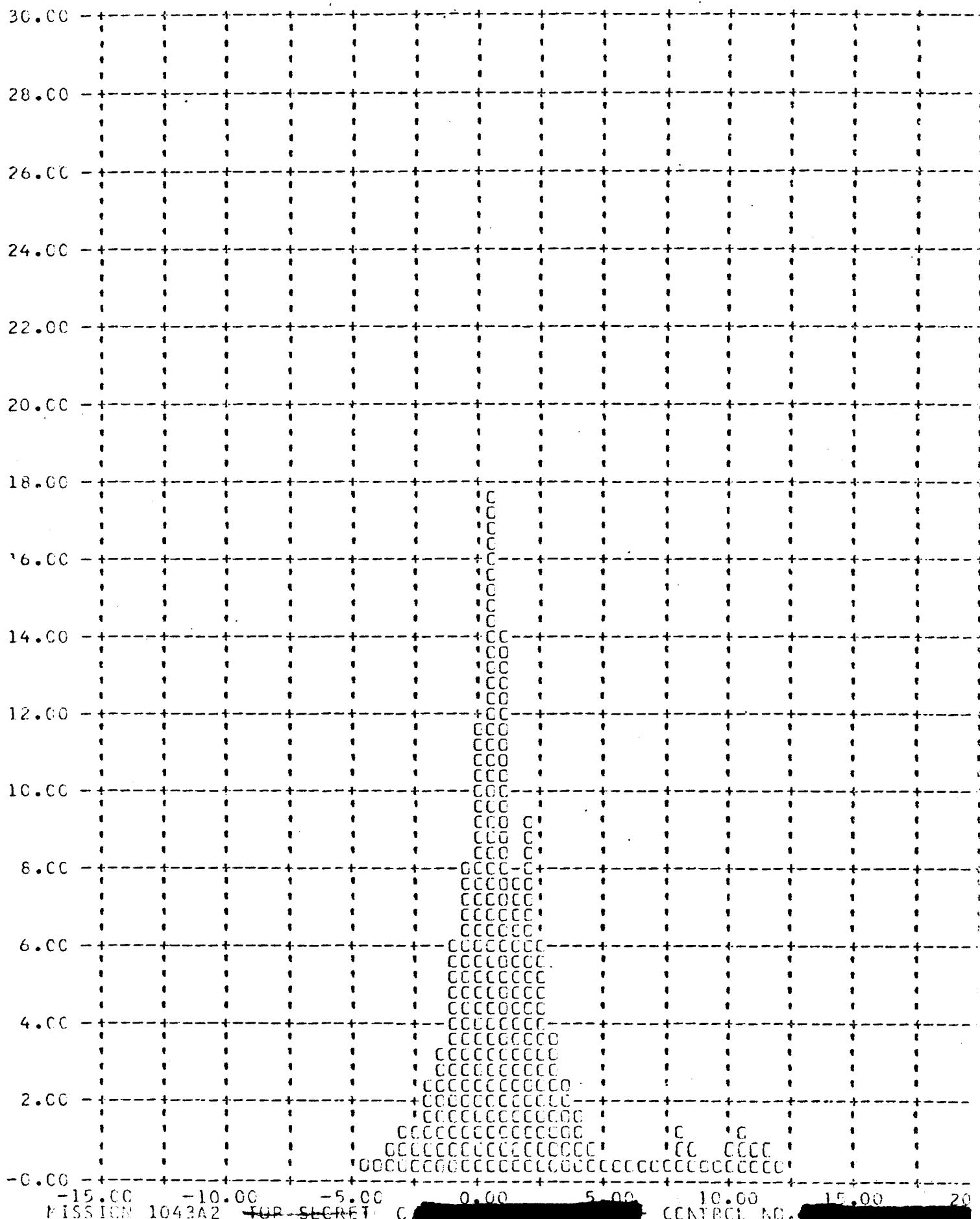
MISSION 1043A1 ~~TOP SECRET~~ C

CONTROL NO. [REDACTED]

PAGE ONE

MISSION 1043A2 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED]
FRAMES 1-6 OF EACH LP CHITTED 90 PERCENT = 3.2

Y IMC ERROR -- PERCENT (X) VERSUS FREQUENCY -- PERCENT (Y)



MISSION 1043A2 ~~TOP SECRET~~ C

CENTRAL NO. [REDACTED]

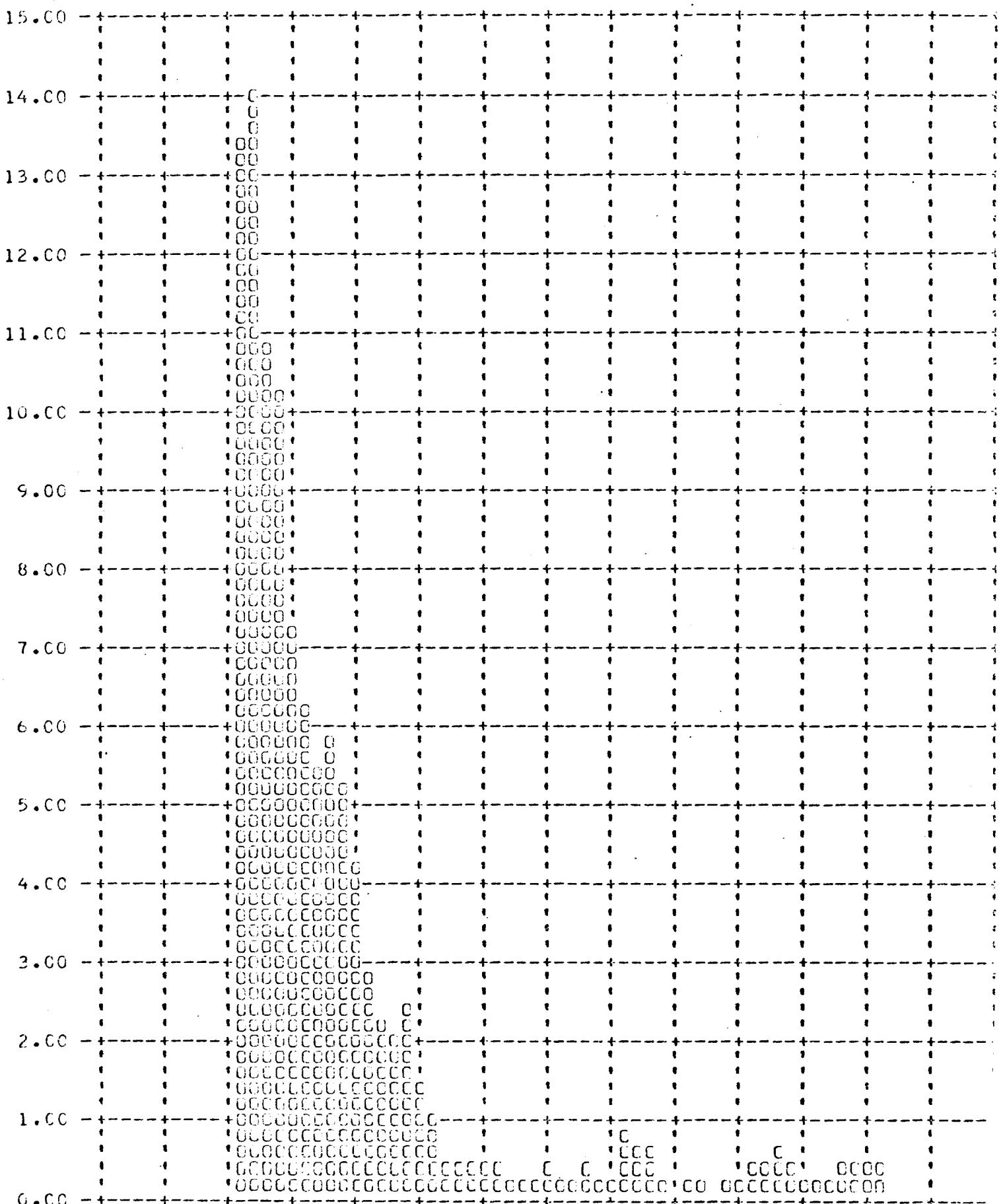
MISSION 1043A2

~~TOP SECRET~~

C

- CONTROL NO. [REDACTED] -
FRAMES 1 TO 6 OF EACH CP OMITTED 90 PERCENT - 2.

Y ALONG TRACK RESOLUTION LIMIT - FEET (X) VERSUS FREQUENCY - PERCENT (%)



MISSION 1043A2

~~TOP SECRET~~

C

- CONTROL NO. [REDACTED]

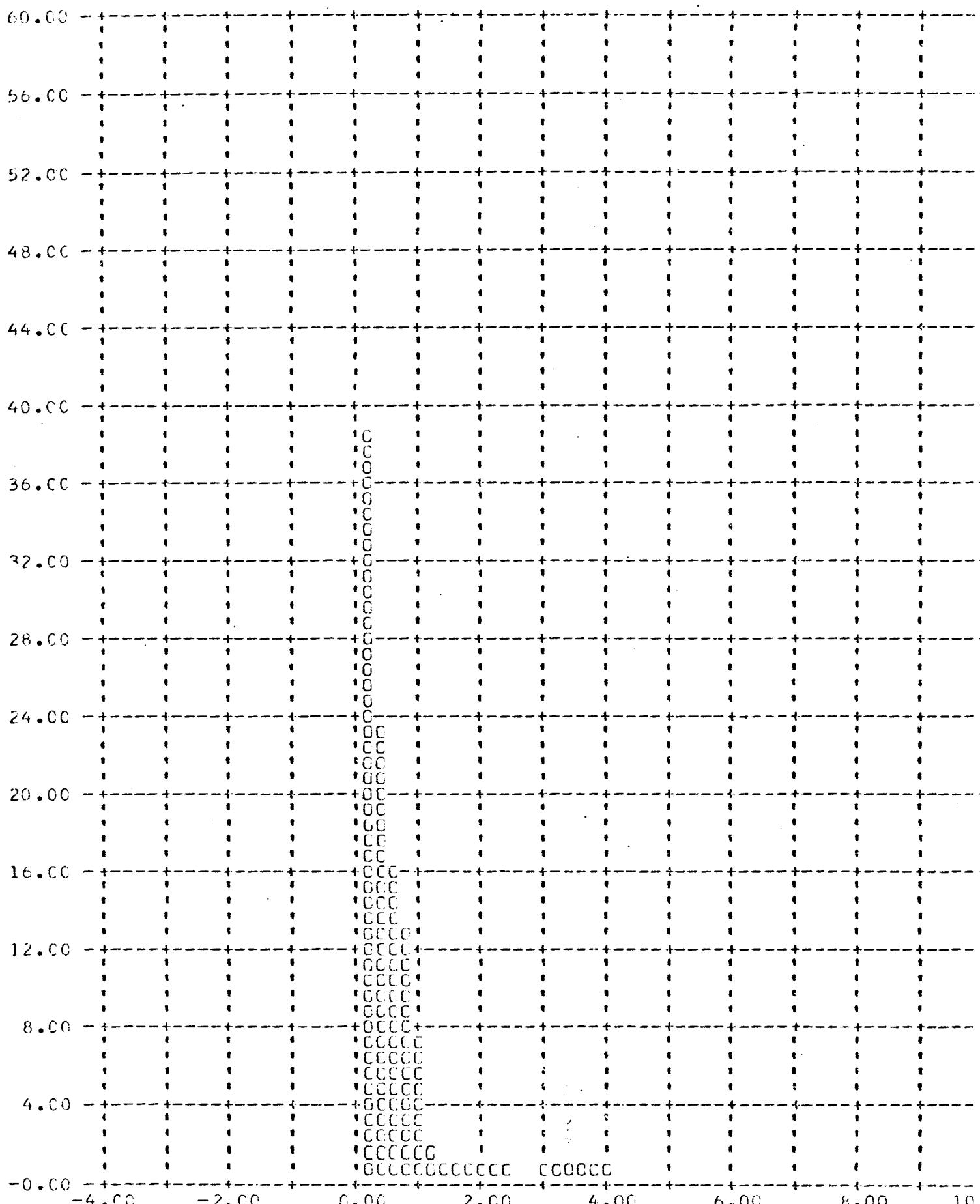
MISSION 1043A2

~~TOP SECRET~~

C [REDACTED] - CONTROL NO.

FRAMES 1-6 OF EACH EP COMMITTED 50 PERCENT = 6.0

Y CROSS TRACK RESOLUTION LIMIT - FEET (X) VERSUS FREQUENCY - PERCENT (%)



MISSION 1043A2

~~TOP SECRET~~

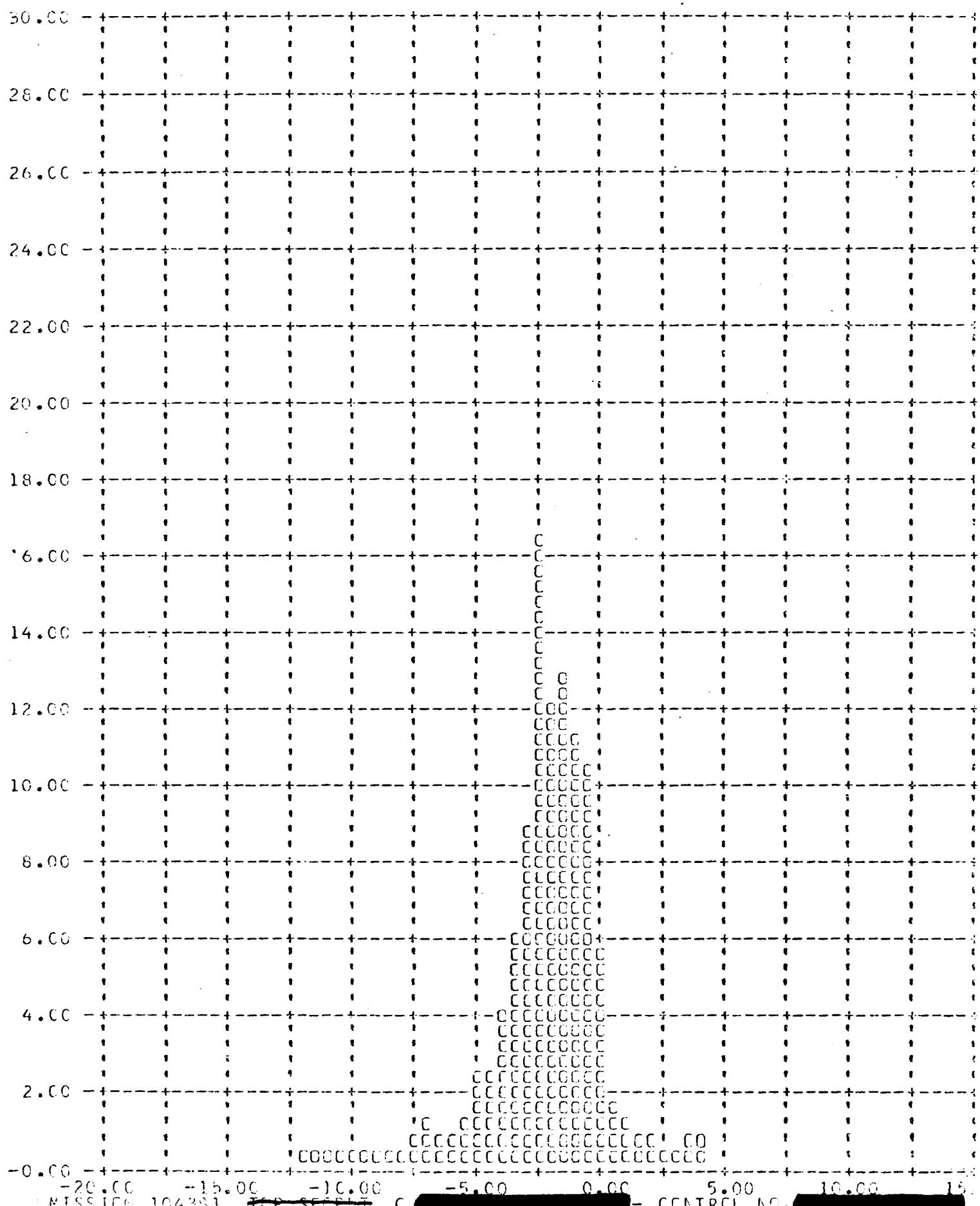
C [REDACTED]

CONTROL NO.

FIGURE 3-6

MISSION 104381 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED] - CONTROL NO.
FRAMES 2 & 3 OF EACH CP OMITTED 90 PERCENT = 4.0

Y INC ERROR -- PERCENT (X) VERSUS FREQUENCY -- PERCENT (Y)

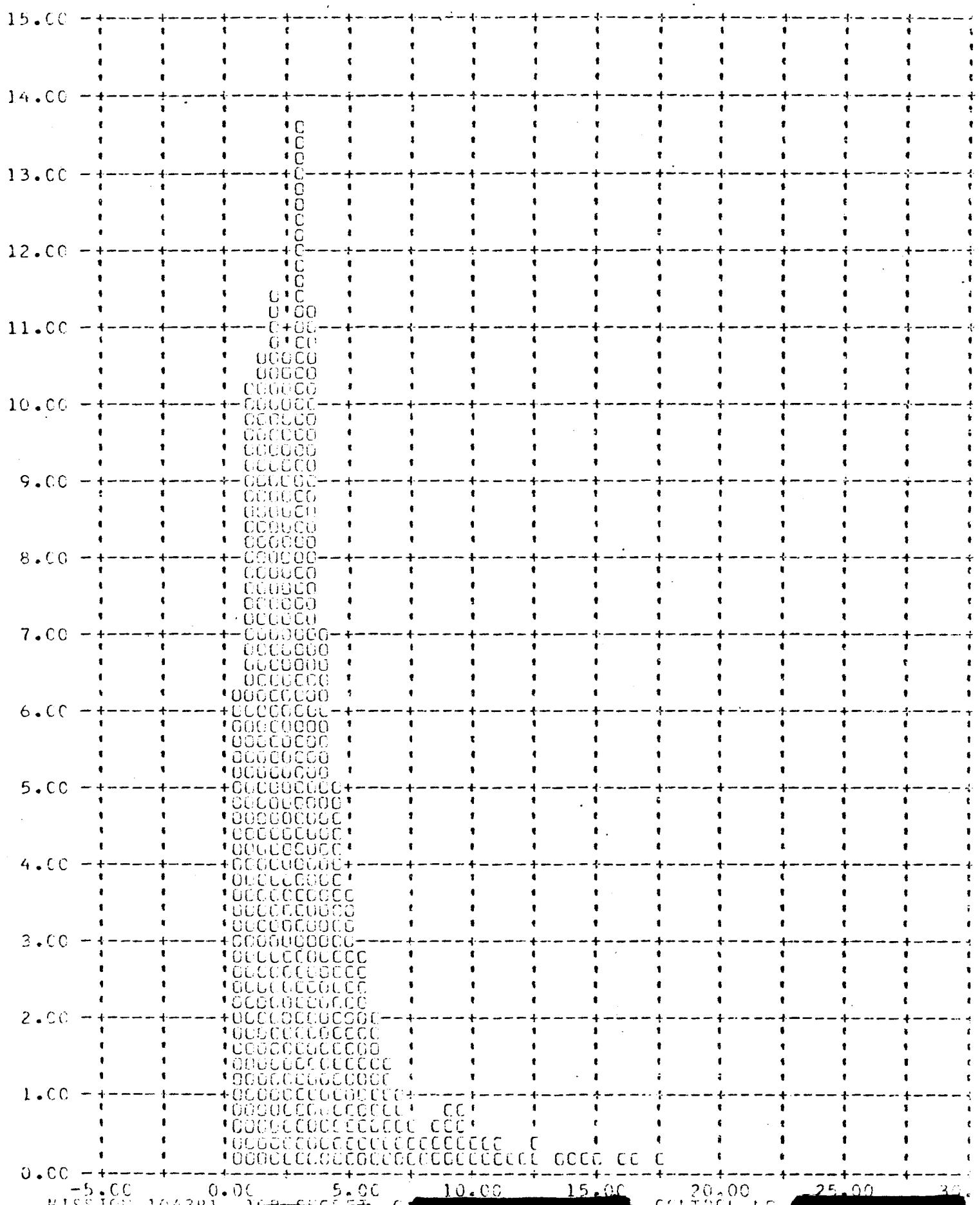


MISSION 104381 ~~TOP SECRET~~ C

CENTRCL NO.

MISSION 1043B1 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED] -
FRAMES 1 TO 10 EACH OF SPOTTED 90 PERCENT = 5.2

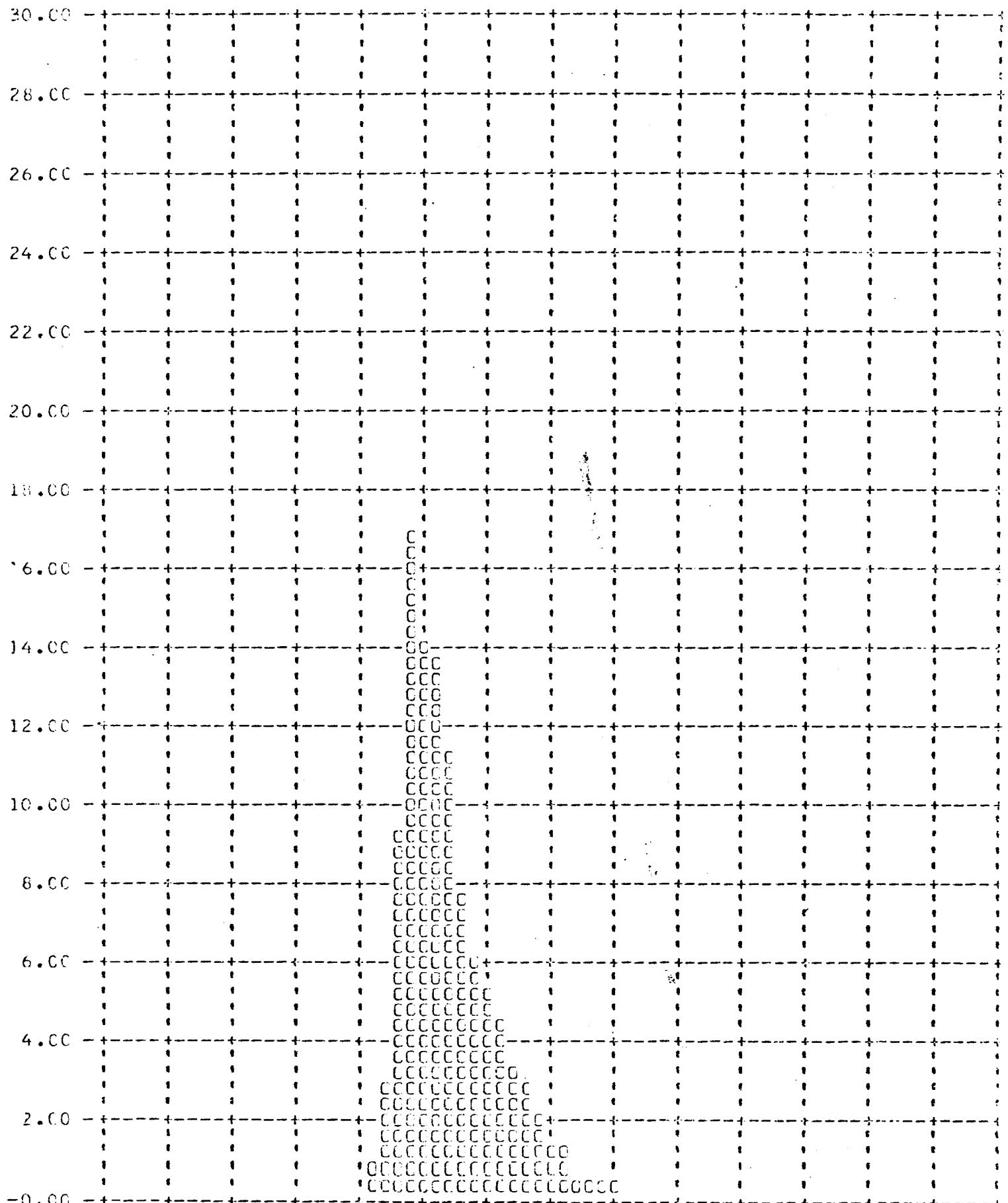
Y ALONG TRACK RESOLUTION LIMIT - FEET (X) VERSUS FREQUENCY - PERCENT (Y)



MISSION 1043B1 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED]

MISSION 1043B1 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED]
FRAMES 1-6 OF EACH LP OMITTED 90 PERCENT = 2.2

Y CROSS TRACK RESOLUTION LIMIT - FEET (X) VERSUS FREQUENCY - PERCENT (%)



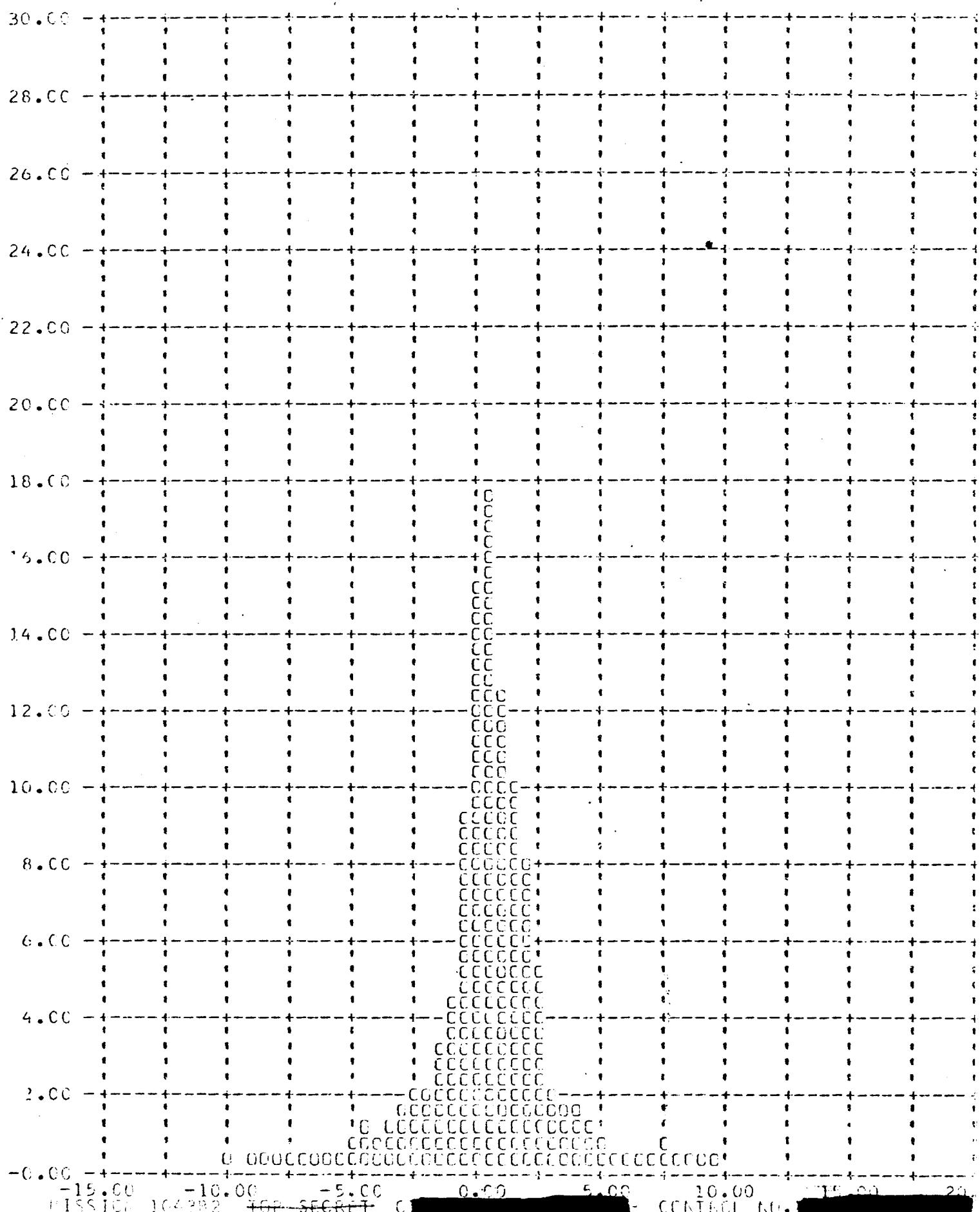
MISSION 1043B1 ~~TOP SECRET~~ C

C - CONTROL NO. [REDACTED]

PAGE NUMBER P-2

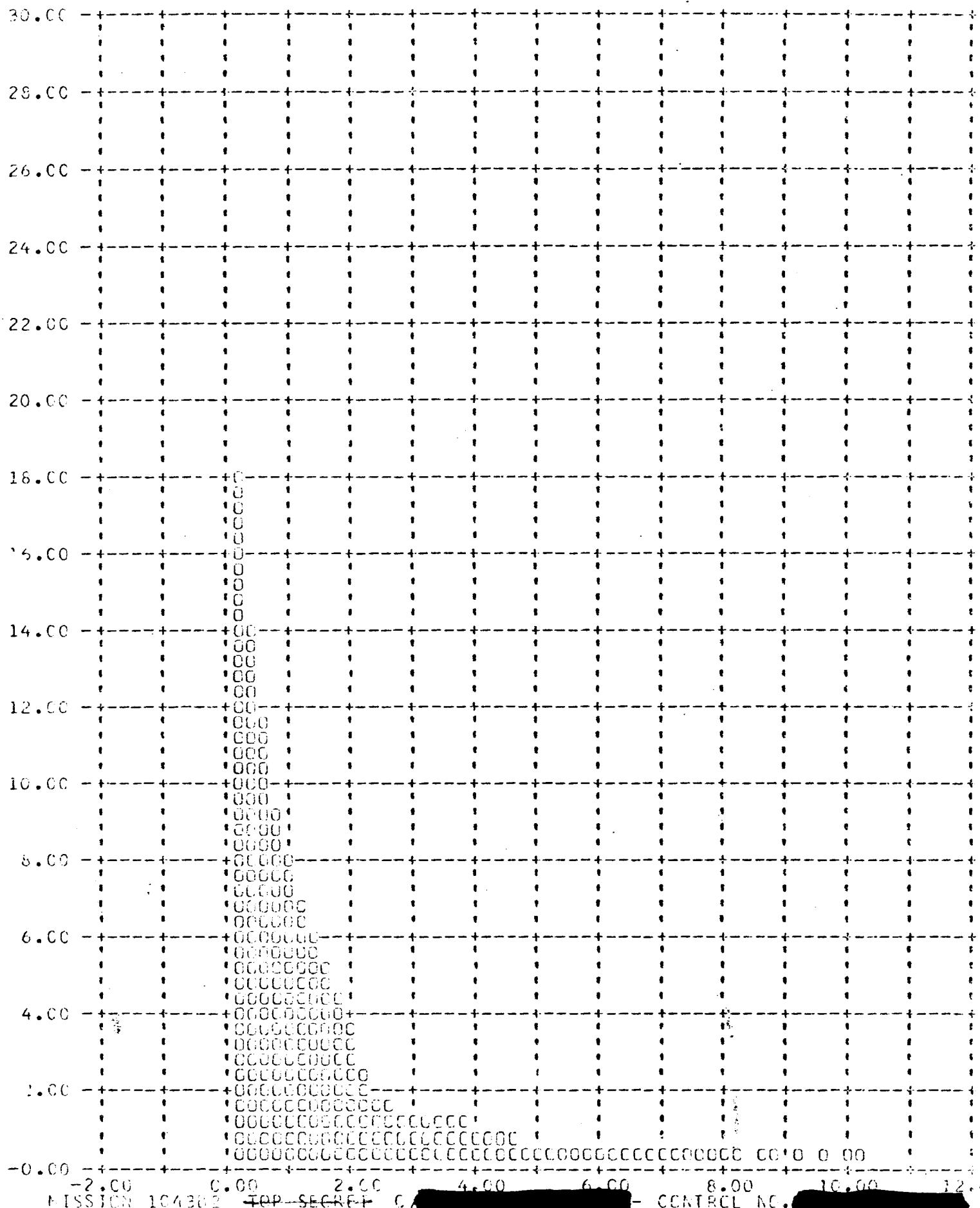
MISSION 104382 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED] -
FRAMES 1-6 OF EACH UP DMITTED 50 PERCENT = 3.2

Y INC ERROR -- PERCENT (X) VERSUS FREQUENCY -- PERCENT (Y)



MISSION 104382 ~~TOP SECRET~~ C - CONTROL NO. [REDACTED]
FRAMES 1-6 OF EACH CP OMITTED 90 PERCENT = 2.7%

Y ALONG TRACK RESOLUTION LIMIT - FEET (X) VERSUS FREQUENCY - PERCENT (Y)

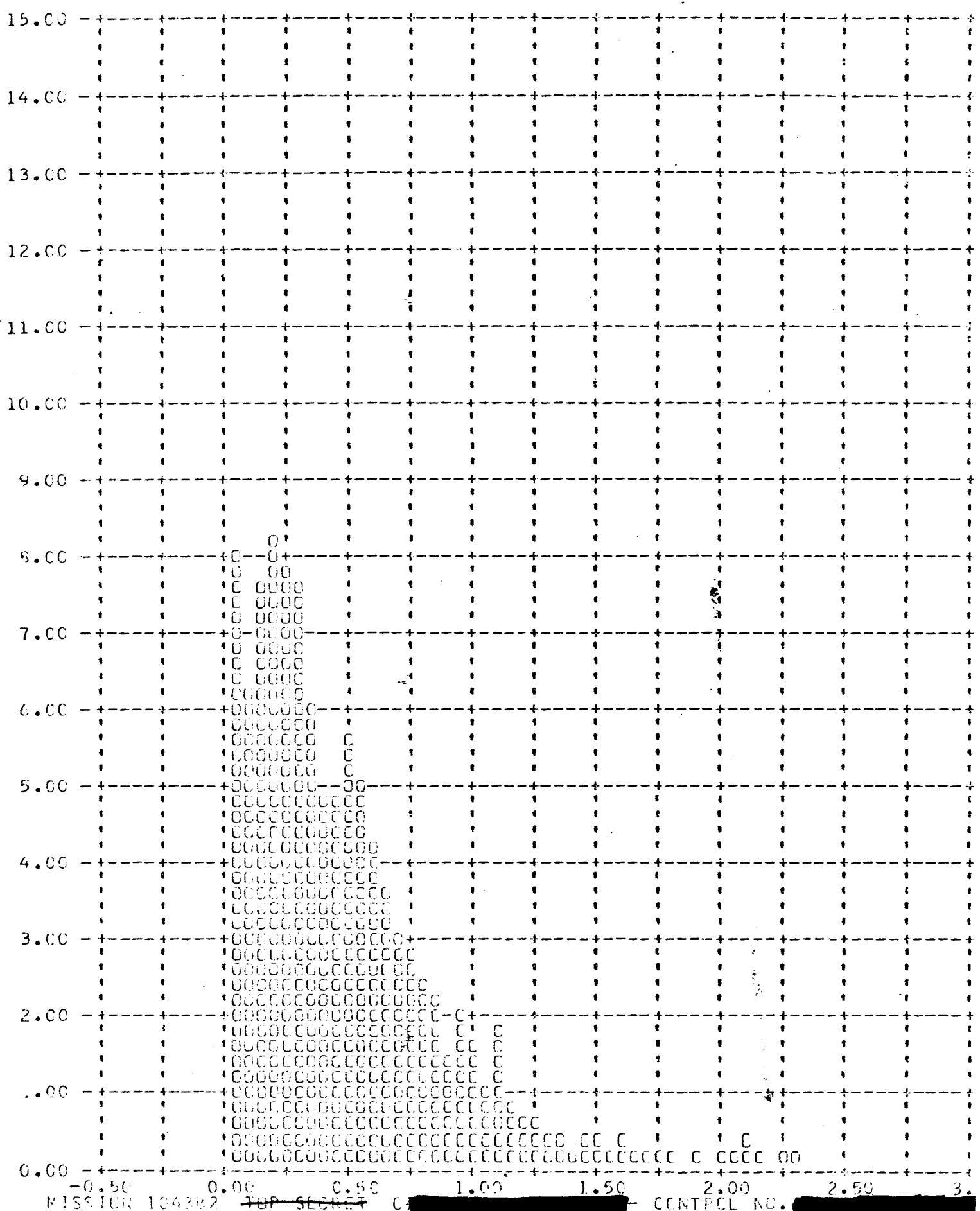


MISSION 104382 ~~TOP SECRET~~ C

- CONTROL NO. [REDACTED]

MISSION 1043B2 ~~TOP SECRET C~~ - CONTROL NO. ~~C~~
FRAMES 1-6 CP EACH CP OMITTED 90 PERCENT = 0.9.

Y CROSS TRACK RESOLUTION LIMIT - FEET (X) VERSUS FREQUENCY - PERCENT (Y)



MISSION 1043B2 ~~TOP SECRET C~~

- CONTROL NO. ~~C~~

SECTION 9

SYSTEM RELIABILITY

Reliability calculations for the payload are based on a sample beginning with M-7. Hence both the major part of the Mural Program and the "J" Program are covered in the calculation. For certain auxiliaries, i.e., the stellar-index camera and the horizon cameras, the sample size is changed to recognize incorporation of modified equipment or new designs where reliability was one of the principal reasons for the modification. However, for primary mission function, the sample size is consistent with reliability reporting for the vehicle.

The reliability estimates of this section deal exclusively with the payload. Failures to achieve orbit or vehicle induced failures are thereby excluded. Recoveries before a complete mission has been completed are considered as full missions providing that early termination was caused by reasons not connected with payload operation. Film quality is not considered in the reliability estimate calculation. Hence, only electrical and mechanical functioning are considered.

The reliability estimate is also divided into primary and secondary functions. The primary functions are operation of the panoramic cameras, main camera door operation, operation of the payload clock, and recovery operations. The secondary mission functions are horizon camera operation excluding catastrophic open shutter failure mode, auxiliary data recording,

and stellar-index camera operation. A summary of estimated reliability is shown in Tables 9-1.

Panoramic Camera Reliability

Sample Size - 187 opportunities to operate.

Two Failures - S/I Programmer on System J-19
Film transport on System J-42

Assume - 3000 cycles per camera per mission.

Estimated Reliability = 98.6 at 50% confidence level.

Main Camera Door Reliability

Sample Size - 60 vehicles x 2 doors = 120 opportunities to operate

Estimated Reliability = 99.4% at 50%

Payload Command and Control

Sample Size - 10,896 hours operation in sample

Two failures

Estimated Reliability = 97.7 at 50% confidence level

Payload Clock Reliability

Sample Size - 10,896 hours operation in sample

No failures

Estimated Reliability = 99.4% at 50% confidence level

Estimated Reliability of Payload Functioning on orbit = 97.2 at 50% confidence level.

Recovery System Reliability

85 opportunities to recover

1 failure - improper separation due to water seal - cutter failure

Estimated Reliability = 98.0 at 50% confidence level

NO.

Stellar-Index Camera Reliability

Sample begins with J5

Sample size = 27,630 cycles

Four failures

Estimated Reliability = 93.1% at 50% confidence level

Horizon Camera Reliability

Sample begins with J5 - 109,000 cycles

Estimated Reliability of Single Camera = 99.0% at 50%
confidence level.Estimated Reliability of Four Horizon Cameras at a Parallel
Redundant System = 99.9% at 50% confidence level.

ESTIMATED RELIABILITY SUMMARY

(AT 50% CONFIDENCE LEVEL)

-TOP SECRET C

NO. [REDACTED]

MISSION NUMBER	PRIMARY FUNCTIONS						SECONDARY FUNCTIONS					
	PANOPTIC CAMERA COMMAND & CONTROL SYSTEM			PAYLOAD CLOCK			ON-ORBIT FUNCTIONS			STELLAR-INDEX HORIZON CAMERAS		
	SAMPLE	SAMPLE	SAMPLE	SAMPLE	SAMPLE	SAMPLE	SAMPLE	SAMPLE	SAMPLE	SAMPLE	SAMPLE	SAMPLE
	FAILURES	FAILURES	FAILURES	FAILURES	FAILURES	FAILURES	FAILURES	FAILURES	FAILURES	FAILURES	FAILURES	FAILURES
	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY
	3124 HOURS	3124 HOURS	3124 HOURS	3124 HOURS	3124 HOURS	3124 HOURS	3124 HOURS	3124 HOURS	3124 CYCLES	3124 CYCLES	3124 CYCLES	3124 CYCLES
9018 TO 10008	52	0	0	0	0	0	96.1	96.1	10,000 CYCLES	10,000 CYCLES	10,000 CYCLES	10,000 CYCLES
	1	97.3	93.6	98.0	98.0	98.0	90.7	90.7	3	0	0	0
1009	54	0	0	0	0	0	96.2	96.2	4250	4250	4250	4250
	1	97.4	93.7	98.0	98.0	98.0	91.5	91.5	3	0	0	0
1010	55	0	0	0	0	0	96.4	96.4	5100	5100	5100	5100
	1	97.6	98.8	98.1	98.1	98.1	92.5	92.5	3	0	0	0
1011	72	0	0	0	0	0	96.8	96.8	21,000	21,000	21,000	21,000
	1	97.7	98.9	98.1	98.1	98.1	93.0	93.0	0*	0	0	0
1012	76	60	0	0	0	0	95.9	95.9	5525	5525	5525	5525
	1	97.8	98.9	98.2	98.2	98.2	93.5	93.5	0	0	0	0
1013	78	62	0	0	0	0	96.0	96.0	5950	5950	5950	5950
	1	97.8	99.0	95.9	95.9	95.9	94.0	94.0	0	0	0	0
1014	82	64	4056	4056	4056	4056	96.1	96.1	6375	6375	6375	6375
	1	97.9	99.0	96.1	96.1	96.1	94.4	94.4	1	0	0	0
1015	86	66	4320	4320	4320	4320	96.1	96.1	7225	7225	7225	7225
	1	98.0	99.0	96.3	96.3	96.3	94.6	94.6	1	0	0	0
1016	90	68	4550	4550	4550	4550	96.4	96.4	7650	7650	7650	7650
	1	98.1	99.0	96.5	96.5	96.5	95.2	95.2	1	0	0	0
1017	94	70	4760	4760	4760	4760	97.6	97.6	95.4	95.4	95.4	95.4
	0*	99.3	99.0	96.7	96.7	96.7	95.2	95.2	38	38	38	38
1018	96	72	4920	4920	4920	4920	96.7	96.7	8925	8925	8925	8925
	1	98.3	99.1	96.8	96.8	96.8	95.6	95.6	1	0	0	0
1019	102	74	5136	5136	5136	5136	96.8	96.8	6075**	6075**	6075**	6075**
	1	99.4	99.1	96.9	96.9	96.9	95.8	95.8	1	0	0	0

* DESIGN FIX INCORPORATED PREVIOUS FAILURE CONSIDERATIONS

** NO SAMPLE OUT OF SEVEN

~~TOP SECRET C~~ NO. [REDACTED]

ESTIMATED RELIABILITY SUMMARY

(AT 50% CONFIDENCE LEVEL)

MISSION NUMBER	PRIMARY FUNCTIONS						SECONDARY FUNCTIONS					
	PANORAMIC CAMERA DOORS			COMMAND & CONTROL SYSTEM			PAYLOAD CLOCK			ON - ORBIT FUNCTIONS		
	SAMPLE FAILURES	SAMPLE FAILURES	SAMPLE FAILURES	SAMPLE FAILURES	SAMPLE FAILURES	SAMPLE FAILURES	SAMPLE FAILURES	SAMPLE FAILURES	SAMPLE FAILURES	SAMPLE FAILURES	SAMPLE FAILURES	SAMPLE FAILURES
	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY	RELIABILITY
1020	78	5644	5544	0	99.1	97.1	0	98.9	96.9	96.9	10,680	48,000
1021	76	5376	5376	0	99.1	97.0	0	98.8	96.9	96.9	41	96.1
1022	80	5784	5784	0	99.1	97.0	0	98.8	96.9	96.9	45	98.0
1023	82	6000	6000	0	99.2	97.3	0	98.9	96.9	96.9	47	12,190
1024	84	6240	6240	0	99.2	95.8	0	98.9	96.2	96.2	49	13,040
1025	86	6480	6480	0	99.2	96.0	0	98.9	96.3	96.3	51	13,890
1026	88	6720	6720	0	99.2	96.1	0	99.0	96.4	96.4	53	14,740
1027	90	6744	6744	0	99.2	96.3	0	99.0	96.5	96.5	55	15,165
1028	92	6960	6960	0	99.2	96.3	0	99.0	96.5	96.5	57	16,015
1029	94	7120	7120	0	99.2	96.4	0	99.0	96.7	96.7	59	16,580
1030	96	7440	7440	0	99.3	96.5	0	99.1	97.1	97.1	61	17,430
1031	98	7704	7704	0	99.3	96.6	0	99.1	96.9	96.9	63	18,280

ESTIMATED RELIABILITY SUMMARY

(AT 50% CONFIDENCE LEVEL)

~~TOP SECRET C~~

NO. [REDACTED]

MISSION NUMBER	PRIMARY FUNCTIONS		SECONDARY FUNCTIONS	
	PANORAMIC CAMERA		RECOVERY SYSTEM	STELLAR INDEX CAMERAS
	SAMPLE DOORS	SAMPLE SAFETY	SAMPLE FAILURES	SAMPLE FAILURES
1033	100	75.08	7.08	97.1
1034	99.3	36.8	0	99.2
1035	102	82.08	0	97.2
1036	99.3	96.9	0	99.2
1037	99.4	97.1	0	97.4
1038	104	85.20	0	97.3
1039	105	99.3	0	99.2
1040	98.9	99.3	0	97.4
1041	99.0	99.4	0	99.3
1042	110	93.36	0	97.5
1043	112	99.4	0	99.3
1044	114	98.40	0	97.5
1045	116	99.4	0	99.3
1046	99.0	99.4	2	97.4
1047	99.1	99.4	2	97.5
1048	110	10.536	0	99.3
1049	110	99.4	2	97.6
1050	110	99.4	2	97.7
1051	120	10.896	0	99.4
1052	98.6	99.4	2	97.7

C [REDACTED] NO. [REDACTED]

SECTION 10

SUMMARY DATA

The comparison of the operating parameters and the performance achieved by previous missions has been difficult due to the large volume of data that results from each mission. Some of the pertinent characteristics from prior missions have been summarized in Tables 10-1 through 10-3.

The summary data was started with Mission 1004 as the J-05 camera system was the first to incorporate the major modifications of the titanium drum and scan arm, four roller scan head and Corona J capabilities. Only those missions that culminated in the recovery of some photography have been listed, therefore Missions 1003, 1005 and 1032 are deleted.

MISSION SUMMARY

~~TOP SECRET C~~ NO.

MISSION NUMBER	PAYOUT NUMBER	VEHICLE NUMBER	LAUNCH DATE	LAUNCH TIME	ORBIT INCLINATION (°)	ALTITUDE (NM)	PERIGEE LOCATION (°N)	RECOVERY PASS	MASTER CAMERA NUMBER	SLAVE CAMERA NUMBER	FILTER TYPE	CAVERA SLIT (#)	SLAVE CAVERA SLIT (#)	FILTER TYPE	STELLAR INDEX	CAMERA NUMBER	
1004	J-05	1174	2/15/64	2130 Z	74.9	99.9	29.0	49	124	0 250	W-21	125	0 250	W-21	D29/23/29	042/42/37	
1005	J-03	1176	6/4/64	2259 Z	79.9	84.0	63.2	65	128	148	0 200	W-21	149	0 200	W-21	D45/47/45	D49/53/42
1007	J-07	1609	6/19/64	2318 Z	85.0	99.2	41.5	65	120	144	0 250	W-25	145	0 200	W-21	D43/43/43	D54/56/51
1008	J-10	1177	7/10/64	2314 Z	85.0	99.4	40.8	49	112	150	0 200	W-21	151	0 200	W-21	D48/45/18	D53/28/32
1009	J-12	1605	8/5/64	2316 Z	80.1	99.6	39.5	49	128	154	0 200	W-21	155	0 200	W-21	D56/54/56	D38/28/34
1010	J-11	1178	9/14/64	2254 Z	84.9	97.4	42.5	65	144	152	0 175	W-21	153	0 175	W-21	D41/41/41	D44/46/46
1011	J-3X	1170	10/5/64	2150 Z	79.9	99.3	20.9	65	—	160	0 175	W-21	161	0 175	W-21	D36/30/30	D57/57/57
1012	J-13	1179	10/17/64	2202 Z	75.0	96.2	32.4	49	81	156	0 200	W-21	157	0 200	W-21	D51/51/47	D46/52/53
1013	J-15	1173	11/2/64	2130 Z	80.0	100.0	25.0	65	81	158	0 225	W-21	159	0 225	W-21	D52/49/55	D47/48/54
1014	J-16	1100	11/18/64	2036 Z	70.0	103.2	65.6	81	145	162	0 250	W-25	139	0 175	W-21	D53/59/49	D50/44/46
1015	J-17	1607	12/19/64	2110 Z	74.9	96.7	21.5	81	175	138	0 250	W-25	141	0 175	W-21	D61/61/61	D58/58/58
1016	J-18	1608	1/15/65	2101 Z	74.9	99.4	30.2	81	159	132	0 250	W-25	133	0 175	W-21	D55/55/50	D59/50/59
1017	J-14	1611	2/25/65	2144 Z	75.0	97.2	25.9	81	145	140	0 250	W-25	165	0 175	W-21	D21/21/21	D60/E1/1
1018	J-19	1612	3/25/65	2111 Z	96.0	100.2	40.3	66	99	122	0 250	W-25	123	0 175	W-21	D20/20/20	D22/22/22
1019	J-04	1614	4/23/65	2144 Z	65.0	99.1	27.1	80	—	118	0 250	W-25	119	0 175	W-21	D39/39/35	D19/18/19
1020	J-20	1613	6/9/65	2158 Z	75.1	97.1	40.6	97	113	136	0 250	W-25	137	0 175	W-21	D67/85/80	D62/63/65
1021	J-21	1615	5/18/65	1803 Z	75.0	109.2	24.3	81	161	166	0 175	W-21	167	0 250	W-25	D63/69/69	D25/27/25
1022	J-22	1617	7/19/65	2201 Z	85.0	99.7	30.3	65	144	168	0 250	W-25	169	0 175	W-21	D65/77/70	D24/24/24
1023	J-23	1618	8/17/65	2100 Z	70.0	97.8	29.0	81	144	170	0 225	W-25	171	0 150	W-21	D17/19/82	D55/75/72
1024	J-24	1619	9/22/65	2131 Z	80.0	95.9	18.4	81	161	172	0 225	W-25	173	0 150	W-21	D69/72/84	D64/82/66
1025	JX-28	1616	10/5/65	1746 Z	75.0	112.9	44.3	81	161	142	0 175	W-21	127	0 175	W-21	D71/78/88	D70/89/83
1026	J-25	1620	10/28/65	2117 Z	75.0	23.0	17.0	81	160	174	0 225	W-25	175	0 150	W-21	D75/92/93	D72/89/85
1027	JX-27	1621	12/9/65	21:0 Z	80.0	97.4	17.3	17	33	164	0 250	W-25	163	0 175	W-21	D71/87/87	D66/74/83
1028	J-26	1610	12/24/65	2106 Z	30.0	97.6	28.4	61	144	176	0 250	W-25	177	0 175	W-21	D77/91/97	D74/76/95

MISSION SUMMARY

MISSION NUMBER	PAYLOAD NUMBER	VIRGIN NUMBER	LAUNCH DATE	LAUNCH TIME	OBJECT INCLINATION (°)	ALTITUDE LOCATION (km)	SLIGHT LOCATION (km)	RECOVERY FACES	MASTER CAMERA		SLAVE CAMERA		STELLAR INDEX CAMERA NUMBER
									CAMERA NUMBER	SPLIT TYPE	CAMERA NUMBER	SPLIT TYPE	
1029	J-27	1623	2/2/66	2132 2	75.1	95.5	22.5	31	160	W-25	179	W-21	D79/94/91 D76/70/94
1030	J-29	1622	3/9/66	2202 2	75.0	97.5	18.7	61	159	W-25	182	W-21	D94/100/07 D92/195/IC2
1031	J-30	1627	4/7/66	2202 2	75.1	104.5	23.3	113	177	W-23A	185	W-21	D93/101/89 D94/106/86
1032	J-20	1625	5/3/66	1725 2	—	—	—	—	—	W-21	181	W-21	D81/97/101 D80/73/100
1033	J-33	1630	5/24/66	2213 2	66.1	102.0	60.7	82	176	W-21	195	W-21	D91/105/09 D94/102/75
1034	J-31	1626	6/21/66	2131 2	80.1	105.4	18.2	81	161	W-23A	187	W-21	D85/109/76 CS7/107/105
1035	J-26	1623	9/20/66	2114 2	85.0	99.5	29.1	91	160	W-23A	189	W-21	D95/112/113 D75/110/4110
1036	J-32	1631	8/9/66	2204 2	100.0	102.4	22.9	115	172	W-23A	191	W-21	D89/110/111 D85/109/106
1037	J-33	1632	11/8/66	1057 2	105.0	91.8	14.5	66	197	W-23A	199	W-21	D10/112/128 D10/13C/134
1038	J-34	1629	11/15/67	2149 2	69.1	96.9	29.2	81	193	W-23A	193	W-21	C93/06/112 D9/111/108
1039	J-39	1625	2/22/67	2202 2	80.0	97.0	30.2	81	177	W-23A	207	W-21	D103/131/132 D100/125/125
1040	J-35	1636	3/30/67	1854 2	85.1	99.7	28.3	81	145	W-21	197	W-225	D78/95/96 D52/73/110
1041	J-40	1634	5/9/67	2132 2	85.1	100.1	33.0	93	208	W-23A	209	W-21	D105/134/133 D02/157/127
1042	J-37	1633	6/16/67	2135 2	80.0	96.5	29.1	97	240	W-23A	205	W-21	D37/120/117 D33/121/118
1043	J-42	1637	8/7/67	2144 2	80.0	102.1	16.3	113	240	W-23A	201	W-21	D107/135/135 D12/143/139

TABLE 10-1

PERFORMANCE SUMMARY

MISSION	CARRIER	TYPE	VEHICLE	SIGHTING	MATERIAL	SIGHTING	ATTITUDE	POSITION	PERCENT ATTITUDE ERROR (%)		PERCENT RATE OF TURN (%)		PERCENT V/H ERROR (%)	
									ROLL	PITCH	ROLL	PITCH	YAW	YAW
1004-1	FWD	124	6.5	4	5.7	10.9	1.5	12.7	0.45	0.42	1.08	3.0	25.0	21.0
1004-2	AFT	125	6.5	4	35.0	43	1.3	32.0	1.25	0.90	0.51	4.40	30.0	29.0
1006-1	FWD	146	9.0	7.0	5.5	88	8.4	97	0.41	0.42	1.14	26.8	28.5	27.8
1006-2	AFT	147	9.0	7.0	35.0	43	6.0	32.0	1.6	0.69	0.40	3.11	27.9	30.0
1007-1	FWD	144	6.5	5.0	5.0	87	6.2	91	0.58	0.46	1.43	37.6	23.9	29.9
1007-2	AFT	145	6.5	5.0	35.0	43	6.3	32.0	1.6	0.64	0.47	4.30	25.8	—
1008-1	FWD	150	1.0	10	8.0	8.9	7.4	7.4	0.61	0.39	0.94	43.8	23.9	29.6
1008-2	AFT	151	1.0	10	35.0	43	6.1	32.0	1.6	0.61	0.32	42.9	24.0	32.5
1009-1	FWD	154	0.5	2.0	6.0	8.7	6.2	9.7	0.65	0.65	0.71	29.2	22.7	27.6
1009-2	AFT	155	0.5	2.0	35.0	7.2	6.5	7.5	0.63	0.65	0.59	33.6	23.9	27.2
1010-1	FWD	152	85	23	2.0	88	8.7	95	0.93	0.30	0.87	39.1	23.6	30.8
1010-2	AFT	153	85	20	35.0	6.0	8.0	92	0.62	0.59	0.70	1.21	45.4	23.6
1011-1	FWD	160	90	6.4	35.0	7.5	6.0	85	8.7	96	0.77	0.39	0.97	43.1
1012-1	AFT	156	92	7.7	—	91	8.7	94	0.64	0.65	0.51	—	47.1	33.2
1012-2	FWD	157	85	6.9	—	80	8.7	80	8.9	100	0.97	0.77	0.51	45.2
1013-1	FWD	158	0.5	6.9	—	80	9.5	85	9.8	91	0.64	0.32	1.34	36.9
1014-1	AFT	159	0.5	6.9	—	80	9.5	80	8.1	103	0.64	0.32	1.34	36.9
1015-1	FWD	162	80	87	—	80	8.0	78	7.4	86	0.62	0.41	1.46	35.0
1015-2	AFT	141	85	83	—	—	80	80	95	107	0.62	0.41	1.44	34.8
1014-2	FWD	139	80	83	—	—	80	75	80	77	1.06	0.55	—	36.4
1016-1	FWD	132	85	6.5	—	—	80	84	86	88	1.06	0.59	—	36.1
1016-2	AFT	133	85	6.2	—	—	80	73	80	72	0.50	0.61	0.64	36.3
1017-1	FWD	140	85	7.2	—	—	80	70	79	86	0.72	0.83	2.01	48.9
1017-2	AFT	165	85	85	—	—	80	65	69	66	0.76	0.76	2.49	35.5
1018-1	FWD	126	85	7.0	—	—	80	75	80	86	0.69	0.69	0.45	36.3
1018-2	AFT	123	85	84	—	—	80	75	77	81	0.91	0.49	—	36.7

PERFORMANCE SUMMARY

~~TOP SECRET C~~

NO.

MISSION NO.	CARRIER	SPEED (KNOTS)	WIND (KNOTS)	COURSE (DEG.)	YAW (DEG.)	ROLL (DEG.)	PITCH (DEG.)	0.0% EXECUTION LIMIT (FEET)		0.0% ATTITUDE RATE (DEG/YAW)	0.0% V/H ERROR (%)	0.0% ALONG TRACK
								ROLL	PITCH			
								ROLL	PITCH			
1020-1	FWD	110	0	05	00	-	-	60	76	0.42	0.97	9.1
	AFT	110	0	05	00	-	-	63	87	0.44	0.96	6.5
1020-1	FWD	136	0	00	04	-	-	63	78	0.46	0.75	8.4
	AFT	136	0	00	04	-	-	80	94	0.46	0.73	5.9
1020-2	FWD	137	-	01	02	-	-	80	105	0.46	0.75	7.6
	AFT	137	-	01	02	-	-	-	-	0.41	0.66	2.8
1021-1	FWD	166	0	05	03	-	-	77	06	0.53	0.37	8.0
	AFT	167	0	05	03	-	-	80	23	0.55	0.59	5.5
1021-2	FWD	167	0	05	03	-	-	74	80	0.59	0.65	8.0
	AFT	167	0	05	03	-	-	74	83	0.59	0.61	5.5
1022-1	FWD	169	0	05	03	-	-	66	78	0.47	0.51	8.6
	AFT	169	0	05	03	-	-	80	101	0.47	0.51	6.1
1022-2	FWD	169	0	05	03	-	-	63	84	0.40	0.51	8.4
	AFT	169	0	05	03	-	-	74	99	0.40	0.50	5.9
1023-1	FWD	170	0	05	03	-	-	94	97	0.49	0.33	8.6
	AFT	170	0	05	03	-	-	80	83	0.49	0.33	6.4
1023-2	FWD	171	0	05	03	-	-	77	97	0.42	0.36	4.3
	AFT	171	0	05	03	-	-	76	76	0.43	0.37	3.9
1024-1	FWD	172	0	05	03	-	-	79	90	0.42	0.25	4.2
	AFT	172	0	05	03	-	-	80	95	0.42	0.25	4.7
1024-2	FWD	173	0	05	03	-	-	95	96	0.52	0.44	5.4
	AFT	173	0	05	03	-	-	95	100	0.36	0.31	3.6
1025-1	FWD	142	0	05	03	-	-	87	60	0.50	0.41	2.7
	AFT	142	0	05	03	-	-	80	97	0.51	0.42	4.2
1025-2	FWD	127	0	05	03	-	-	80	85	0.42	0.42	3.9
	AFT	127	0	05	03	-	-	91	96	0.52	0.44	4.7
1026-1	FWD	174	0	05	03	-	-	76	89	0.65	0.24	3.6
	AFT	174	0	05	03	-	-	80	98	0.13	0.65	2.5
1026-2	FWD	175	0	05	03	-	-	88	80	0.55	0.56	2.5
	AFT	175	0	05	03	-	-	85	92	0.59	0.65	2.4
1027-1	FWD	164	0	05	03	-	-	93	90	0.59	0.37	2.5
	AFT	164	0	05	03	-	-	80	80	0.51	0.37	2.5
1028-1	FWD	176	0	05	03	-	-	81	99	0.52	0.37	2.0
	AFT	176	0	05	03	-	-	80	92	0.52	0.37	2.0
1028-2	FWD	177	0	05	03	-	-	80	87	0.76	0.76	2.0
	AFT	177	0	05	03	-	-	77	84	0.76	0.52	2.0
1029-1	FWD	176	0	05	03	-	-	91	91	0.67	0.34	2.0
	AFT	176	0	05	03	-	-	80	73	0.68	0.33	2.0
1029-2	FWD	179	0	05	03	-	-	91	92	0.64	0.48	2.0
	AFT	179	0	05	03	-	-	91	94	0.65	0.48	2.0
1030-1	FWD	132	0	05	03	-	-	95	76	0.66	0.25	2.0
	AFT	132	0	05	03	-	-	74	79	0.77	0.25	2.0
1030-2	FWD	163	0	05	03	-	-	80	81	0.70	0.27	2.0
	AFT	163	0	05	03	-	-	77	74	0.70	0.26	2.0
1031-1	FWD	164	0	05	03	-	-	65	96	0.60	0.47	2.0
	AFT	164	0	05	03	-	-	91	80	0.61	0.41	2.0
1031-2	FWD	185	0	05	03	-	-	80	71	0.66	0.57	2.0
	AFT	185	0	05	03	-	-	91	94	0.60	0.75	2.0
1033-1	FWD	164	0	05	03	-	-	94	87	0.11	0.33	2.0
	AFT	164	0	05	03	-	-	80	93	0.15	0.27	2.0
1033-2	FWD	195	0	05	03	-	-	75	91	0.21	0.24	2.0
	AFT	195	0	05	03	-	-	93	73	0.20	0.24	2.0

PERFORMANCE SUMMARY

~~TOP SECRET C~~

NO.

MISSION NUMBER	CAMERA	SERIAL NUMBER	M.I.P. VALUE	AIS/PFF MTF/AM		90% ATTITUDE ERROR (°)			90% ATTITUDE RATES (°/HR)			90% V/H. ERROR (m)		90% RESOLUTION LIMIT (FEET)	I.M.C. ERROR	
				AVERAGE SLIT (μ)	AVERAGE SLIT (μ)	PITCH	ROLL	YAW	PITCH	ROLL	YAW	ALONG TRACK	CROSS TRACK			
1034-1	FWD	185	00	75	Cl	0.20	0.19	0.29	19.3	20.4	24.9	15.0	17.8	5.9		
	AFT			23	90	0.20	0.19	0.29	19.3	20.4	24.9	15.2	13.6	4.5		
	FWD	187	80	74	80	0.34	0.36	0.34	21.1	28.9	16.2	8.7	10.4	7.1		
	AFT			69	86	0.34	0.36	0.33	21.1	29.0	16.2	8.9	8.0	5.3		
1035-1	FWD	189	85	66		0.16	0.54	2.39	18.9	27.9	33.9	4.0	4.8	3.7	4.0	
	AFT			70	82	0.17	0.54	2.43	19.3	23.4	32.4	4.1	3.7	2.4	4.1	
	FWD	193	75	61	—	0.16	0.50	3.02	18.4	30.1	27.5	5.2	4.0	3.5	3.2	
	AFT			67	72	0.17	0.51	3.02	19.2	24.7	26.3	3.4	3.3	2.4	3.4	
1036-1	FWD	190	85	50	—	0.76	0.56	0.60	31.2	26.6	29.5	3.4	5.1	6.8		
	AFT			54	80	0.76	0.56	0.60	31.1	25.5	29.4	3.3	5.6	5.1		
	FWD	191	75	62	—	0.94	0.70	0.40	35.0	29.7	23.3	3.3	3.6	6.5		
	AFT			65	74	0.94	0.70	0.40	32.9	21.7	23.3	3.1	2.7	4.9		
1037-1	FWD	192	85	75	80	—	0.24	0.25	1.50	21.3	40.0	29.3	9.5	10.1	8.0	9.6
	AFT			81	84	—	0.25	0.25	1.51	28.7	30.9	32.4	10.1	8.0	6.1	10.3
	FWD	193	85	71	80	—	0.24	0.24	1.50	29.5	32.5	26.2	6.3	6.6	7.5	6.5
	AFT			82	84	—	0.27	0.27	1.17	33.8	36.6	53.4	6.6	5.4	5.6	7.0
1038-1	FWD	192	80	70	80	—	0.22	0.25	2.98	18.7	33.7	39.9	3.6	4.1	3.7	3.5
	AFT			76	80	—	0.27	0.24	2.99	41.8	27.2	34.4	3.4	3.3	2.5	3.7
	FWD	23	80	63	—	0.59	0.51	2.87	20.0	46.7	27.8	3.4	3.6	3.8	3.1	
	AFT			77	—	0.39	0.51	2.90	50.4	28.3	27.3	3.4	3.6	2.4	3.9	
1039-1	FWD	206	50	50	—	0.21	0.43	3.03	19.0	27.8	39.2	5.1	6.2	4.6	5.2	
	AFT			55	71	—	0.20	0.41	3.05	37.5	23.0	28.5	5.2	4.8	3.2	5.2
	FWD	207	85	65	80	—	0.30	0.54	2.50	33.1	30.2	25.0	4.6	5.5	5.4	4.7
	AFT			85	65	—	0.34	0.53	2.52	27.1	24.2	23.9	4.8	4.6	3.8	5.0
1040-1	FWD	196	85	94	80	—	0.33	0.56	2.99	26.0	22.2	28.4	2.6	3.9	2.1	2.8
	AFT			60	80	—	0.30	0.56	3.00	22.1	23.2	28.5	2.1	1.9	2.5	2.1
	FWD	197	85	75	—	0.32	0.49	2.96	27.5	30.0	32.7	1.6	2.2	2.0	1.7	
	AFT			85	—	0.29	0.46	2.96	27.2	26.4	28.7	2.7	2.5	2.2	2.6	
1041-1	FWD	208	85	72	80	—	0.34	0.16	3.05	14.7	14.0	12.7	5.1	6.4	3.4	5.2
	AFT			82	85	—	0.35	0.16	3.05	15.8	13.5	13.0	5.9	5.7	3.0	5.7
	FWD	209	85	73	80	—	0.26	0.23	2.94	22.9	15.7	10.8	4.9	6.4	2.1	4.9
	AFT			78	—	0.28	0.24	3.01	23.9	16.2	21.0	5.6	5.5	2.0	5.5	
1042-1	FWD	204	85	79	80	—	0.31	0.22	2.86	22.1	26.3	27.0	3.1	3.3	1.5	3.1
	AFT			85	80	—	0.32	0.24	2.83	23.4	33.0	25.9	3.2	2.7	1.1	3.4
	FWD	205	95	70	80	—	0.31	0.38	2.39	16.1	46.1	31.4	2.1	2.5	2.2	2.3
	AFT			74	—	0.32	0.37	2.31	19.9	33.6	25.6	2.6	2.3	1.3	2.0	
1043-1	FWD	200	85	67	80	—	0.28	0.23	3.11	23.9	22.0	41.5	4.2	5.4	1.5	4.2
	AFT			65	85	—	0.31	0.23	3.14	25.4	20.5	34.9	3.3	2.8	0.8	3.3
	FWD	201	85	75	—	0.30	0.34	2.73	29.2	31.6	47.9	4.3	5.3	2.2	4.4	
	AFT			—	0.34	0.34	2.78	27.3	29.9	45.1	3.1	2.8	0.9	3.2		

EXPOSURE - PROCESSING SUMMARY

MISSION NUMBER	CAMERA	SOLAR ELEVATION (°)	PREDICTED PROCESSING (%)	REPORTED PROCESSING (%)	COMPUTED PROCESSING (%)	RANGE	TERRAIN D-MIN	TERRAIN D-MAX	SLCING RANGE	D-MAX	UNDER EXPOSED (%)	OVER EXPRESSED (%)	CLOUD COVER (%)
		LONGITUDE (°)	HEIGHT (ft.)	P	I	F	LOW	HIGH	MEAN	LOW	HIGH	MEAN	LOW
1015-1	FWD	24	70	2.4	152	0	21	79	22	32	46	4	56
	AFT	23	70	2.1	152	0	92	8	26	35	19	3	87
1020-1	FWD	30	75	1.9	150	0	19	81	13	48	39	1	58
	AFT	29	75	1.7	156	0	64	36	15	56	29	0	74
1020-2	FWD	47	69	1.0	35	-	-	-	-	-	-	-	-
	AFT	46	69	1.7	33	-	-	-	-	-	-	-	-
1021-1	FWD	15	65	-146	-23	6	60	32	14	39	47	-1	32
	AFT	14	65	-147	-25	9	52	19	11	37	47	0	57
1021-2	FWD	13	52	-133	-41	0	29	71	13	41	46	0	57
	AFT	13	52	-133	-41	0	100	0	53	25	22	0	50
1022-1	FWD	28	67	30	150	0	36	64	8	36	56	0	42
	AFT	27	67	26	150	0	69	11	7	42	51	0	53
1022-2	FWD	28	74	19	152	0	100	0	10	44	46	0	53
	AFT	28	74	19	152	0	0	0	53	47	0	21	11
1023-1	FWD	9	61	22	82	0	164	0	5	95	19	27	0
	AFT	20	81	5	163	0	116	0	11	63	39	61	0
1023-2	FWD	29	81	-13	177	0	177	0	7	93	19	81	0
	AFT	26	80	-13	178	0	3	37	17	92	22	18	0
1024-1	FWD	10	61	24	37	0	0	0	0	57	43	0	28
	AFT	9	61	21	136	0	0	0	0	28	72	0	82
1024-2	FWD	9	79	11	151	0	3	00	12	19	69	0	25
	AFT	8	79	9	151	0	0	0	1	22	77	0	66
1025-1	FWD	-1	70	-123	-18	0	63	32	10	41	42	0	43
	AFT	0	70	-121	-19	0	72	24	8	49	43	0	56
1025-2	FWD	0	56	-124	-31	0	71	29	3	42	53	0	56
	AFT	0	56	-122	-33	0	73	27	3	45	52	0	51
1026-1	FWD	0	57	23	135	0	4	56	0	21	79	0	24
	AFT	0	57	21	135	0	5	35	0	6	96	0	36
1026-2	FWD	0	72	8	84	0	0	100	0	0	59	0	94
	AFT	0	57	13	78	0	0	100	0	2	53	0	93
1027-1	FWD	3	63	26	110	0	0	0	0	0	0	0	0
	AFT	2	63	23	108	0	0	0	0	0	0	0	0
1026-3	FWD	3	73	16	135	0	4	96	0	16	92	0	75
	AFT	2	73	14	133	0	5	54	0	16	84	0	77
1026-2	FWD	2	81	5	48	0	3	97	-1	9	90	0	81
	AFT	1	60	5	43	0	10	99	0	6	94	0	90
1029-1	FWD	3	63	18	120	0	8	92	16	84	92	0	83
	AFT	2	62	16	120	0	1	96	0	20	80	0	82
1029-2	FWD	0	80	4	146	0	4	96	0	16	92	0	82
	AFT	0	69	3	145	0	10	99	0	11	90	0	83
1030-1	FWD	5	63	27	130	0	53	92	16	94	97	0	94
	AFT	4	62	22	129	0	53	47	0	16	94	0	94
1030-2	FWD	3	76	10	153	0	-1	92	16	94	97	0	94
	AFT	2	78	7	157	1	-1	23	76	0	23	0	94
1031-1	FWD	17	70	20	140	0	18	91	1	18	94	0	95
	AFT	17	70	13	140	0	14	66	16	43	42	0	45
1031-2	FWD	19	62	6	67	0	99	1	18	34	46	0	55
	AFT	0	54	34	131	0	86	14	6	14	43	0	55
1033-1	FWD	10	47	46	135	0	85	11	0	3	97	0	45
	AFT	11	47	45	135	0	10	90	3	4	99	0	45
1033-2	FWD	0	54	34	131	0	84	16	0	3	99	0	45
	AFT	0	54	34	131	0	86	14	6	14	43	0	45

TOP SECTION C

INSUFFICIENT DATA

~~TOP SECRET~~

C

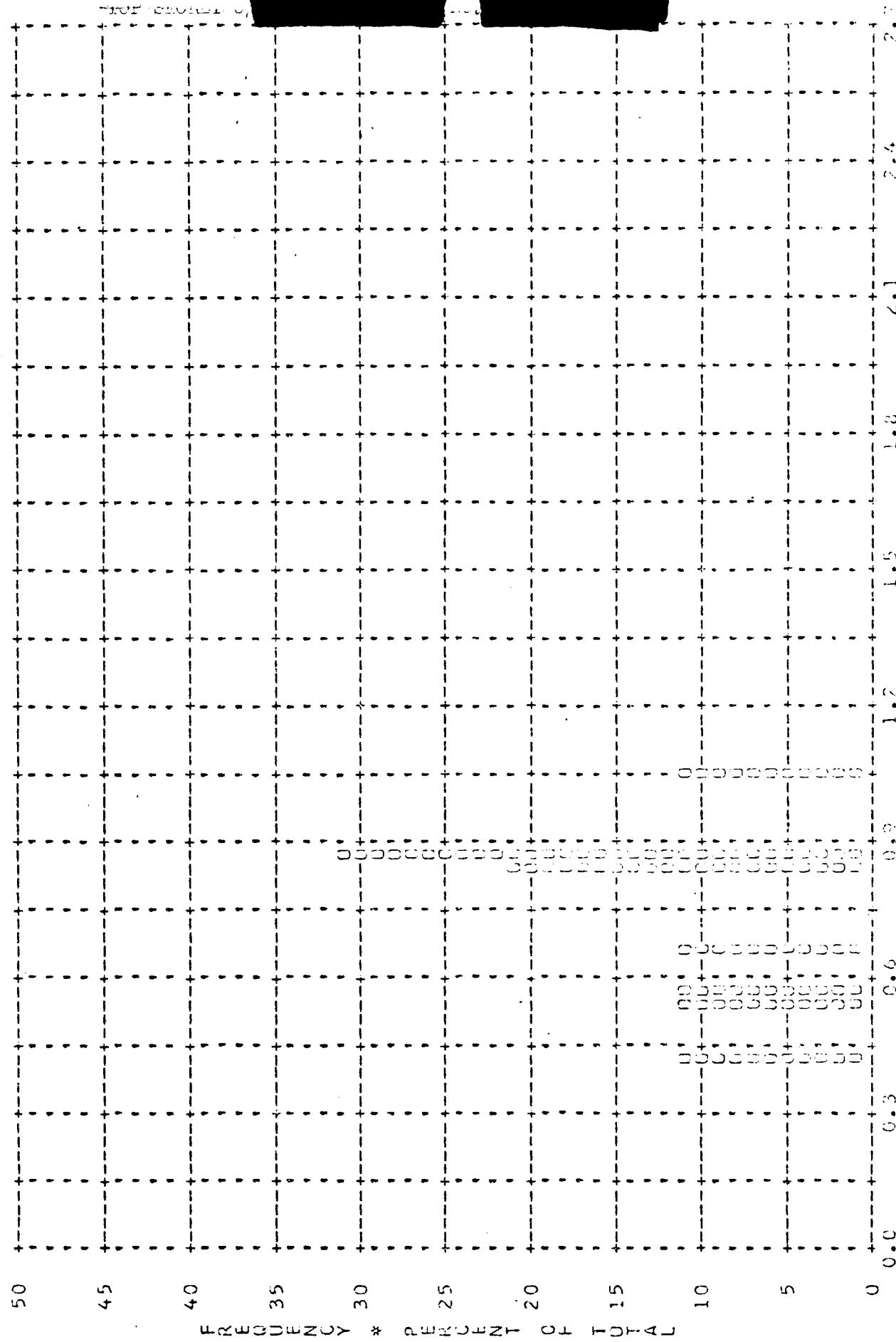
CO

SECTION A

APPENDIX

-TOP SECRET C

MISSION # 1043-1 * INSTR # FWD * 1/9/68 PLOT OF D MIN & TERRAIN * PROCESSING * PRIMACY
WITH MEAN # 0.74 * MEDIAN # 0.83 * STD DEV # 0.19 * RANGE # 0.42 TO 1.03 WITH 10 SAMPLES



A-1

FIGURE A-1

-TOP SECRET C

* ELLIPTIC *

-TOP SECRET C

TOP SECRET C

MISSION * 1043-1 * INSTR * FWD * 1/9/68 PLOT OF D MAX * TERRAIN * PROCESSING * PRIMARY
ARITH MEAN * 1.36 * MEDIAN * 1.42 * STD DEV * 0.18 * RANGE * 1.04 TO 1.54 WITH 10 SAMPLES

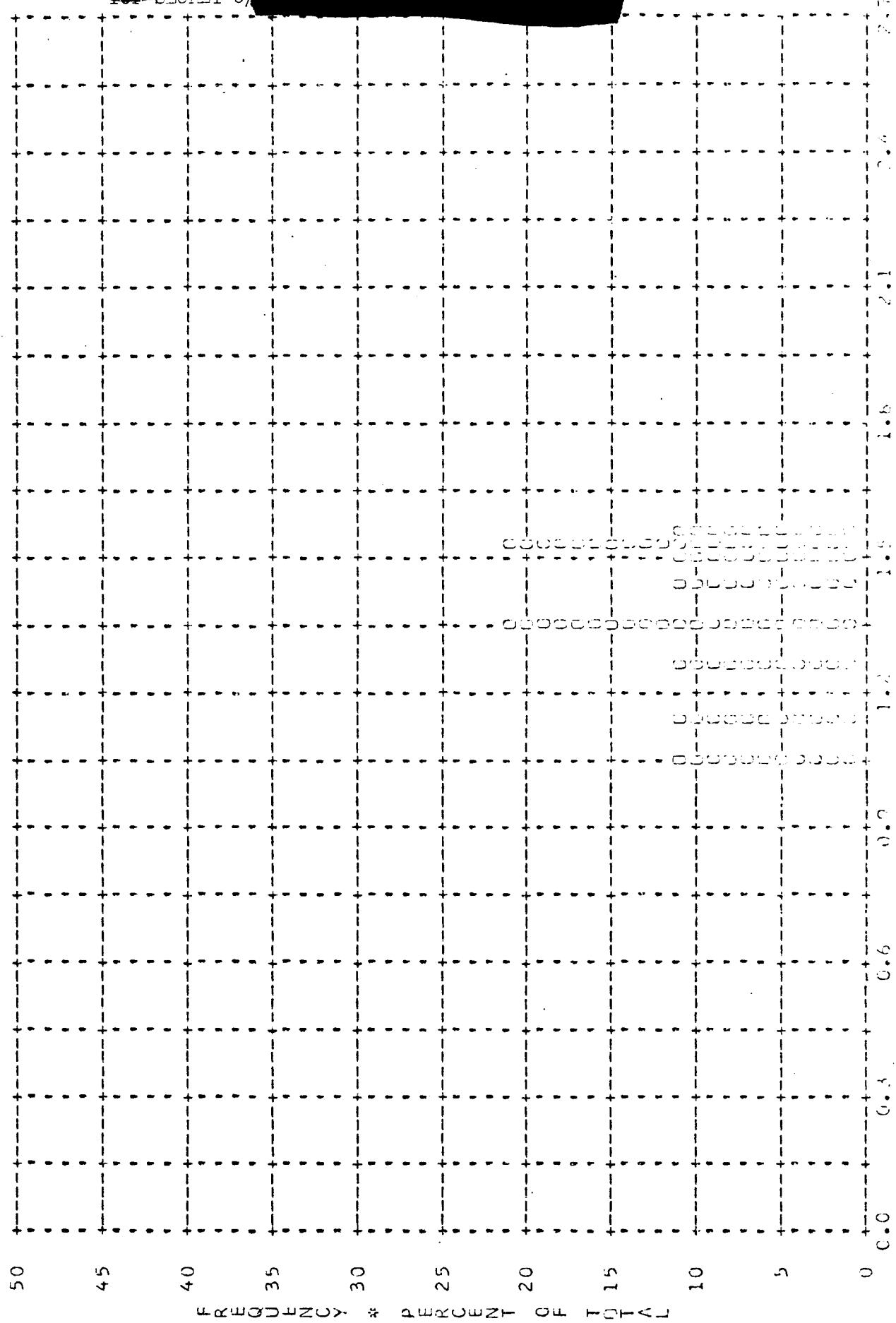


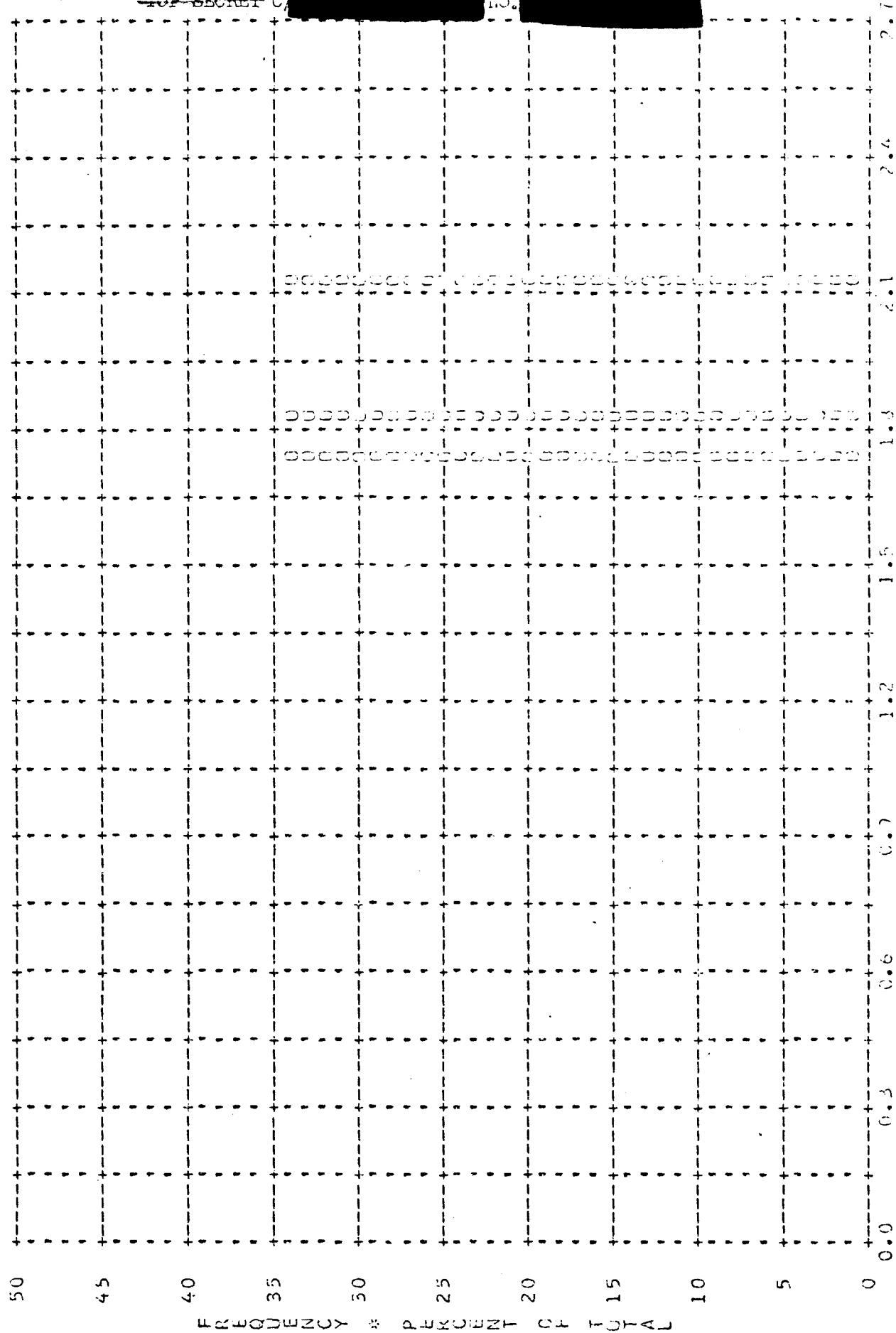
FIGURE A-1

A-2

TOP SECRET C

-TOP-SECRET C

MISSION * 1643-1 * INSTR * FWD * 1/9/68 PLCT OF D MAX * CLOUD * PROCESSING * PRIMARY
ARITH MEAN * 1.69 * MEDIAN * 1.81 * STD DEV * 0.22 * RANGE * 1.72 TO 2.13 WITH 3 SAMPLES



A-3

FIGURE A-1

-TOP-SECRET C

-TOP-SECRET C

-TOP SECRET C/

MISSION * 1043-1 * INSTR * FWD * 1/9/68 PLOT CF D MIN * TERRAIN * PROCESSING * INTERMEDIATE
ARITH MEAN * 0.64 * MEDIAN * 0.57 * STD DEV * 0.29 * RANGE * 0.15 TO 1.63 WITH 66 SAMPLES

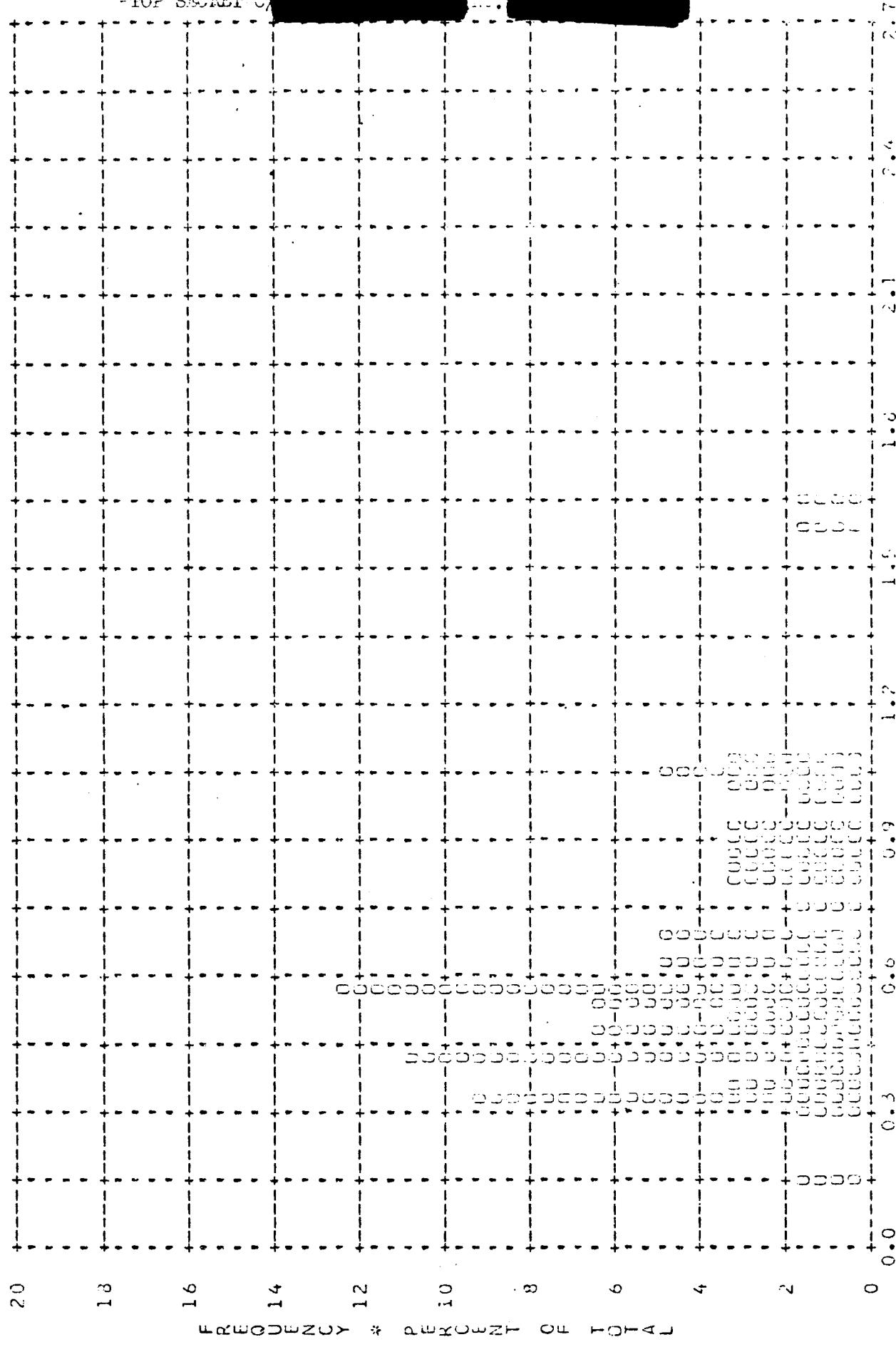


FIGURE A-1

A-4

-TOP SECRET C/

* DENSITY

-TOP SECRET C/

TUP SECRET C

MISSION * 1043-1 * INSTR * FWD * 1/9/68 PLCT OF D MAX * TERRAIN * PROCESSING * INTERMEDIATE
ARITH MEAN * 1.51 * MEDIAN * 1.54 * STD DEV * 0.28 * RANGE * 0.62 TO 2.08 WITH 66 SAMPLES

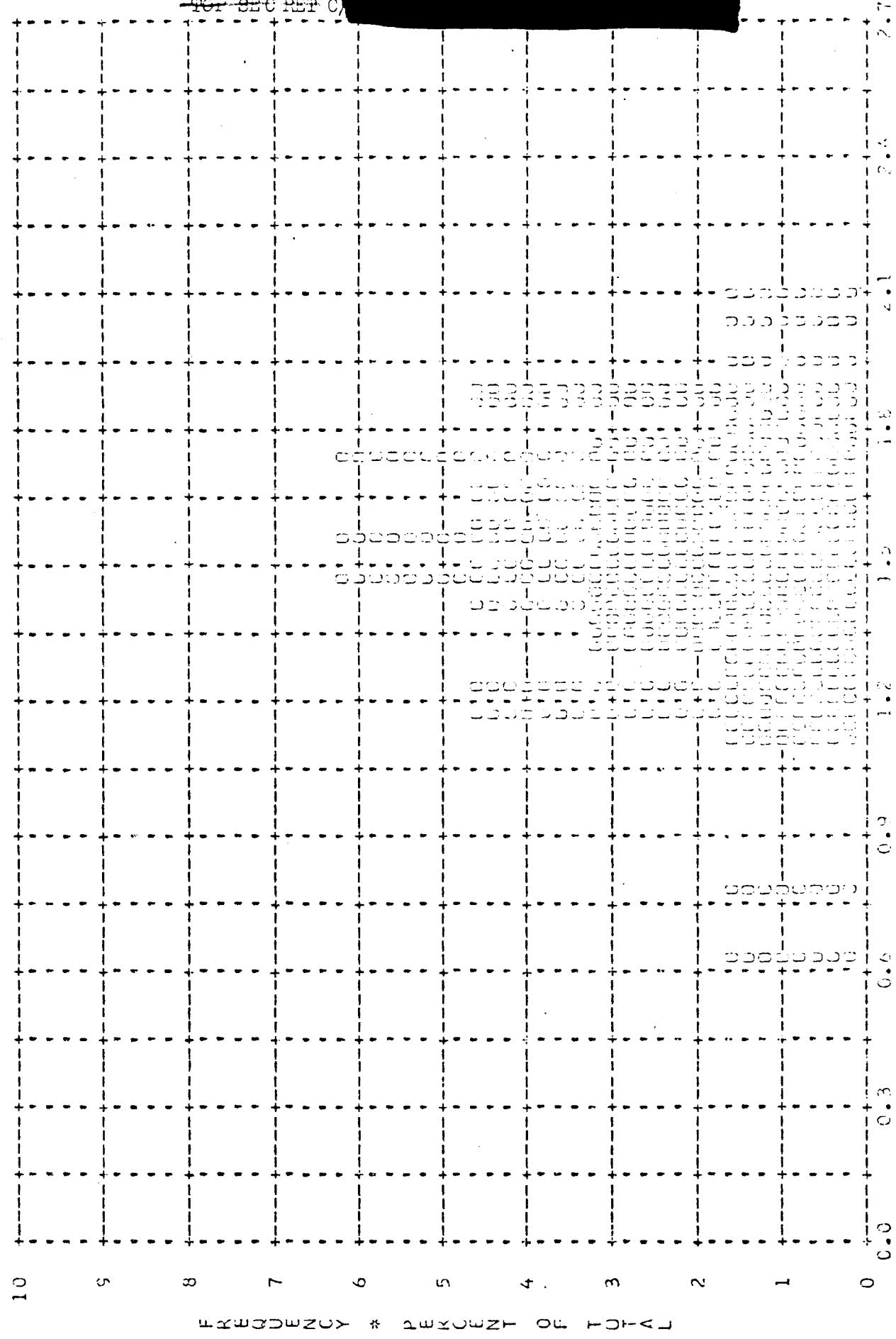


FIGURE A-1

TUP SECRET C

TOP SECRET C

MISSION * 1043-1 * INSTR * FWD * 1/9/68 * PLCT OF D MAX * CLOUD * PROCESSING * INTERMEDIATE
ARITH MEAN * 2.61 * MEDIAN * 2.07 * STD DEV * 0.26 * RANGE * 0.56 TO 2.33 WITH 34 SAMPLES

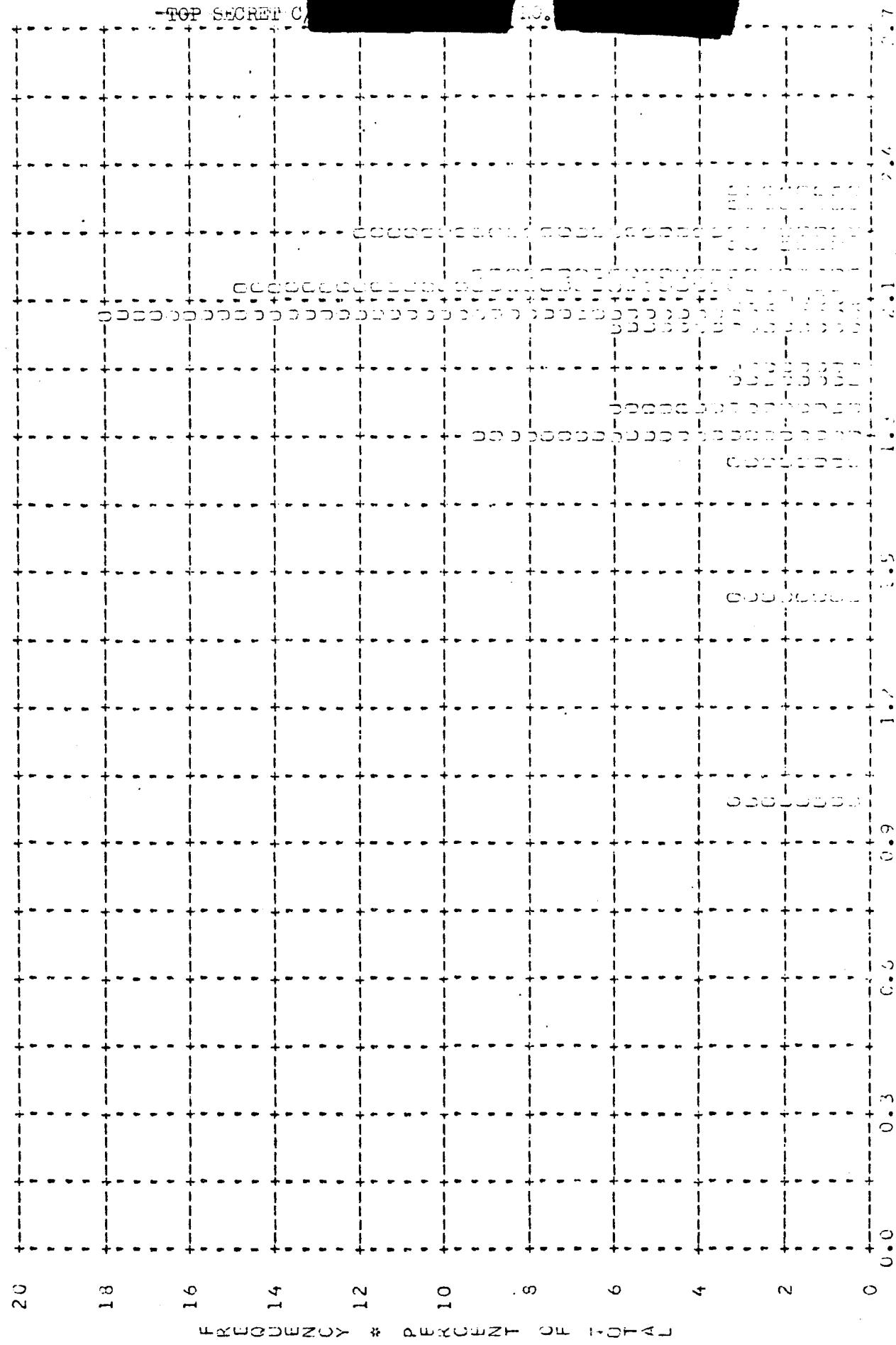


FIGURE A-1

TOP SECRET-C
MISSION * 1043-1 * INSTK * FWD * 1/9/68 PLOT OF D MIN * TERRAIN * PROCESSING * FULL
ARITH MEAN * 0.50 * MEDIAN * 0.46 * STD DEV * 0.19 * RANGE * 0.28 TU 1.47 WITH 175 SAMPLES

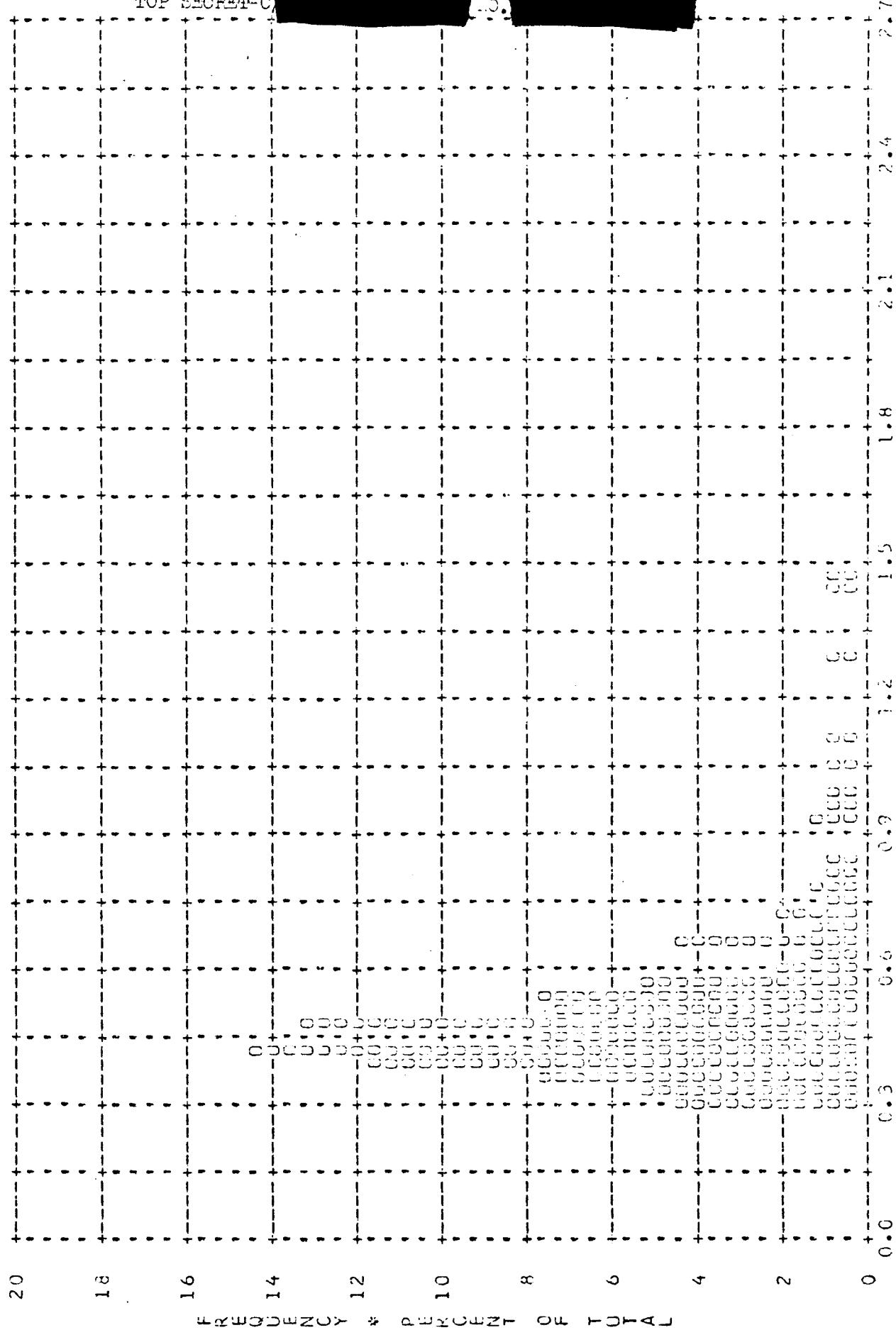


FIGURE A-1

A-7

TOP SECRET-C

TOP SECRET C

MISSION # 1943-1 * INSTR # FID * 1/9/68 PLCT OF D MAX * TERRAIN * PROCESSING * FULL
ARITH MEAN # 1.36 * MEDIAN # 1.35 * STD DEV # 0.33 * RANGE # 0.61 TO 2.25 WITH 175 SAMPLES

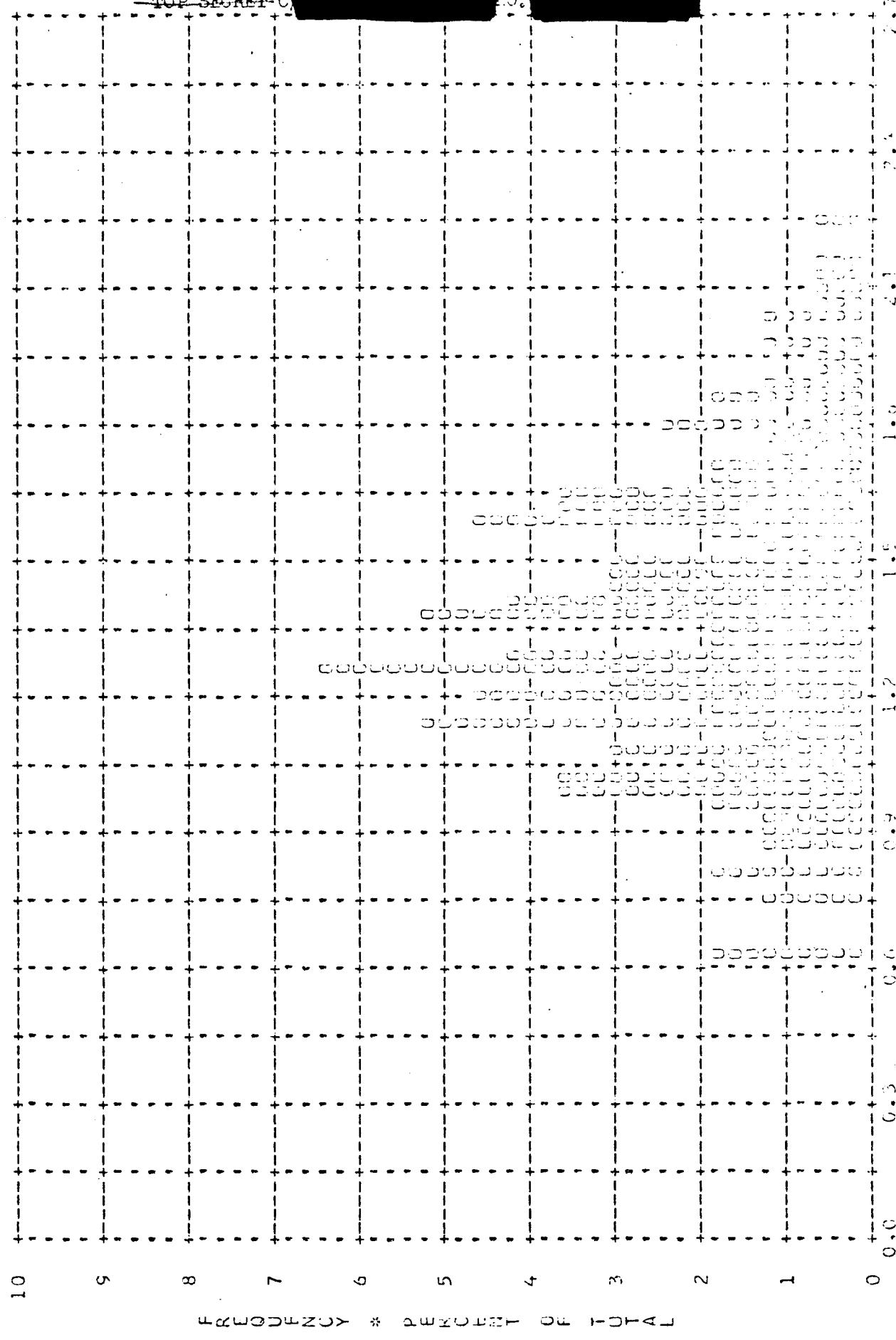


FIGURE A-1

MISSION * 1043-1 * INSTR * FWD * 1/9/68 PLCT OF D MAX * CLOUD * PROCESSING * FULL
ARITH MTAN * 2.15 * MEDIAN * 2.18 * STD DEV * 0.17 * RANGF * 1.30 TU Z.41 WITH 194 SAMPLES

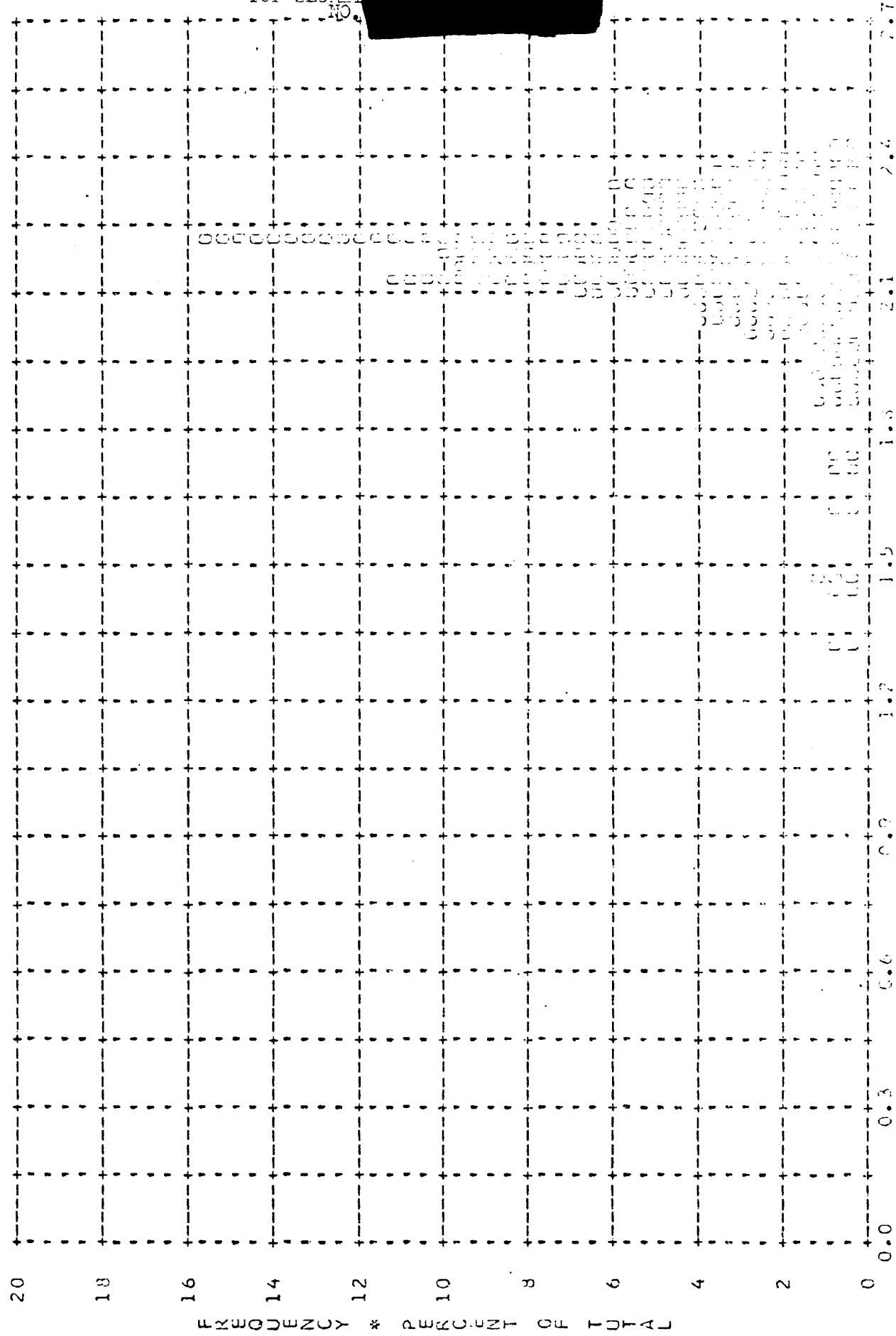


FIGURE A-1

TOP SECRET C/

MISSION * 1043-1 * INSTR * FWD * 1/9/68 PLUT OF D MIN * TERRAIN * PROCESSING * ALL LEVELS
ARITH MEAN * 0.54 * MEDIAN * 0.47 * STD DEV * 0.23 * RANGE * 0.15 To 1.63 WITH 251 SAMPLES

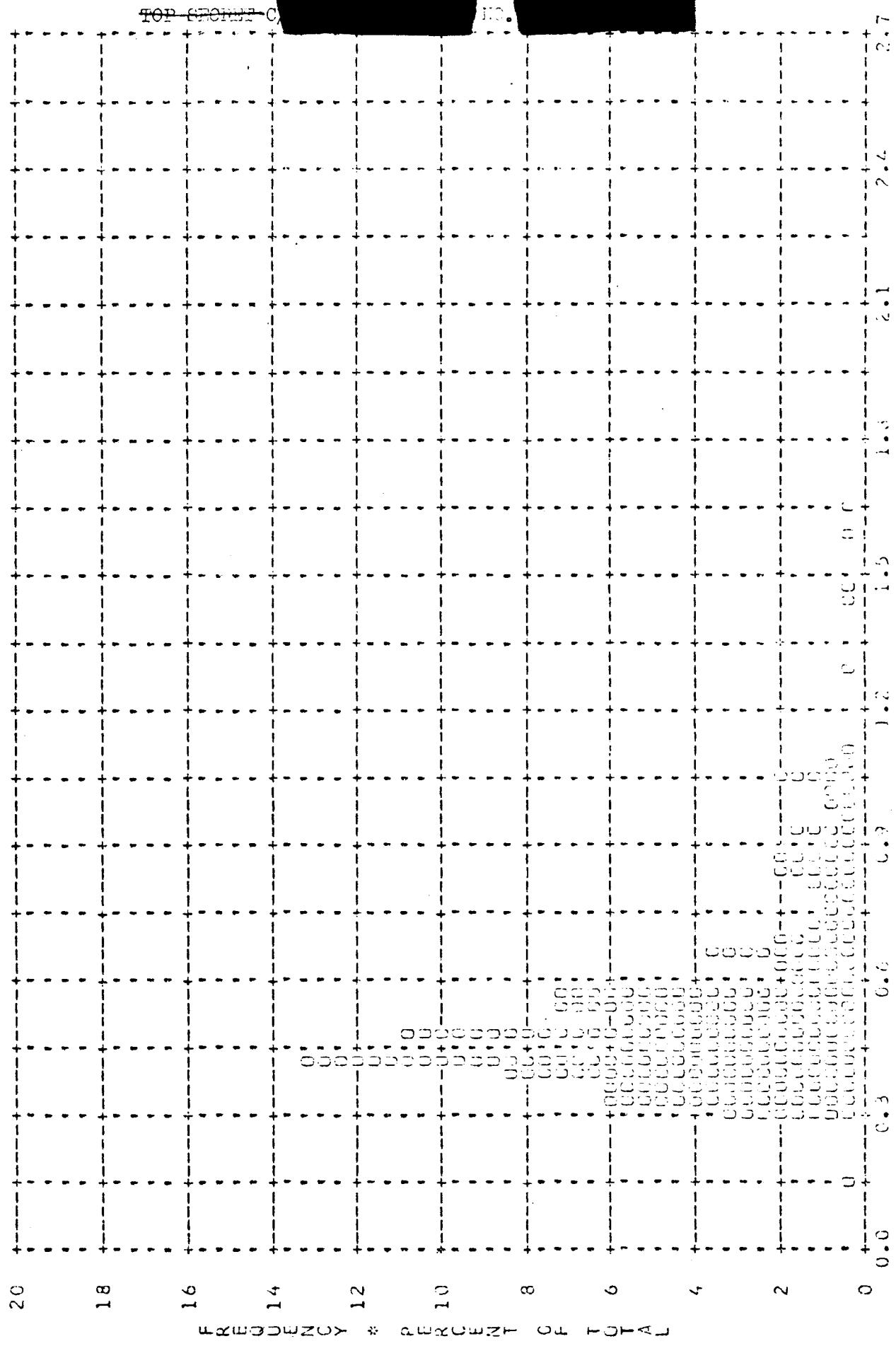


FIGURE A-1

* DENSITY *

-TOP SECRET C

MISSION * 1043-1 * INSTR * FWD * 1/9/68 PLOT GF D MAX * TERRAIN * PROCESSING * ALL LEVELS
ARITH MEAN * 1.40 * MEDIAN * 1.39 * STD DEV * 0.32 * RANGE * 0.61 TO 2.25 WITH 251 SAMPLES

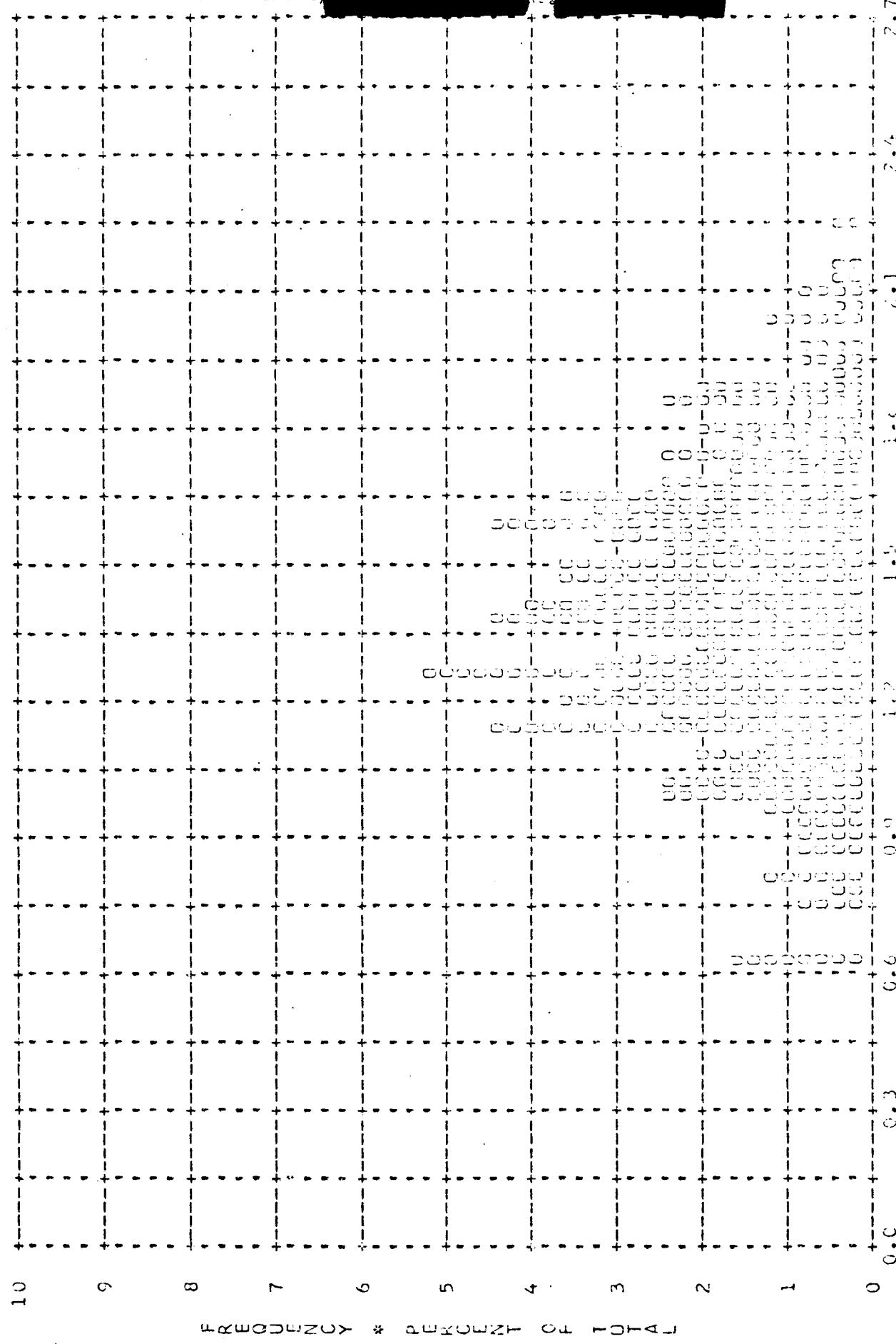


FIGURE A-1

MISSION * 1043-1 * INSIR * FWD * 1/9/68 PLUT OF D MAX * CLOUD * PROCESSING * ALL LF VFLS
ARITH MEAN * 2.13 * MEDIAN * 2.16 * STD DEV * 0.20 * RANGE * 0.98 TO 2.41 WITH 221 SAMPLES

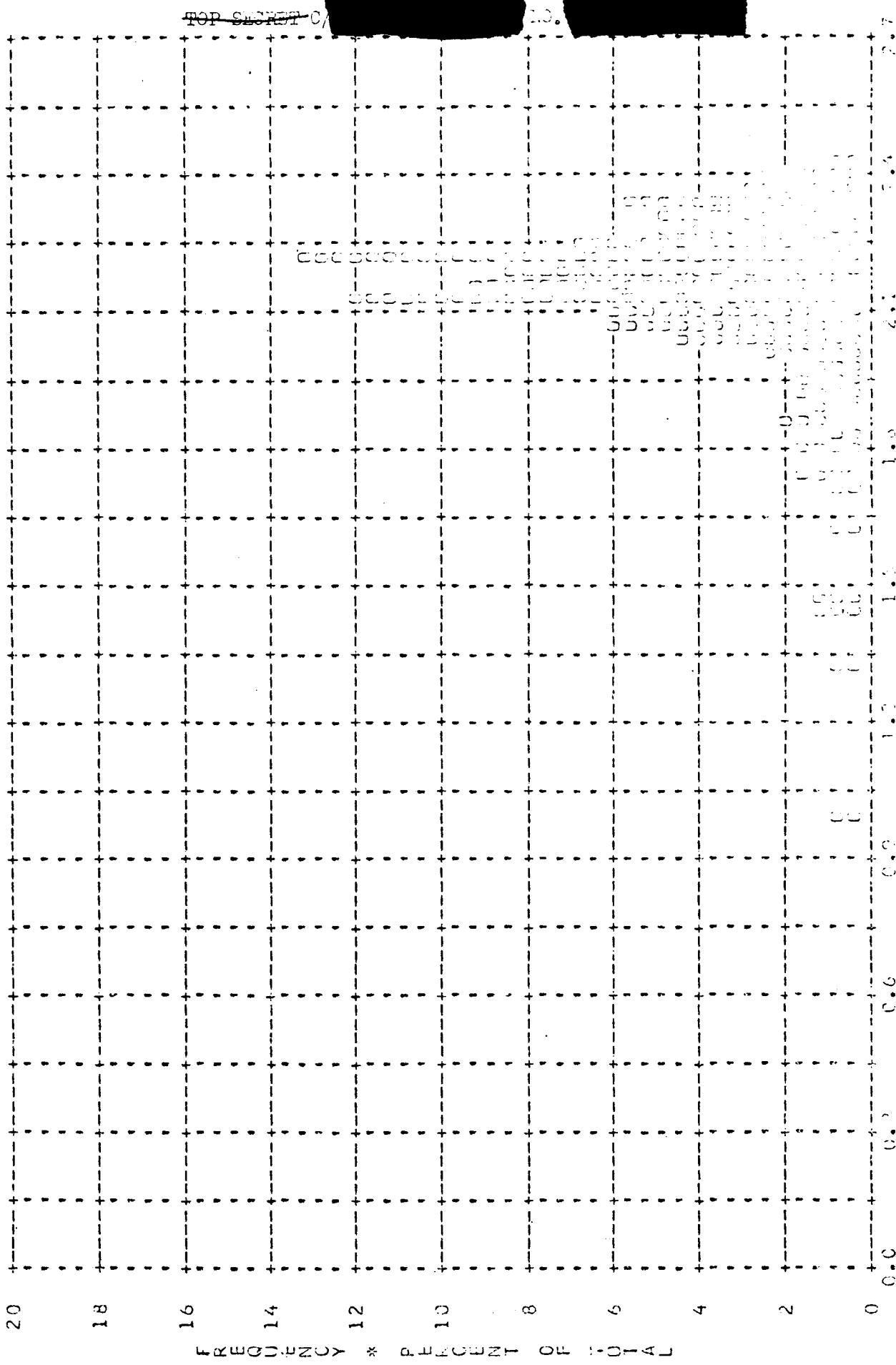


FIGURE A-1

TOP SECRET C

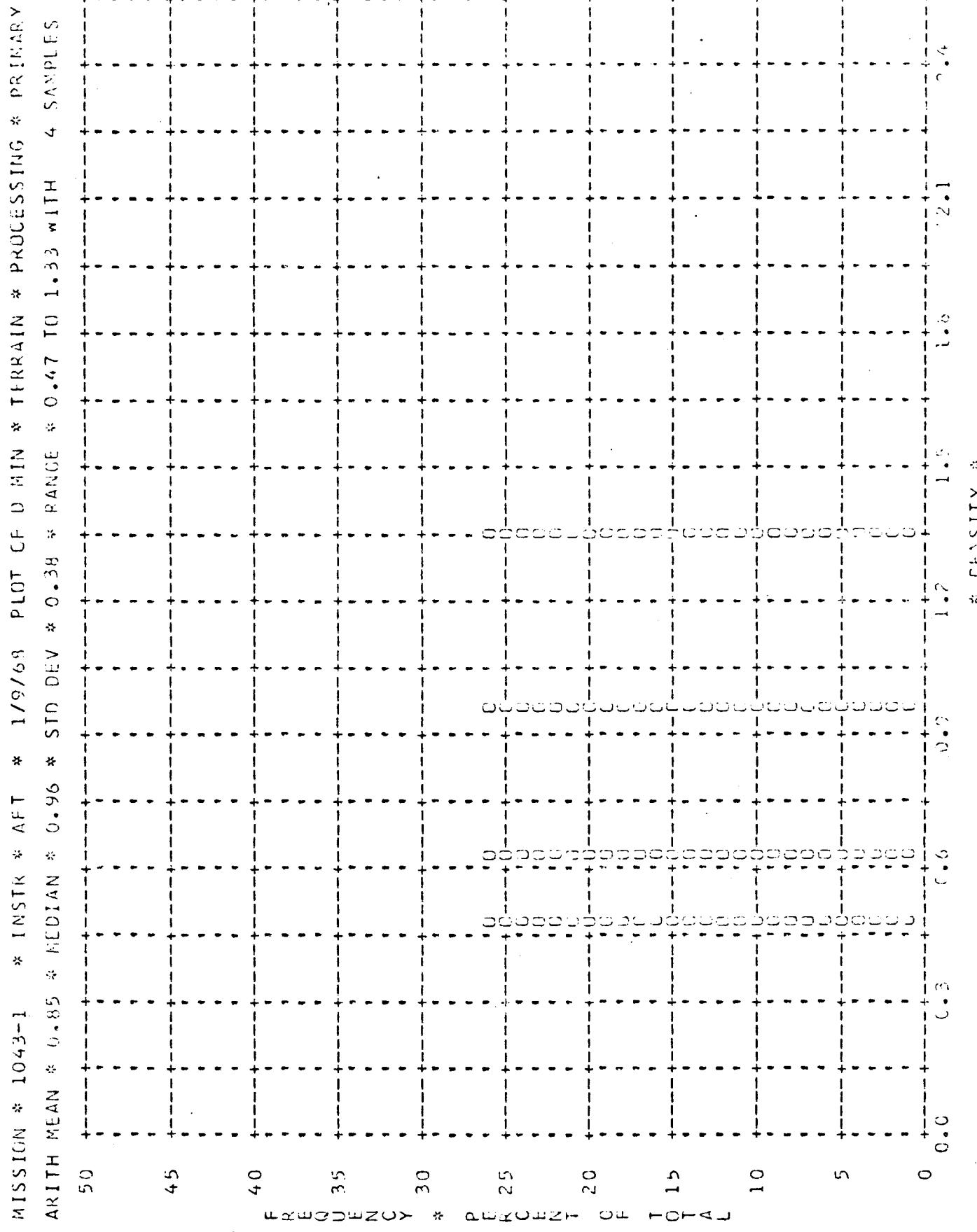


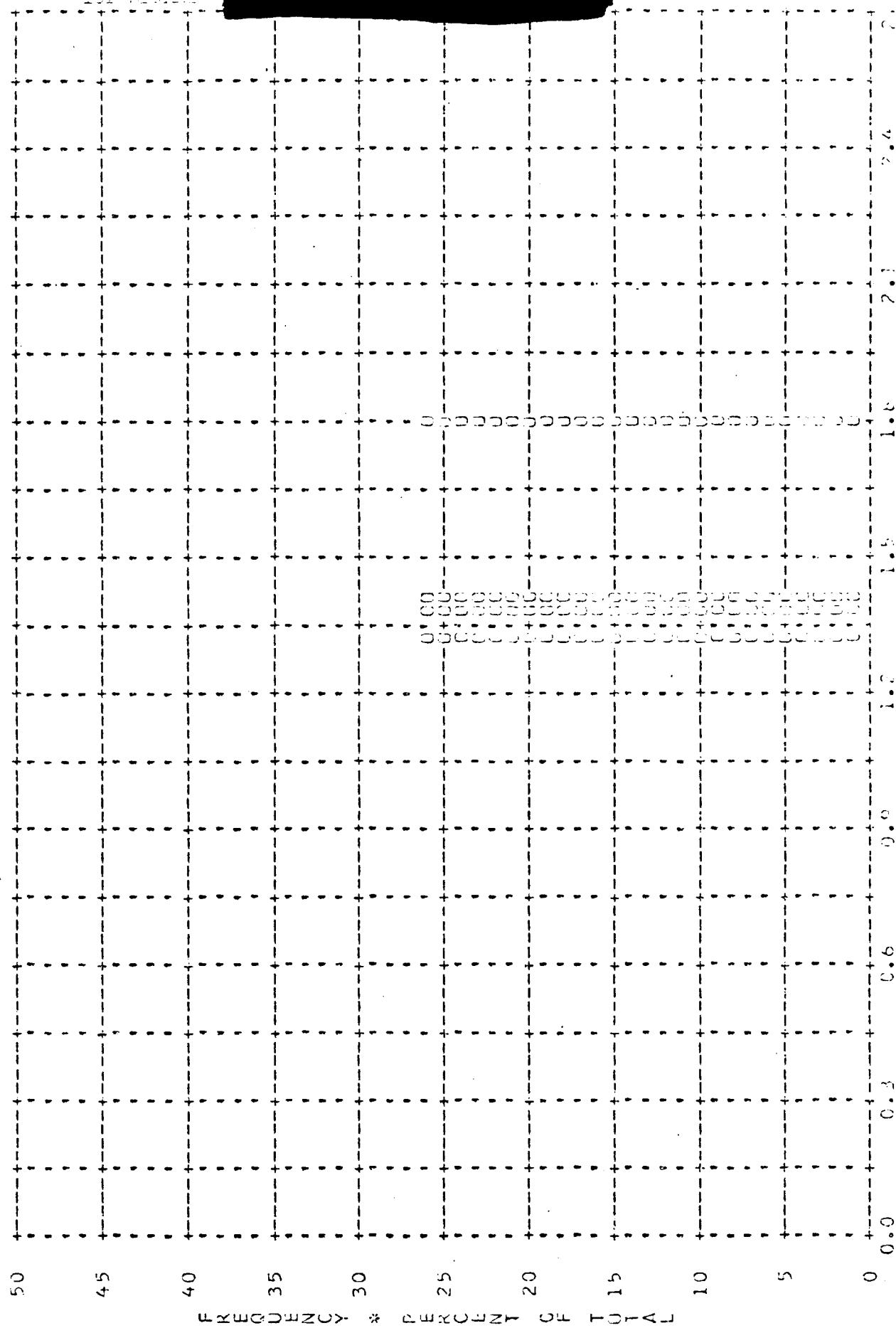
FIGURE A-2

A-13

TOP SECRET C

TOP SECRET C

MISSION * 1043-1 * INSTR * AFT * 1/9/58 PLOT CF D MAX * TERRAIN * PROCESSING * PRIMARY
ARITH MEAN * 1.47 * MEDIAN * 1.41 * STD DEV * 0.22 * RANGE * 1.32 TO 1.79 WITH 4 SAMPLES



A-14

FIGURE A-2

TOP SECRET C

TOP SECRET C

MISSION * 1043-1 * INSTR * AFT * 1/9/68 PLCT CF D MAX * CLOUD * PROCESSING * PRIMARY
ARITH MEAN * 2.23 * MEDIAN * 2.23 * STD DEV * 0.00 * RANGE * 2.23 TO 2.23 WITH 1 SAMPLES

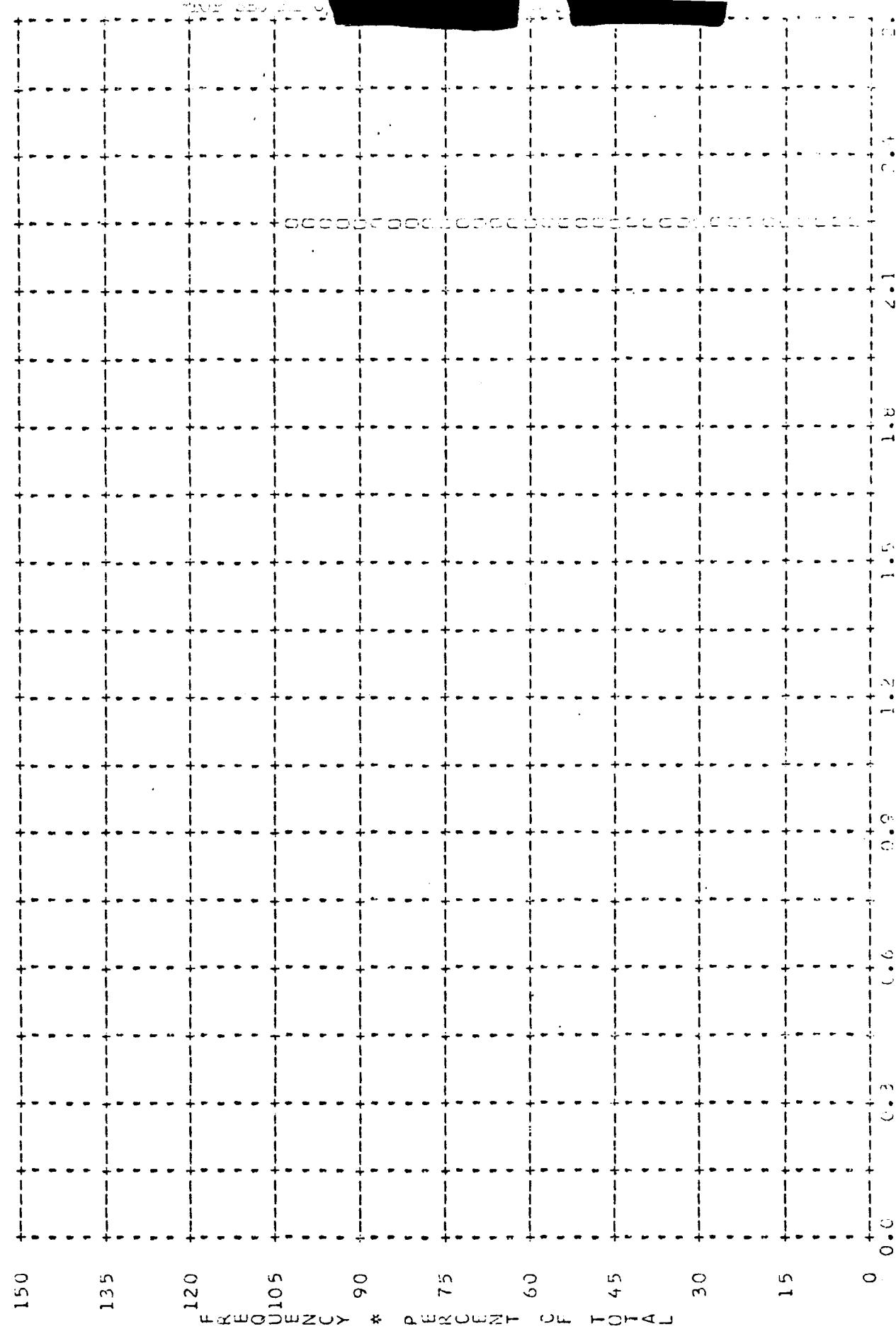
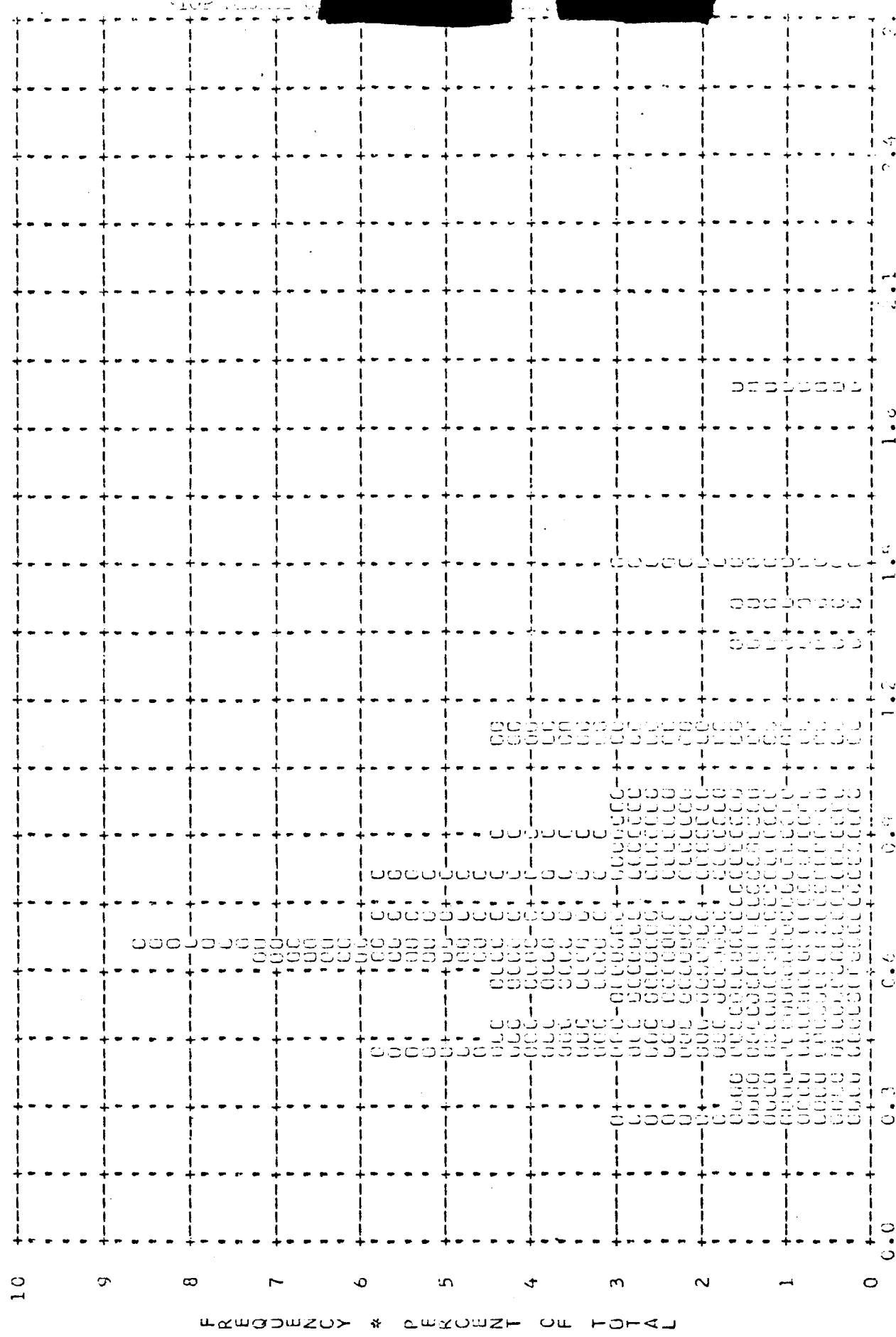


FIGURE A-2

A-15

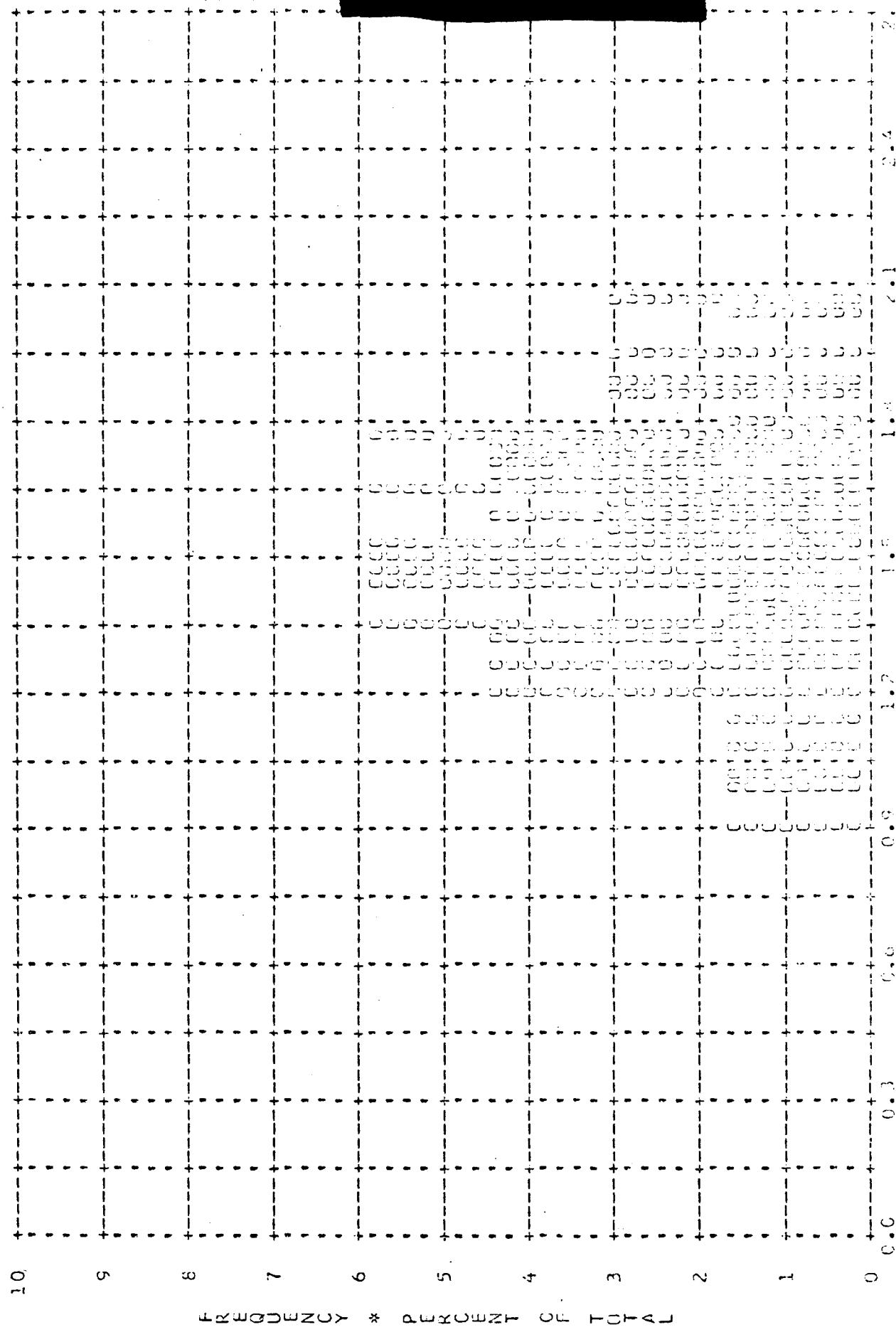
TOP SECRET C

MISSION * 1043-1 * INSTR * AFT * 1/9/68 PLCT OF D MIN * TERRAIN * PROCESSING * INTEGRATED
ARITH MEAN * 0.74 * MEDIAN * 0.67 * STD DEV * 0.31 * RANGE * 0.25 TC 1.69 WITH 71 SAMPLES

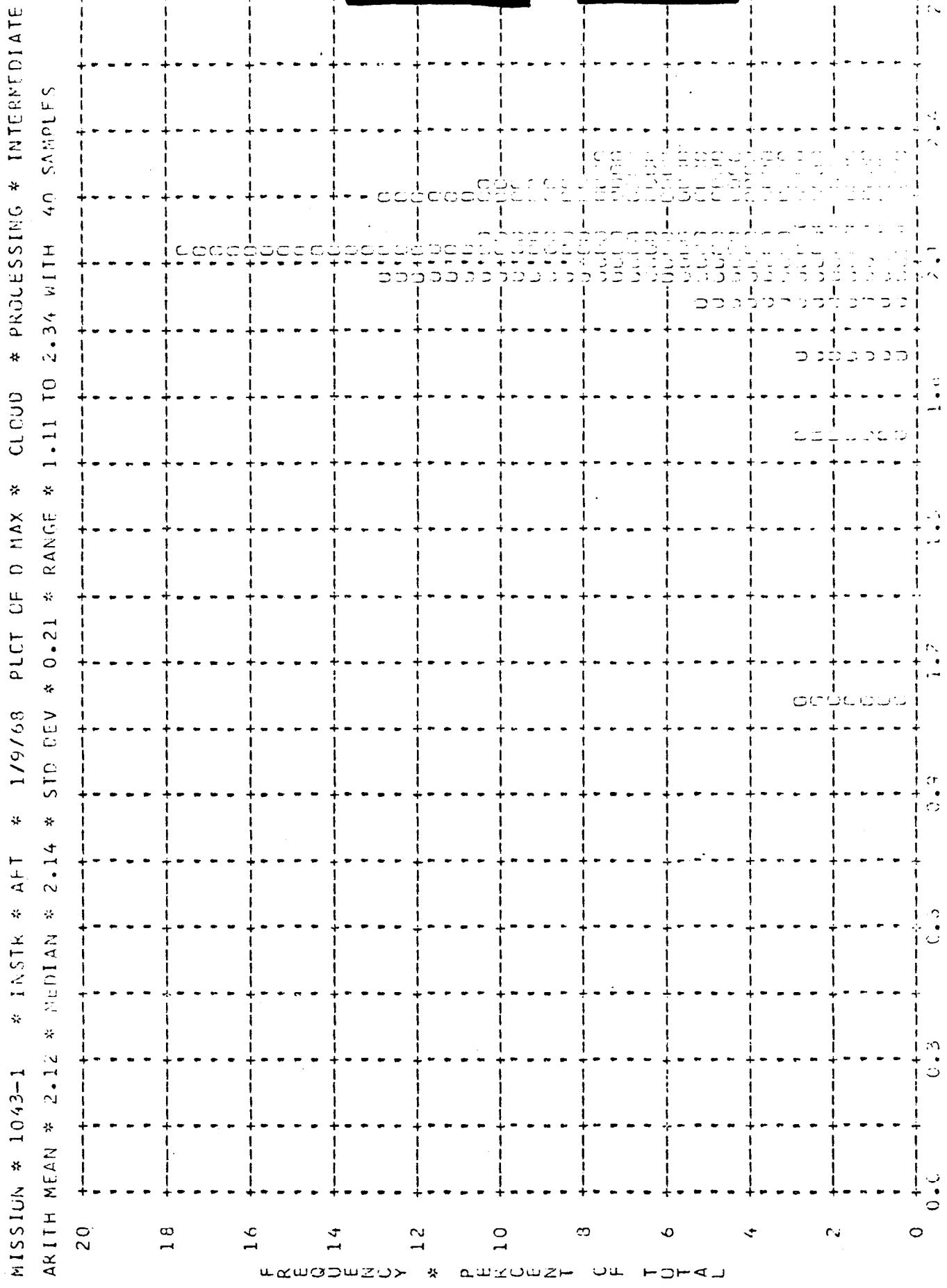


TOP SECRET-C

MISSION # 1043-1 * INSTR # AFT * 1/9/63 PLCT OF D MAX * TERRAIN * PROCESSING * INTERIM
ARITH MEAN # 1.53 * MEDIAN # 1.51 * STD DEV # 0.26 * RANGE # 0.88 TO 2.06 WITH 71 SAMPLES



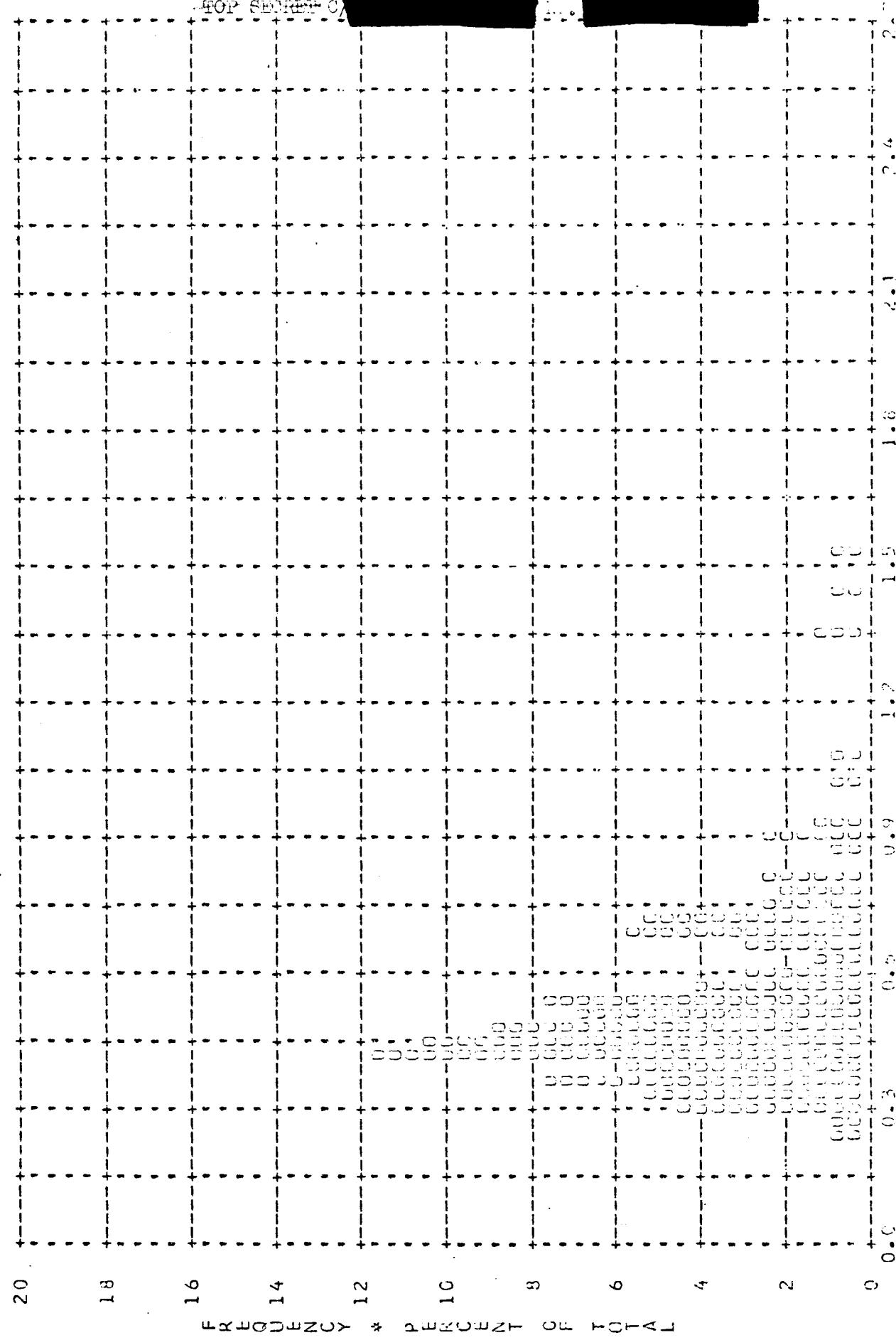
-TOP SECRET C



-TOP SECRET C

TOP SECRET C

MISSION * 1043-1 * INSTR * AFT * 1/9/68 PLCT CF D MIN * TEPRAIN * PROCESSING * FULL
ARITH MEAN * 0.53 * MEDIAN * 0.47 * STD DEV * 0.21 * RANGE * 0.24 TO 1.51 WITH 187 SAMPLES

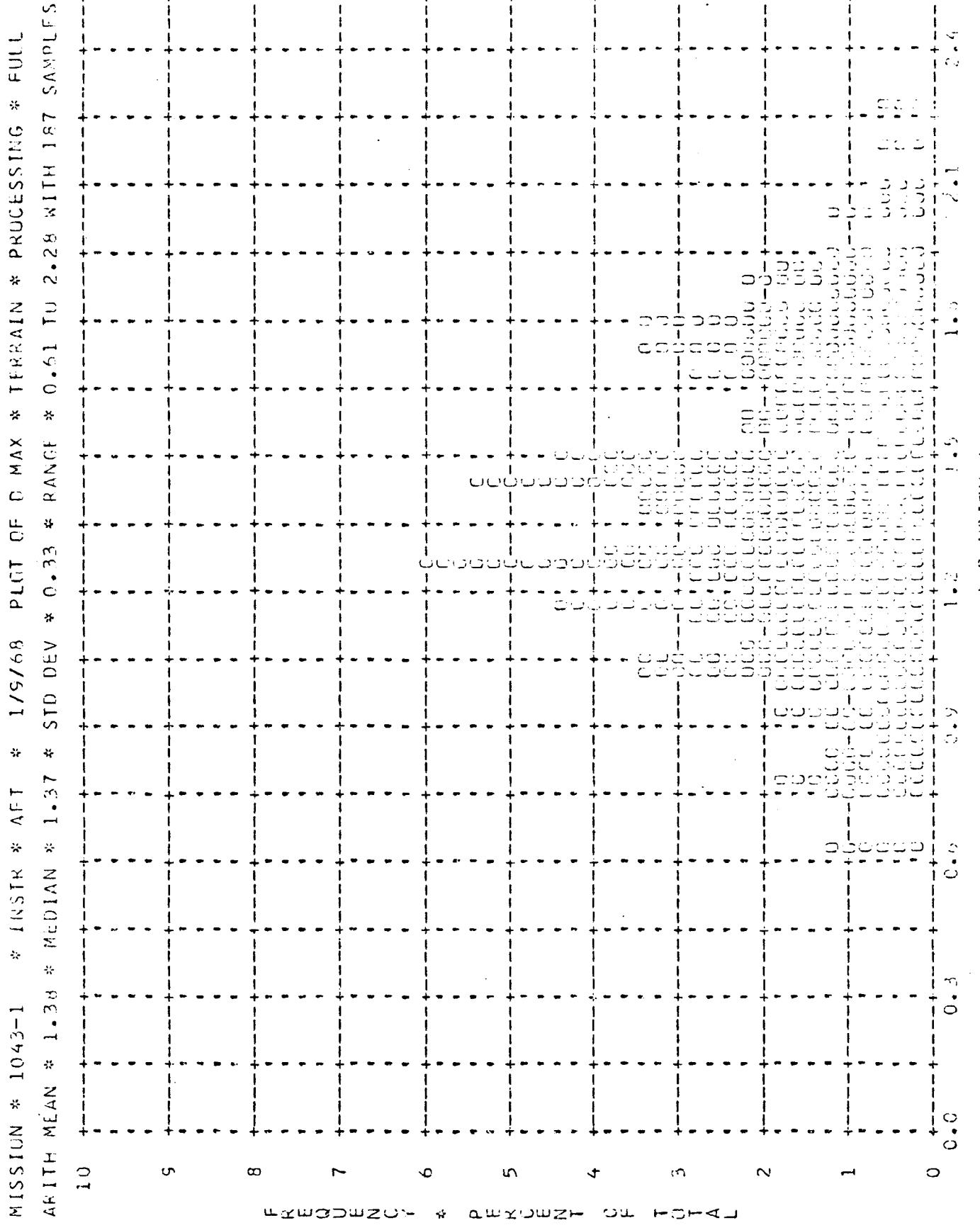


A-19

FIGURE A-2

TOP SECRET C

-TOP SECRET C



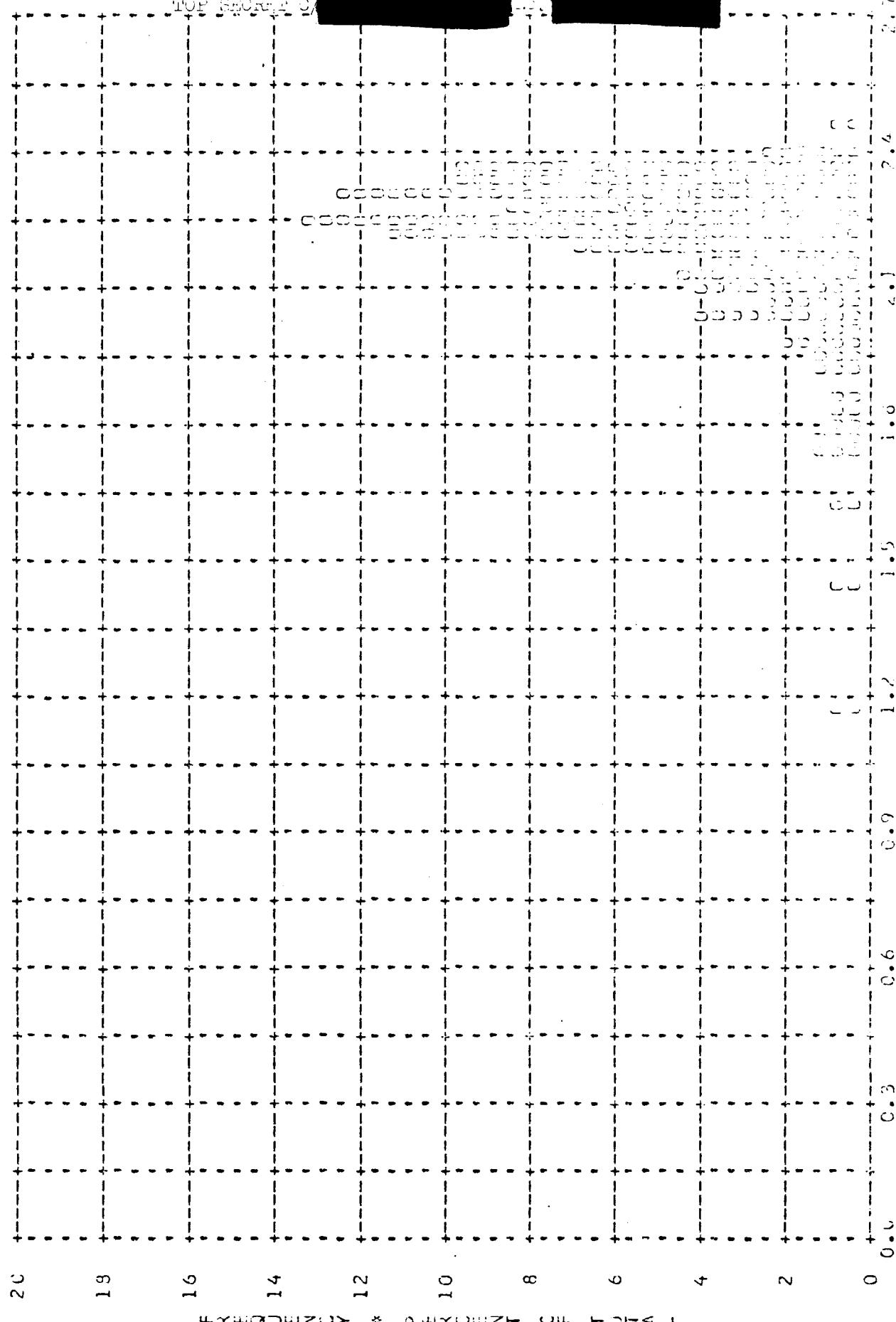
A-20

FIGURE A-2

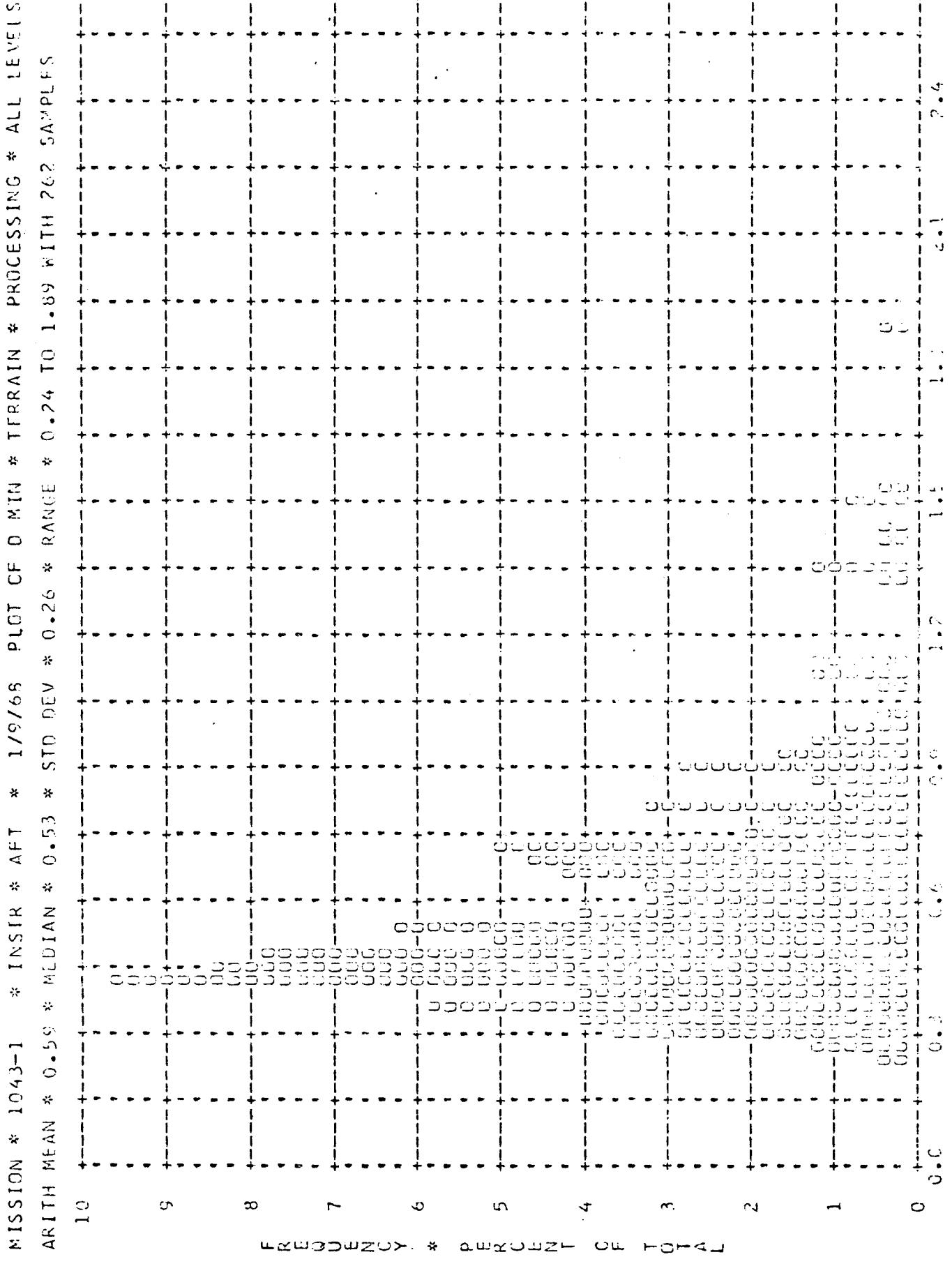
-TOP SECRET C

TOP SECRET C

MISSION * 1043-1 * INSTR * AFT * 1/9/69 PLCT CF D MAX * CLOUD * PROCESSING * FULL
ARITH MEAN * 2.20 * MEDIAN * 2.24 * STD DEV * 0.17 * RANGE * 1.17 TO 2.44 WITH 183 SAMPLES



TOP SECRET C



A-22

FIGURE A-2

TOP SECRET C

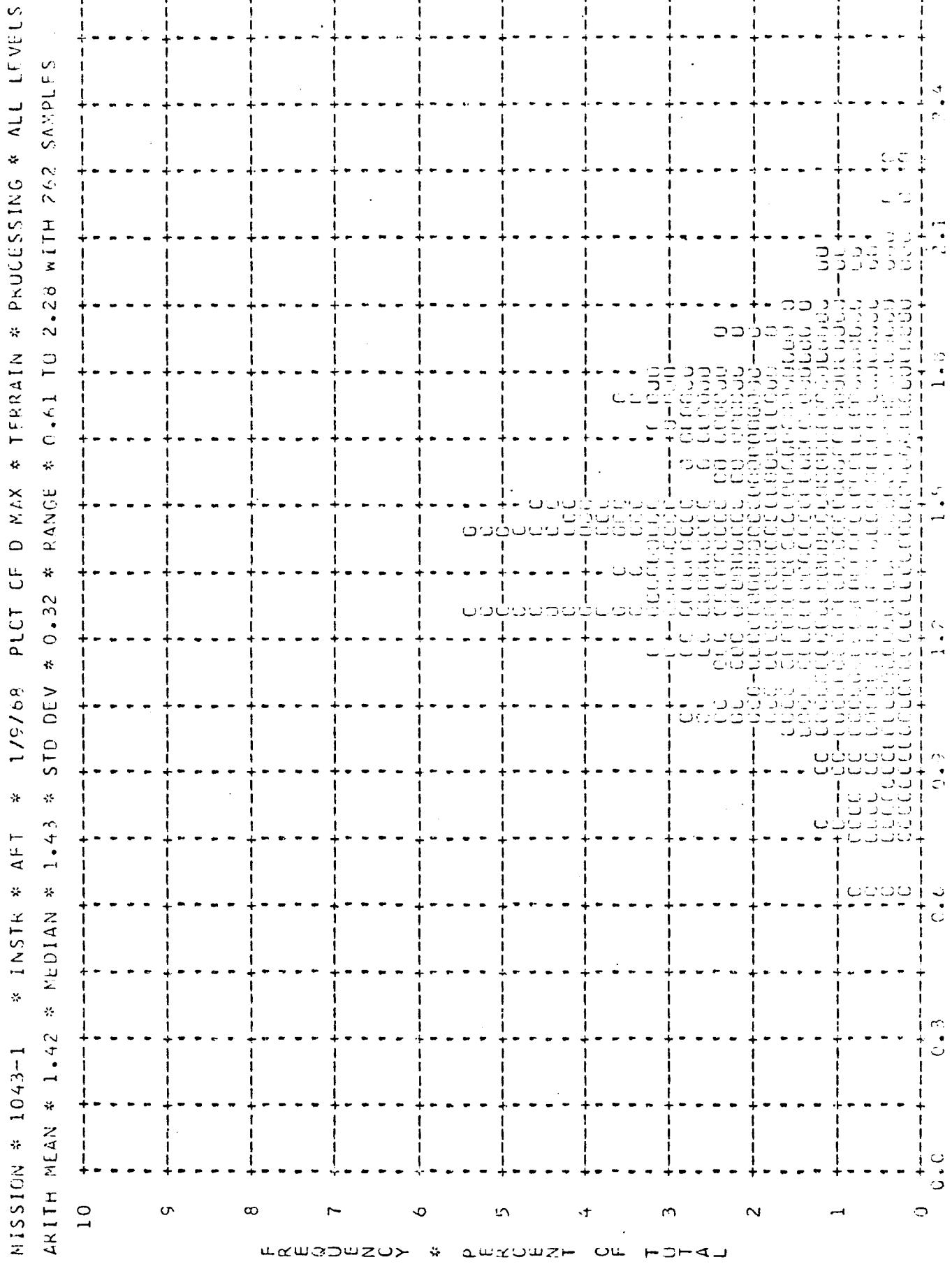
TOP SECRET//~~C~~

FIGURE A-2

TOP SECRET C

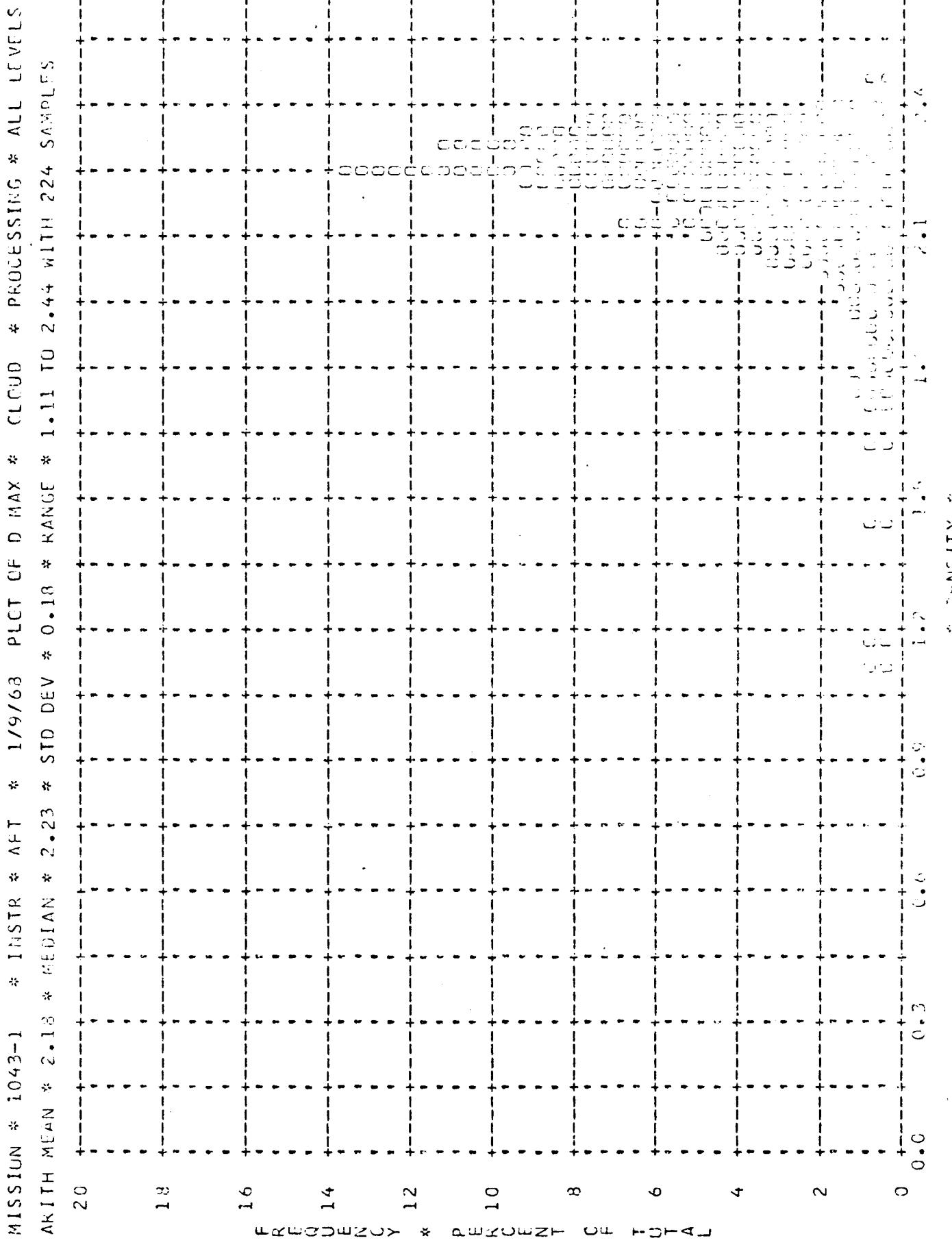
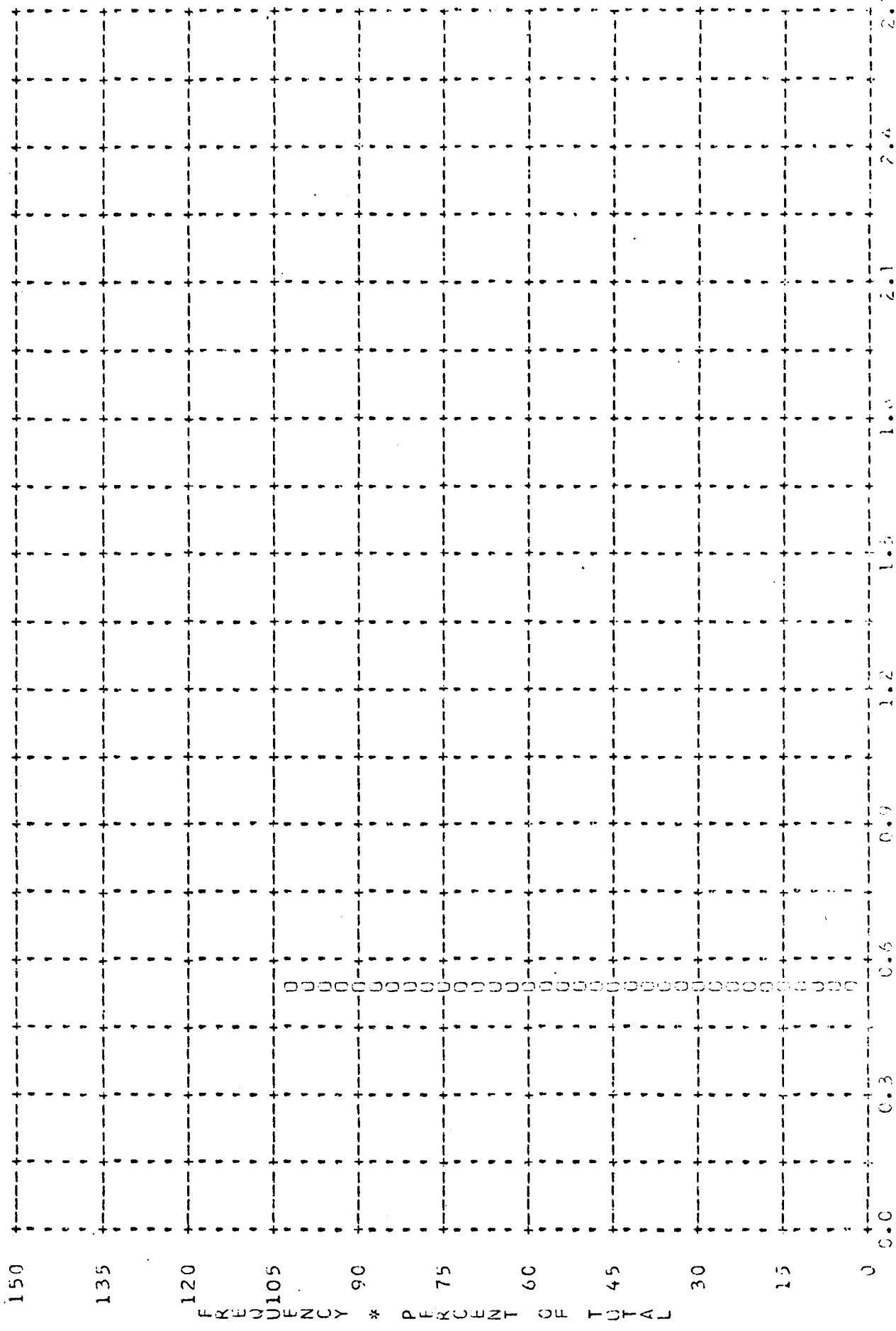


FIGURE A-2

TOP SECRET

TOP SECRET C.I.A. I.C.

MISSION # 1043-2 * INSTR # FWD * 1/9/68 PLCT OF D MIN * TERRAIN * PROCESSING * PRIMARY
ARITH MEAN # 0.54 * MEDIAN # 0.54 * STD DEV # 0.00 * RANG # 0.54 TU 0.54 WITH 1 SAMPLES



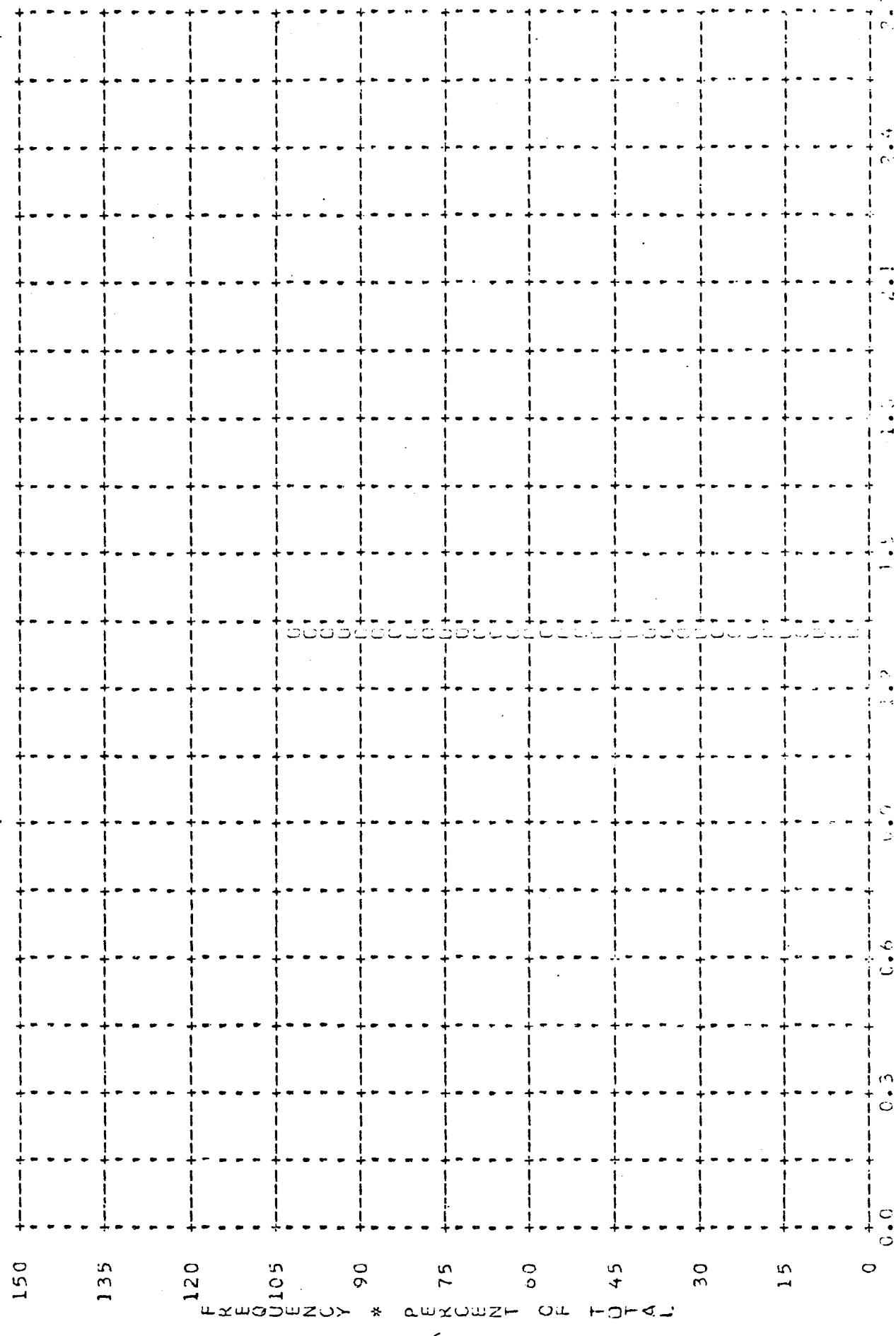
A-25

FIGURE A-3

TOP SECRET

TOP SECRET C

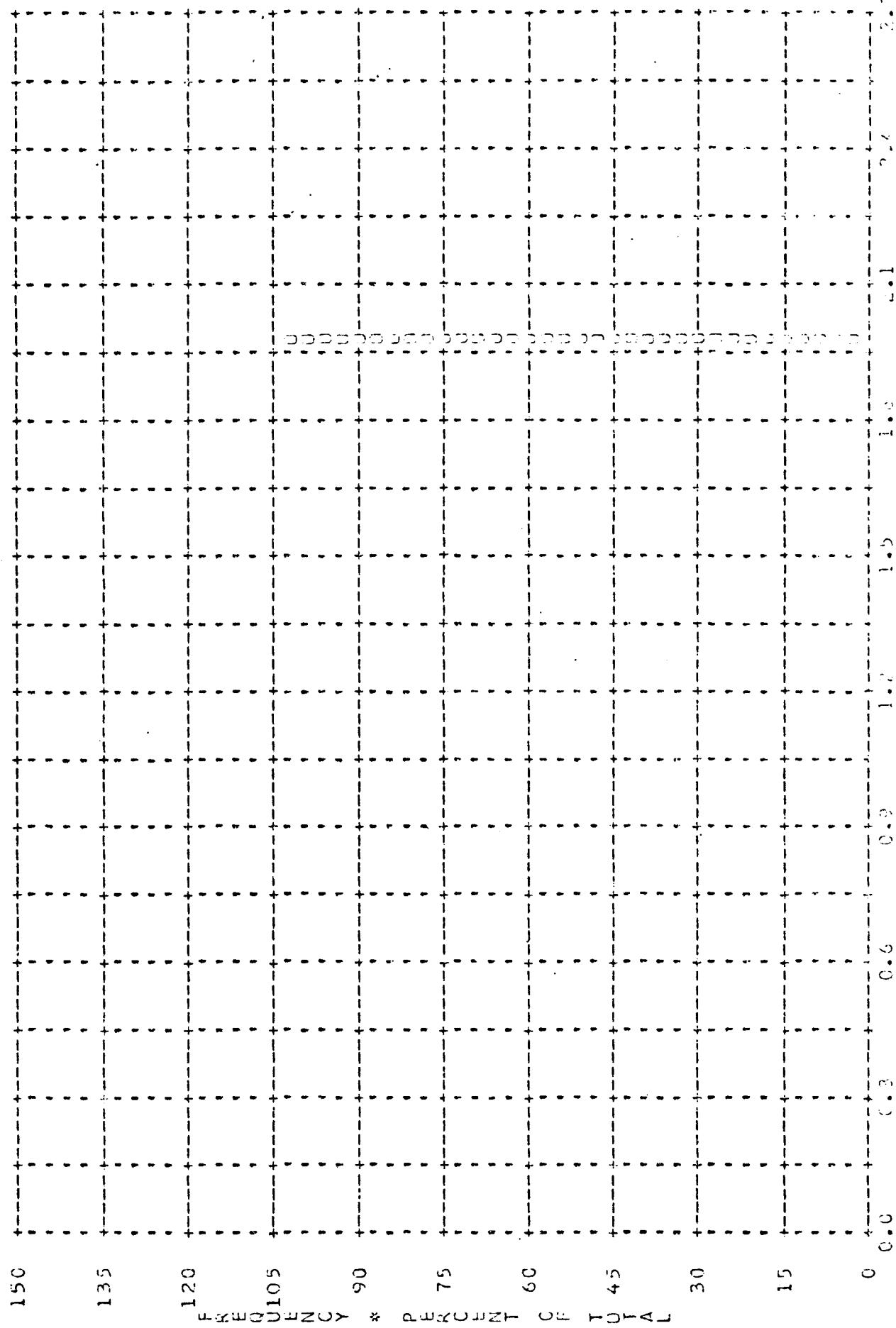
MISSION # 1043-2 * INSTK * FWD * 1/9/68 PLCT OF D MAX & TERRAIN * PROCESSING * PRIMARY
AITH MEAN * 1.32 * MEDIAN * 1.32 * STD DEV * 0.00 * RANGE * 1.32 TU 1.32 WITH 1 SAMPLES



TOP SECRET C

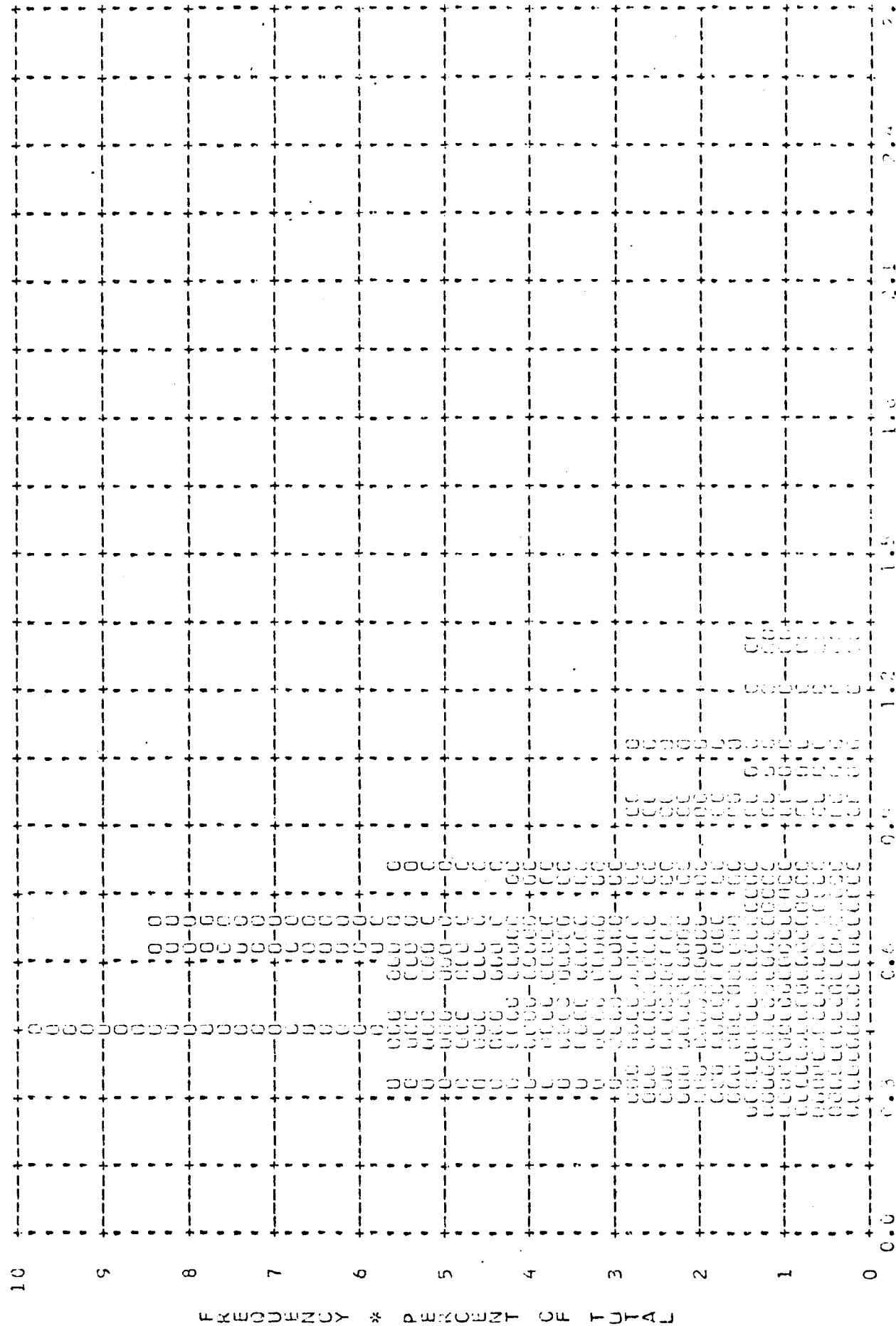
FIGURE A-3

MISSION * 1043-2 * INSTR * FWD * 1/9/68 PLCT OF D MAX * CLOUD * PROCESSING * PRIMARY
 ARITH MEAN * 1.96 * AVERAGE * 1.96 * STD DEV * 0.06 * RANGE * 1.96 TG 1.96 WITH 1 SAMPLES



TOP SECRET C

MISSION * 1043-2 * INSTR * FWD * 1/9/63 PLCT OF D MIN * TERRAIN * PROCESSING * INTERMEDIATE
ARITH MEAN * 0.62 * MEDIAN * 0.59 * STD DEV * 0.24 * RANGE * 0.27 TO 1.32 WITH 72 SAMPLES



A-28

FIGURE A-3

TOP SECRET C

* CLASSITY *

TOP SECRET C

7.7

7.4

7.1

6.8

6.5

6.2

5.9

5.6

5.3

5.0

4.7

4.4

4.1

3.8

3.5

3.2

2.9

2.6

2.3

2.0

1.7

1.4

1.1

0.8

0.5

0.2

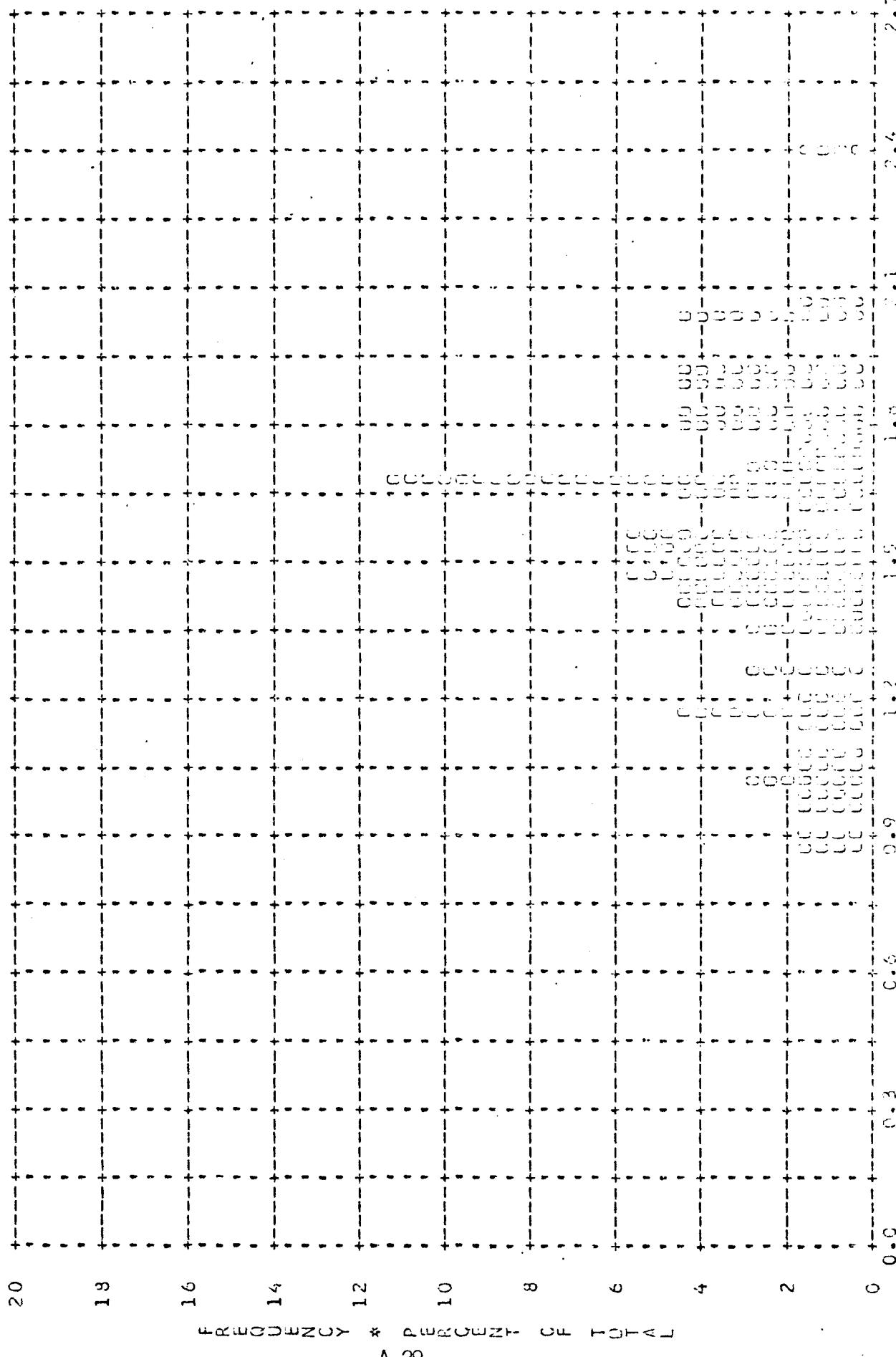
0.1

0.0

TOP SECRET C

TOP SECRET C

MISSION * 1043-2 * INSTA * FWD * 1/9/68 PLOT OF D MAX * TERRAIN * PROCESSING * INTERMEDIATE
ARITH MEAN * 1.54 * MEDIAN * 1.55 * STD DEV * 0.31 * RANGE * 0.85 TO 2.39 WITH 72 SAMPLES



A-29

TOP SECRET C

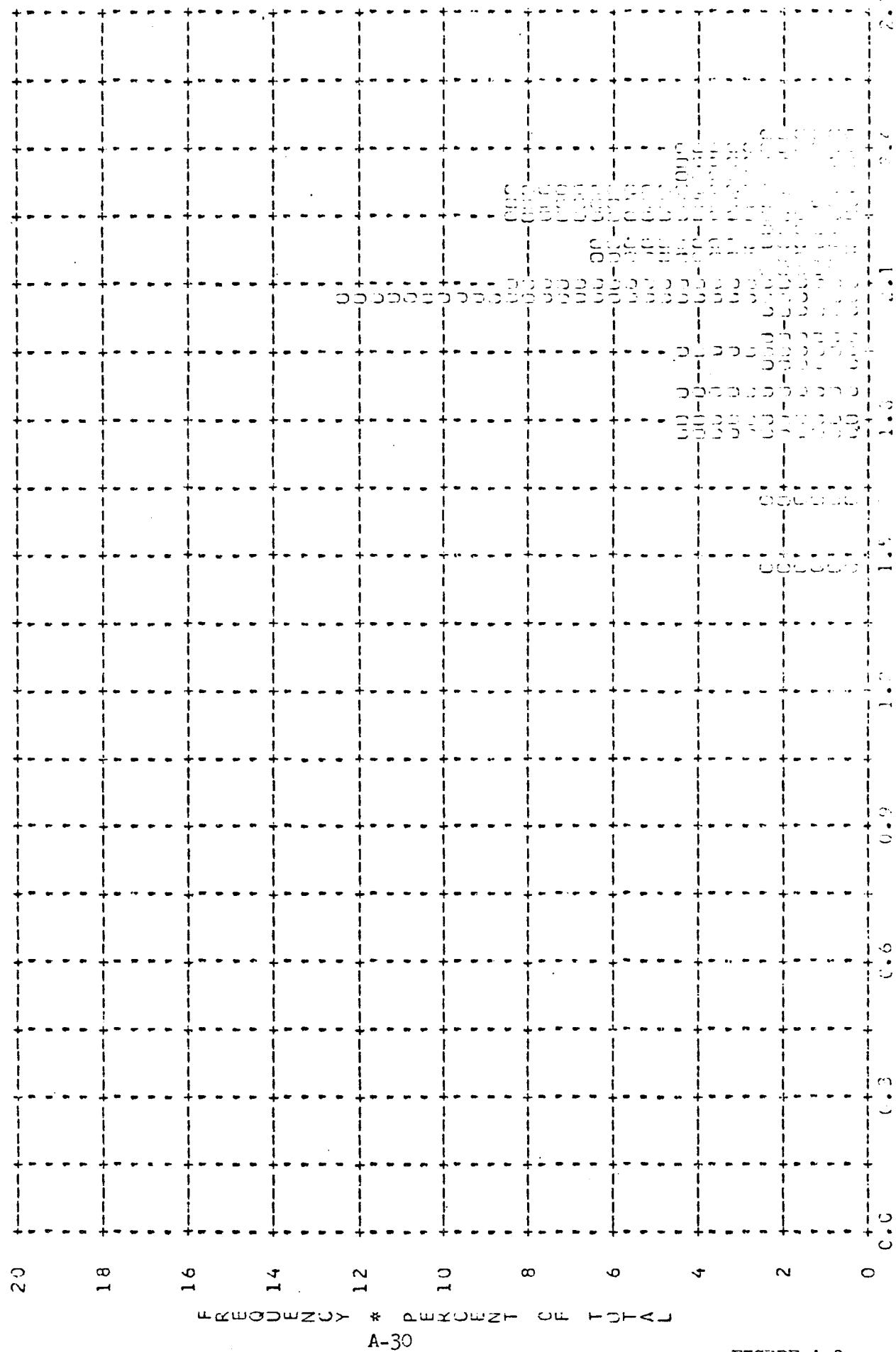
FIGURE A-3

* DENSITY *

TOP SECRET C

TOP SECRET C

MISSION # 1045-2 * INSTR # FAD # 1/9/68 PLCT OF D MAX # CLCUD # PROCESSING # INTERPOLATE
ARITH MEAN # 2.11 * MEDIAN # 2.16 * STD DEV # 0.21 * RANGE # 1.45 TO 2.41 WITH 50 SAMPLES

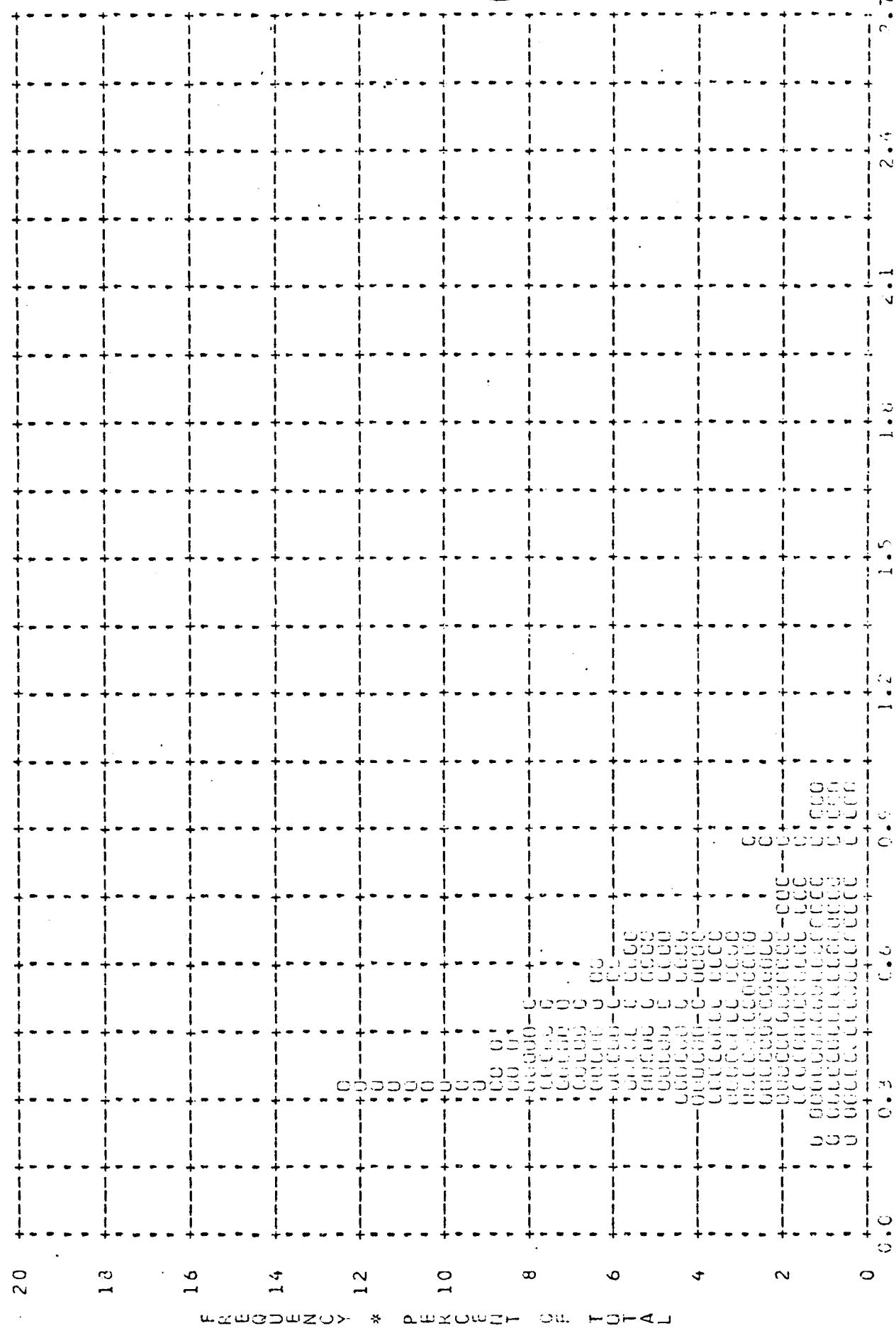


A-30

FIGURE A-3

-TOP SECRET C

MISSION * 1043-2 * INSTR * FWG * 1/9/68 PLCT OF D MIN * TERRAIN * PROCESSING * FULL
ARIITH MEAN * 0.49 * MEDIAN * 0.45 * STD DEV * 0.16 * RANGE * 0.19 TU 0.97 WITH 114 SAMPLES



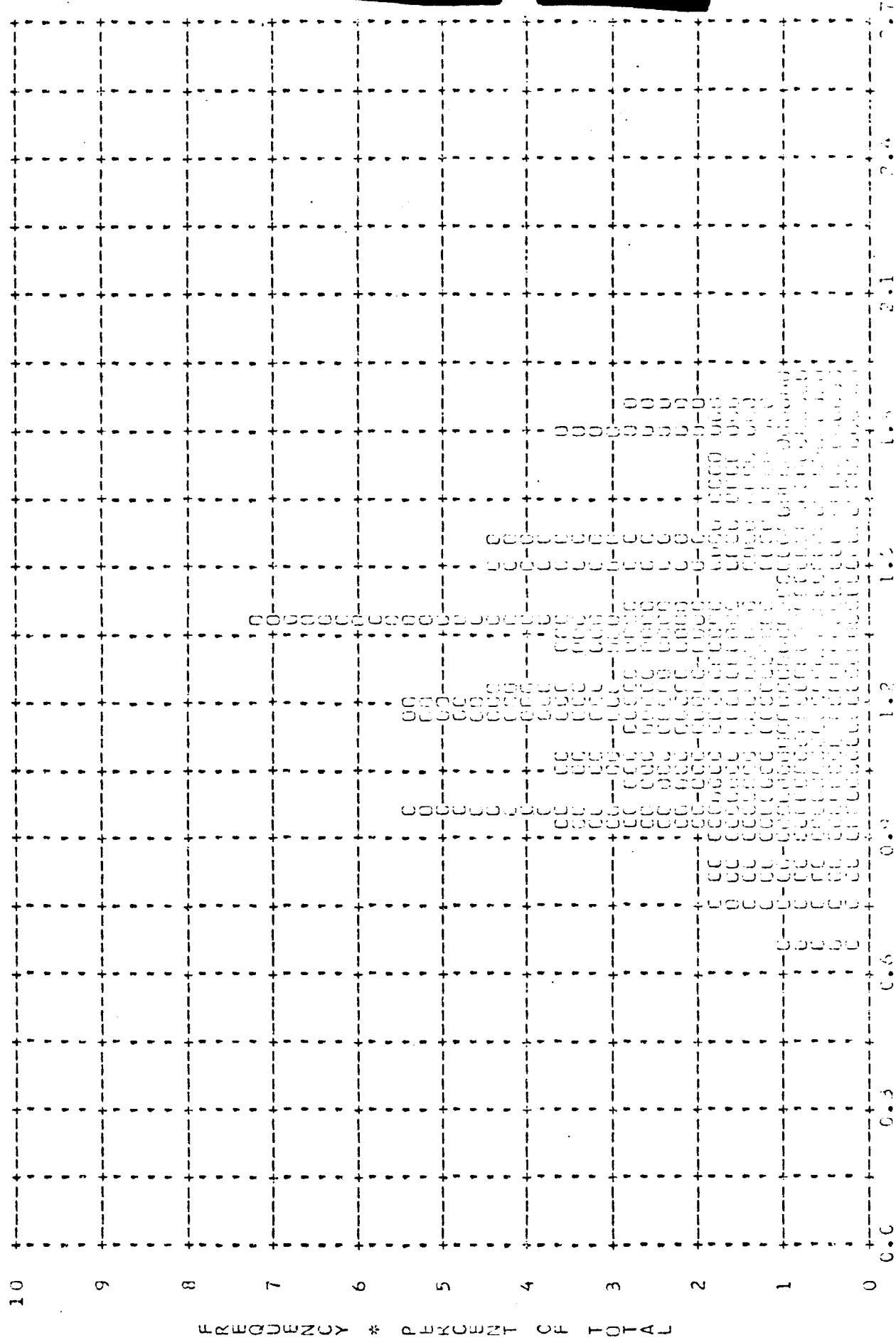
A-31

FIGURE A-3

-TOP SECRET C

~~TOP SECRET C~~

KISSION * 1043-2 * INSTR * FWD * 1/9/68 PLCT OF D MAX * TERRAIN * PROCESSING * FULL
ARITH MEAN * 1.30 * MEDIAN * 1.28 * STD DEV * 0.30 * RANGE * 0.66 TO 1.91 WITH 114 SAMPLES



A-32

FIGURE A-3

TOP SECRET C

MISSION * 1043-2 * INSTR * FWD * 1/9/68 PLCT CF D MAX * CLCUD * PROCESSING * FULL
ARITH MEAN * 2.21 * MEDIAN * 2.24 * STD DEV * 0.20 * RANGE * 0.84 TO 2.44 WITH 131 SAMPLES

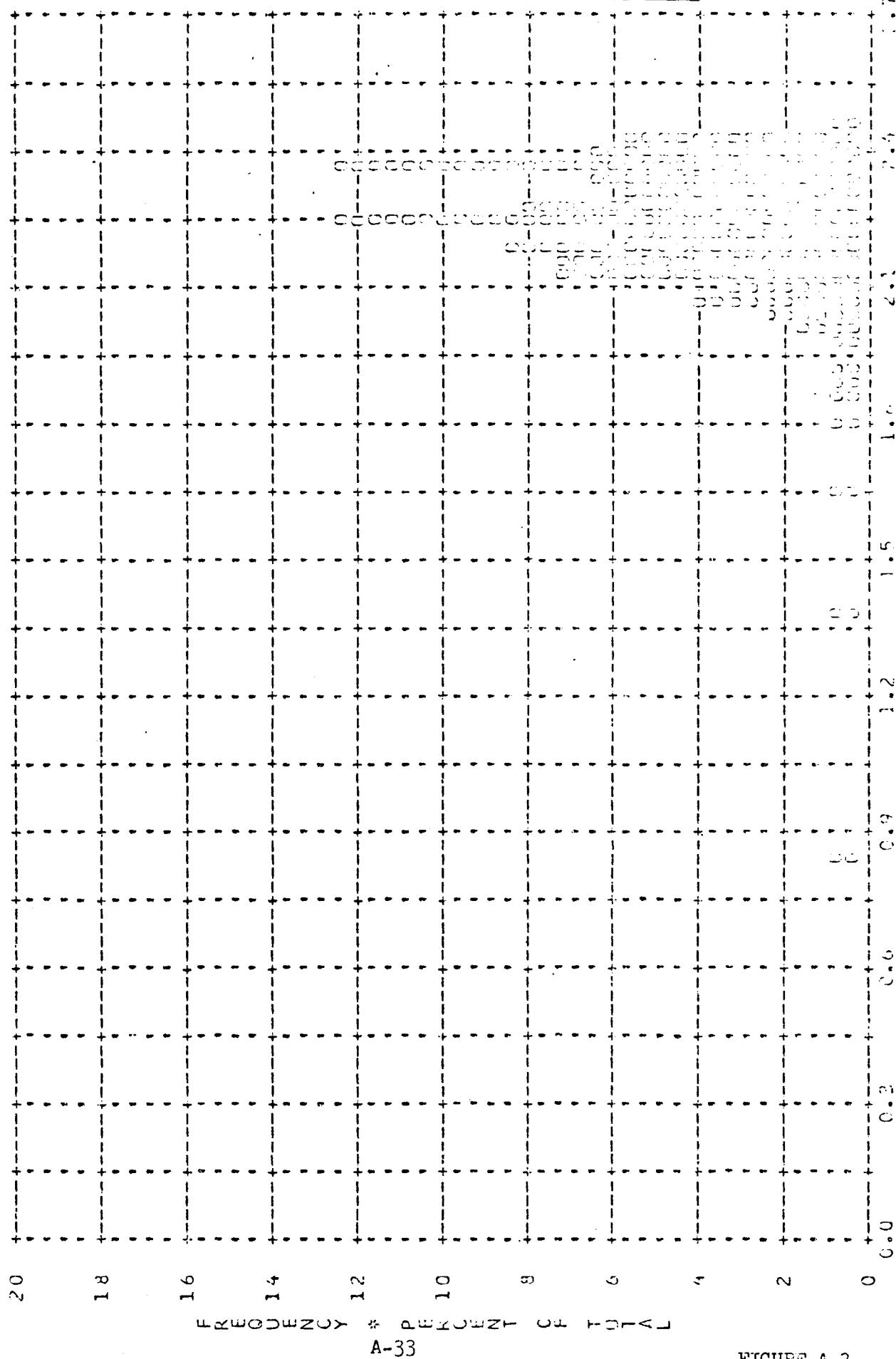
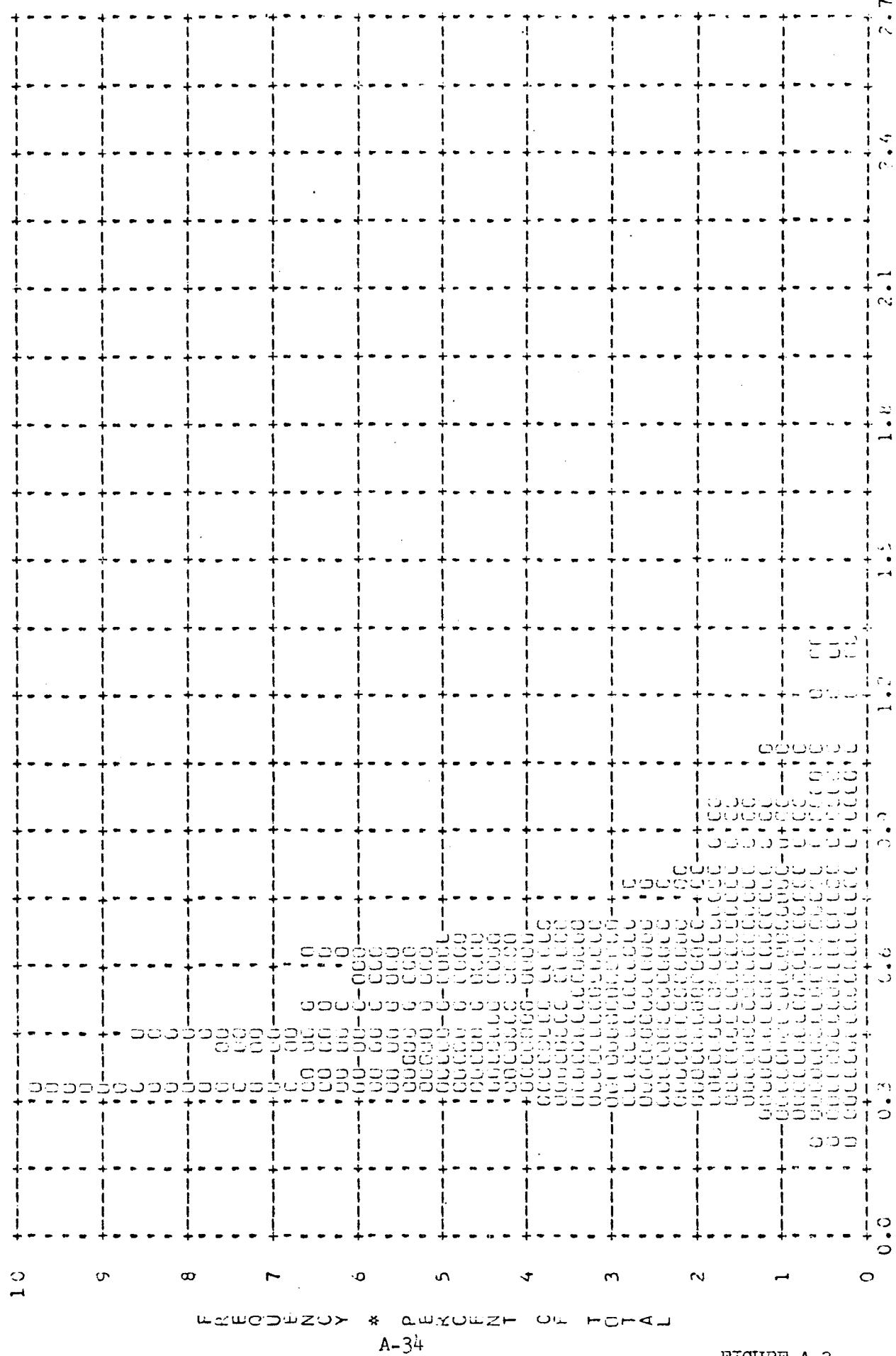


FIGURE A-3

TOP SECRET C

TOP SECRET C

MISSION # 1043-2 * INSTR # FAD * 1/9/68 PLCT OF D MIN * TERRAIN * PROCESSING * ALL LEVELS
ARITH MEAN # 0.54 * MEDIAN # 0.50 * STD DEV # 0.20 * RANGE # 0.19 TO 1.37 WITH 187 SAMPLES



A-34

FIGURE A-3

TOP SECRET C

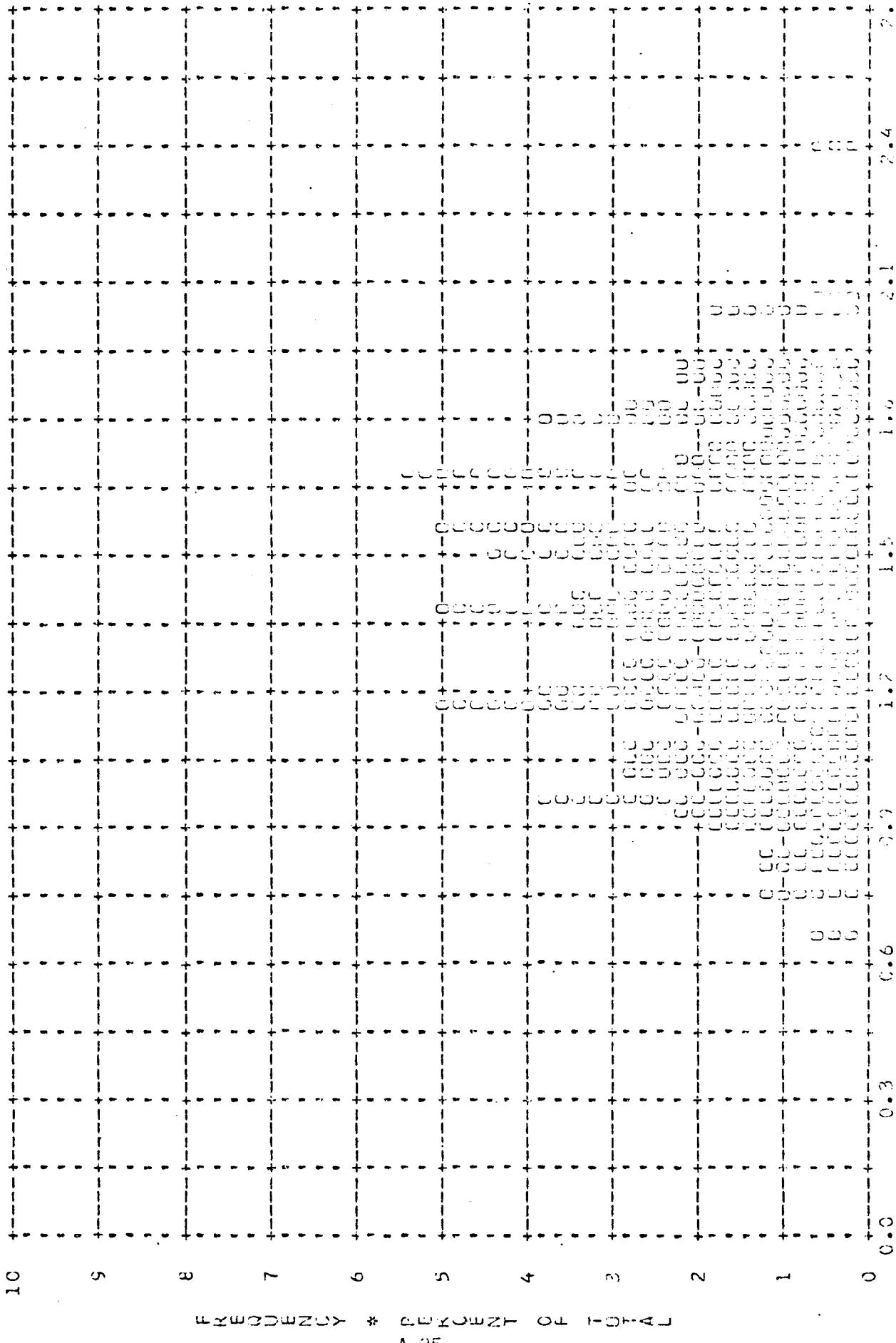
* DENSITY

TOP SECRET C

TOP SECRET C

TOP SECRET C

MISSION # 1043-2 * INSTR # FAD * 1/9/68 PLC1 CF D MAX * TERRAIN * PROCESSING * ALL LEVELS
WITH MEAN # 1.39 * MEDIAN # 1.39 * STD DEV # 0.33 * RANGE # 0.66 TO 2.39 WITH 187 SAMPLES



A-35

FIGURE A-3

TOP SECRET C

TOP SECRET C

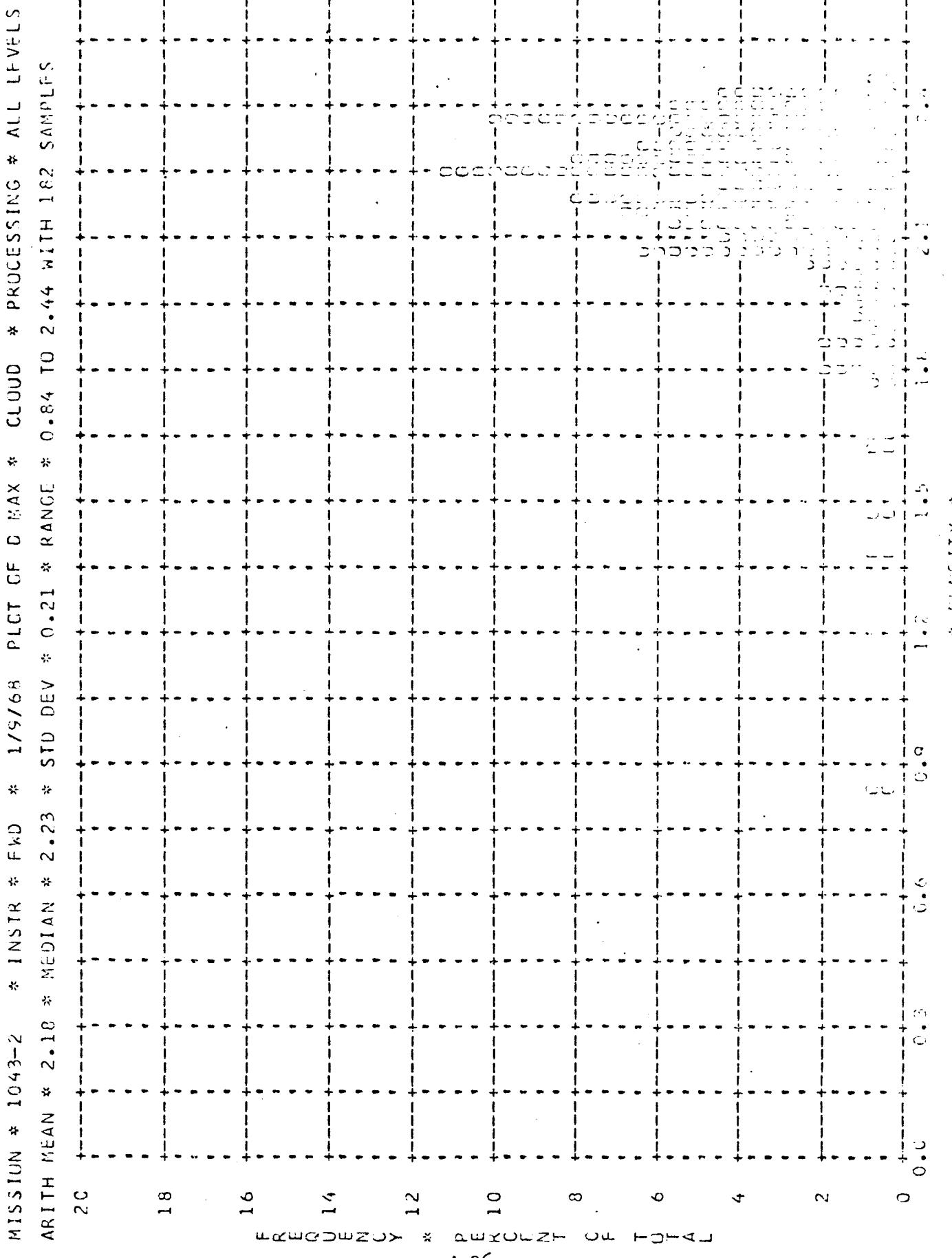
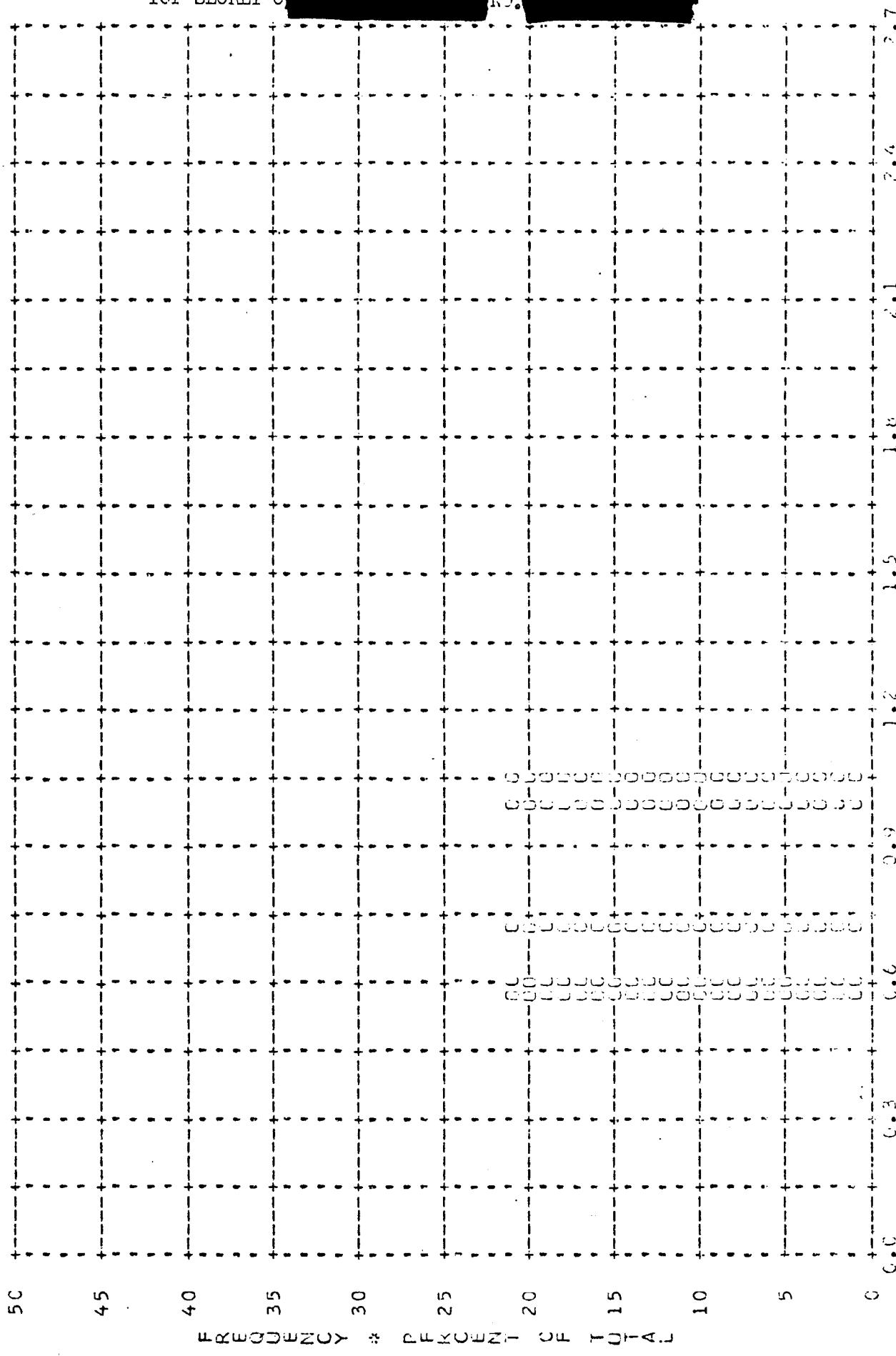


FIGURE A-3

TOP SECRET C

MISSION * 1043-2 * INSTR * AFT * 1/9/68 PLOT CF MIN * TERRAIN * PROCESSING * PRIMARY
ARITH MEAN * 0.78 * MEDIAN * 0.70 * STD DEV * 0.22 * RANGE * 0.57 TU 1.04 WITH 5 SAMPLES

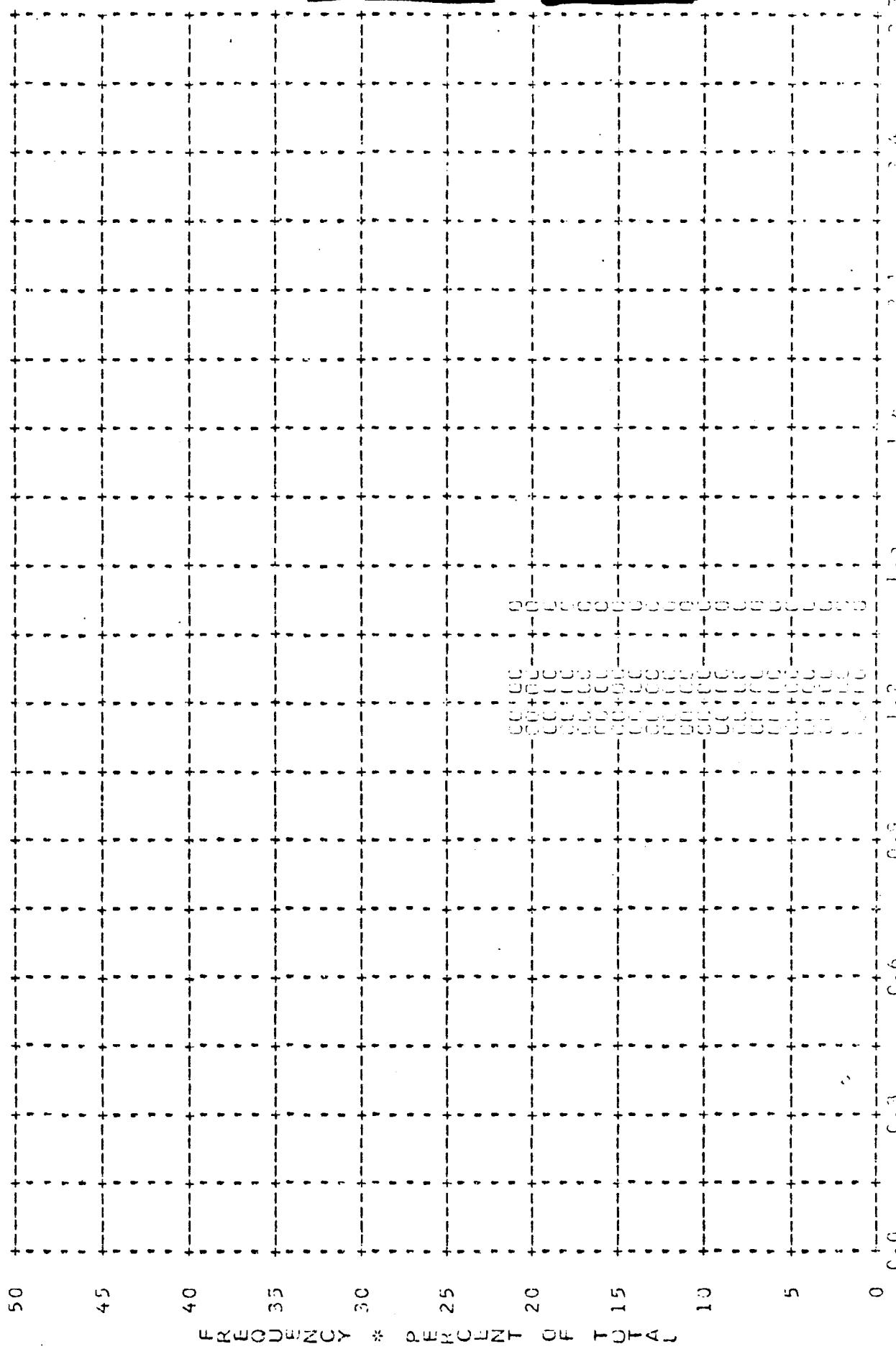


A-37

FIGURE A-4

-TOP SECRET C

MISSION * 1043-2 * INSTR * AFT * 1/9/68 PLOT CF D MAX * TERRAIN * PROCESSING * PRINTAV
 ARITH MEAN * 1.23 * MEDIAN * 1.21 * STD DEV * 0.10 * RANGE * 1.14 TO 1.39 WITH 5 SAMPLES

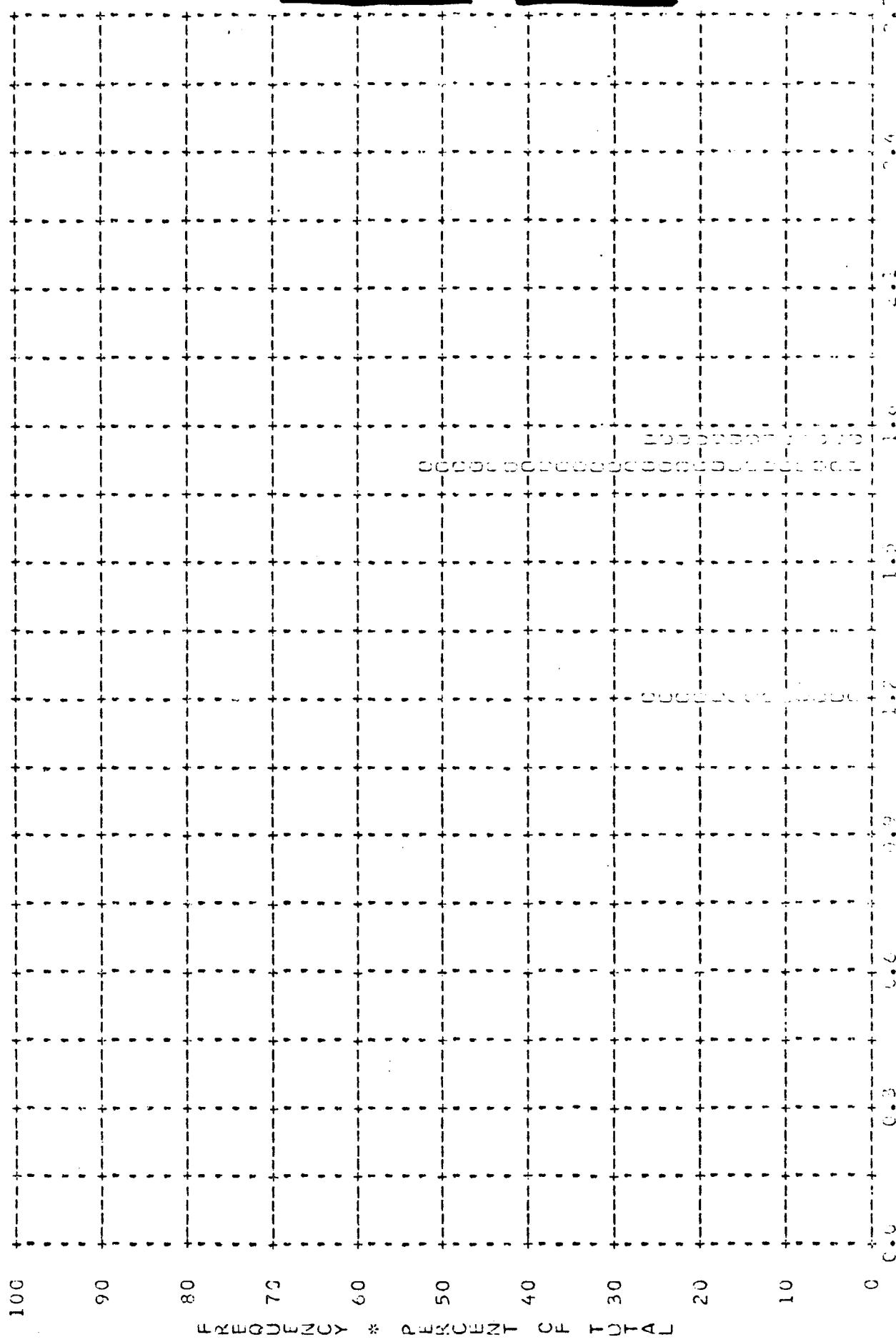


~~TOP SECRET C~~

~~TOP SECRET C~~

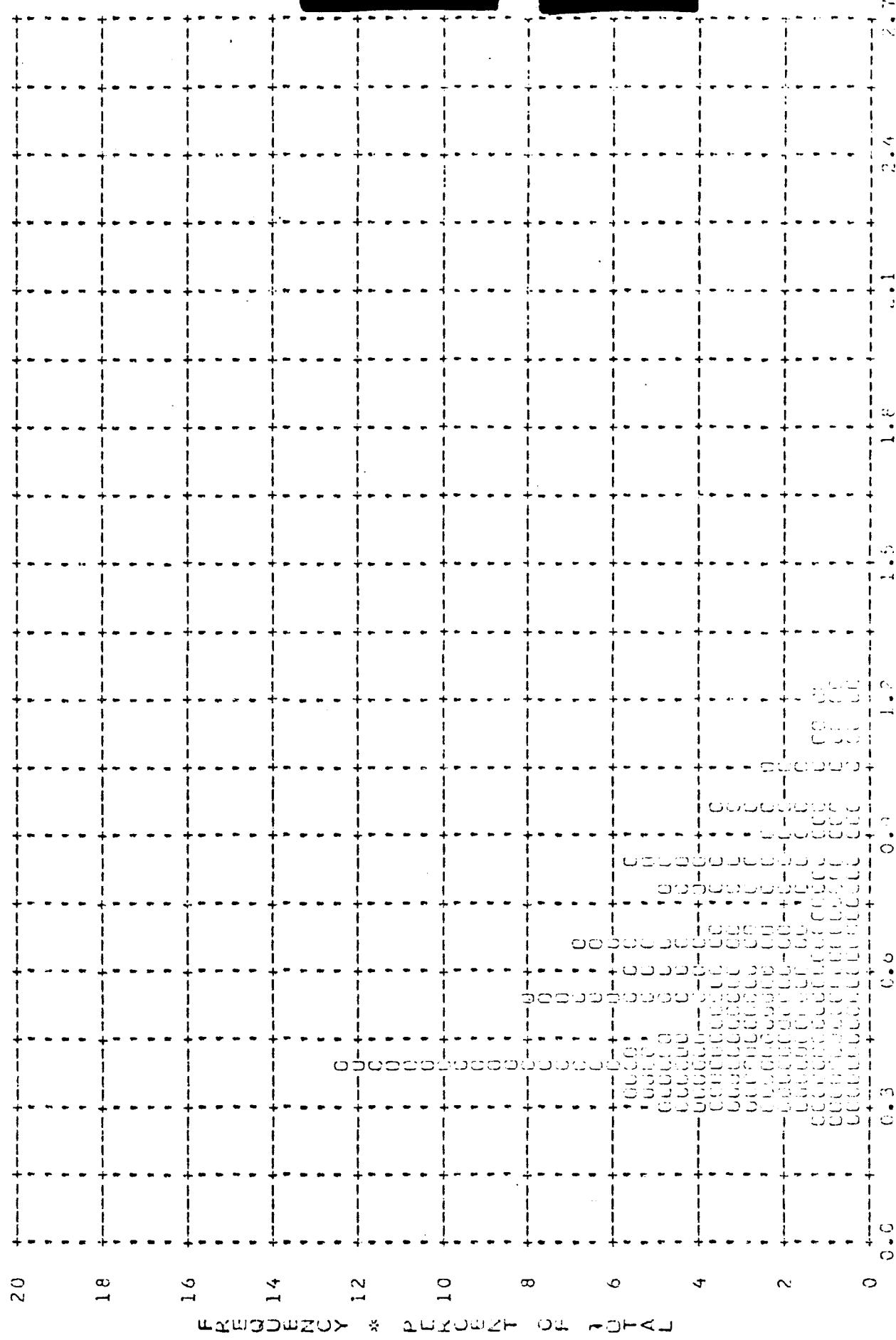
~~NO.~~

MISSION * 1043-2 * INSTR * AFT * 1/9/68 PLCT OF D MAX * CLCUD * PROCESSING * PRIMARY
ARITH MEAN * 1.59 * MEDIAN * 1.71 * STD DEV * 0.26 * RANGE * 1.20 TO 1.77 WITH 4 SAMPLES



MISSION * 1043-2 * INSTR * AFT * 1/9/68 PLT OF D MIN * TERRAIN * PROCESSING * INTERIM

ARITH MEAN * 0.50 * MEDIAN * 0.53 * STD DEV * 0.23 * RANGE * 0.25 TO 1.22 WITH 60 SAMPLES



A-40

FIGURE A-4

~~TOP SECRET C~~

MISSION * 1043-2 * INSTK * AFT * 1/9/68 PLCT CF D MAX * TERRAIN * PROCESSING * INTERMEDIATE
ARITH MEAN * 1.36 * MEDIAN * 1.44 * STD DEV * 0.29 * RANGE * 0.61 TO 1.88 WITH 90 SAMPLES

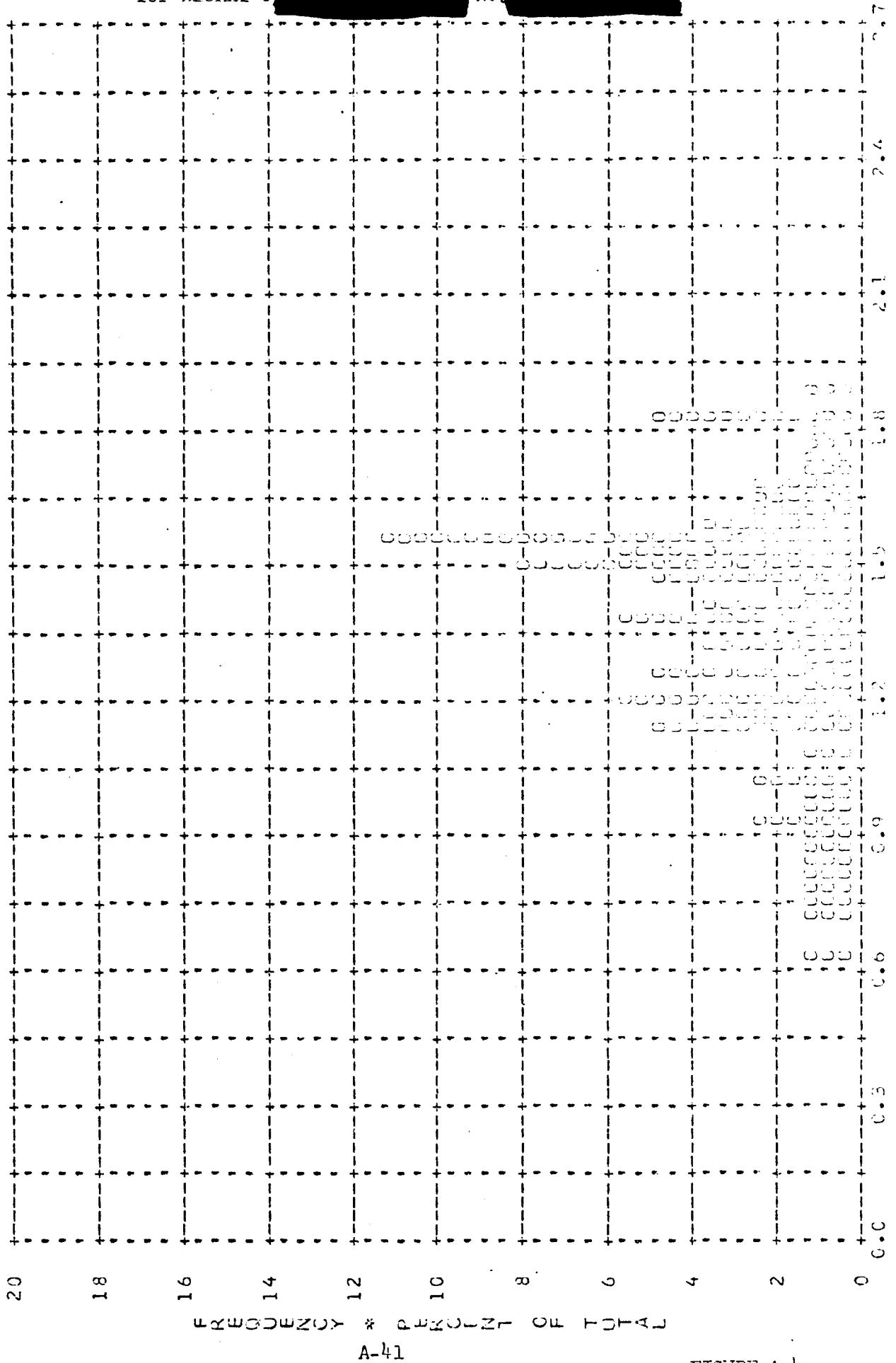
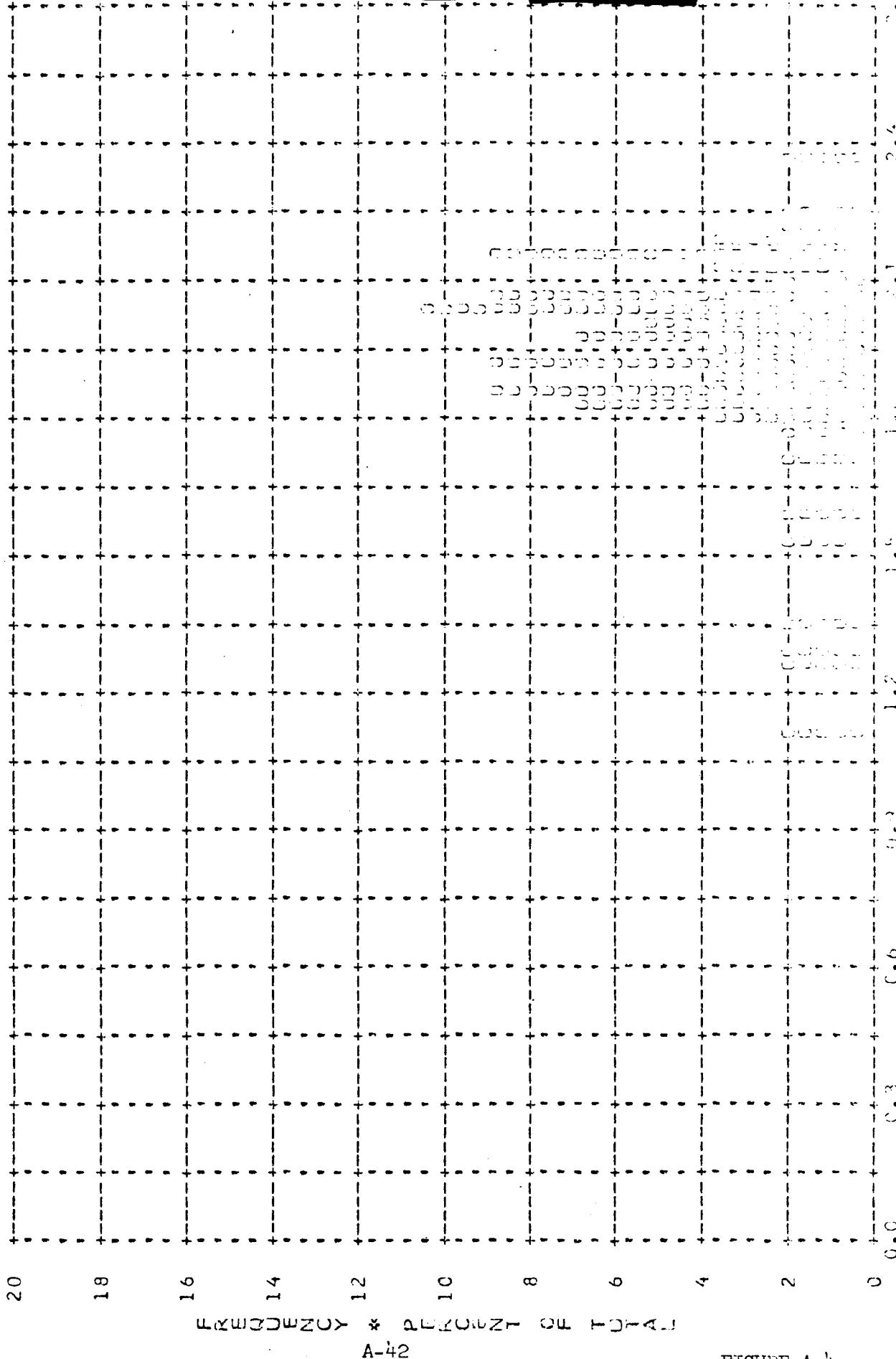


FIGURE A-4

~~TOP SECRET C~~

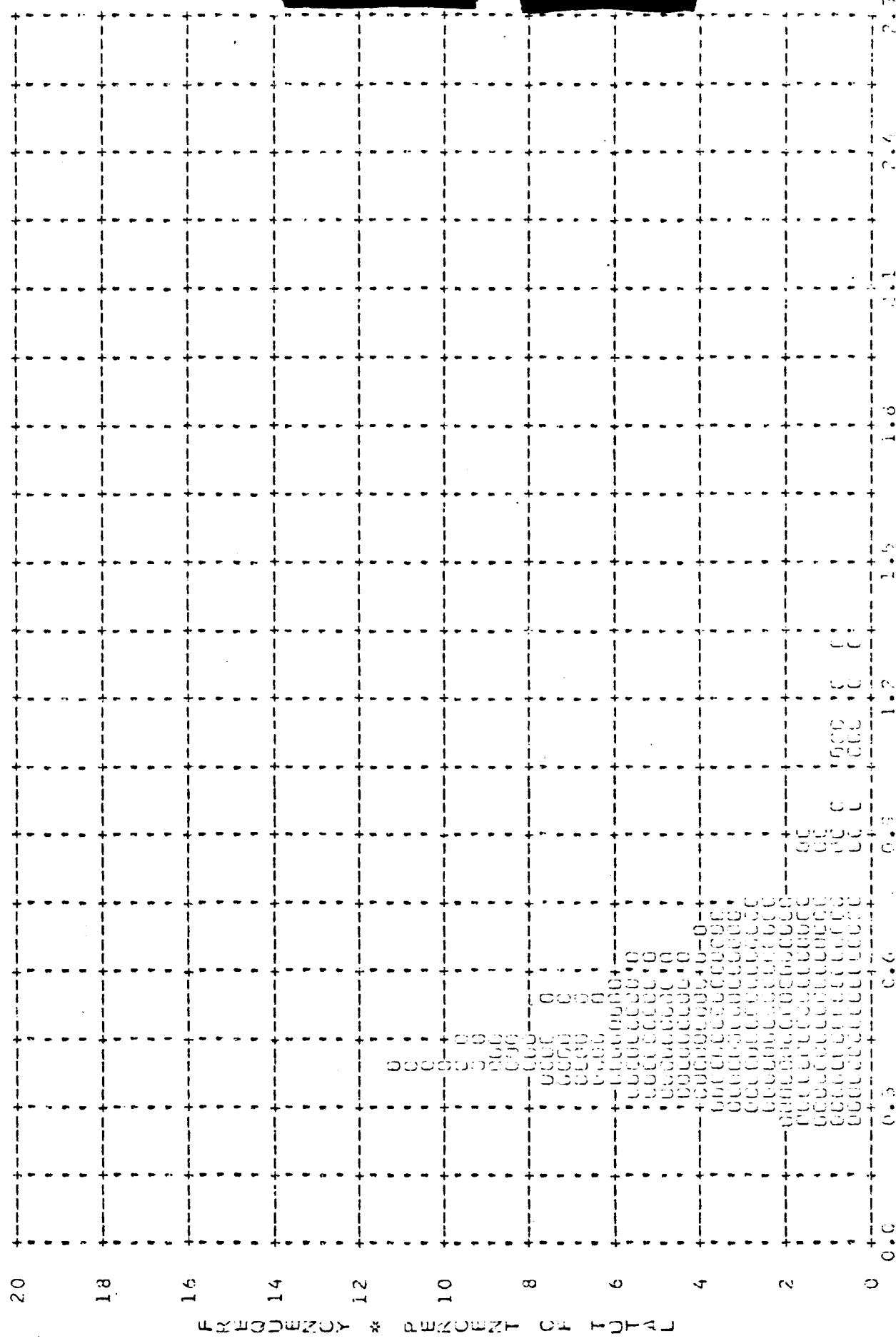
~~TOP SECRET C~~ [REDACTED] C
MISSION * 1043-2 * INSTR * AFT * 1/9/63 PLCT OF D MAX * CLCUD * PROCESSING * INTERIMEDIATE
ARITH MEAN * 1.42 * MEDIAN * 1.97 * STD DEV * 0.24 * RANGE * 1.09 TO 2.35 WITH 59 SAMPLES



A-42

FIGURE A-4

~~TOP SECRET C~~ [REDACTED] 10. [REDACTED]
MISSION * 1043-2 * INSTR * AFT * 1/9/68 PLOT OF D MIN * TERRAIN * PROCESSING * FULL
ARITH MEAN * 0.51 * MEDIAN * 0.47 * STD DEV * 0.19 * RANGE * 0.26 TO 1.32 WITH 152 SAMPLES



-TOP SECRET C [REDACTED] 1.0 [REDACTED]
MISSION # 1043-2 * INSTN # AFT * 1/9/68 PLCT OF D MAX * TERRAIN * PROCESSING * FULL
ARITH MEAN # 1.22 * MEDIAN # 1.21 * STD DEV # 0.32 * RANGE # 0.55 TU 2.06 WITH 152 SAMPLES

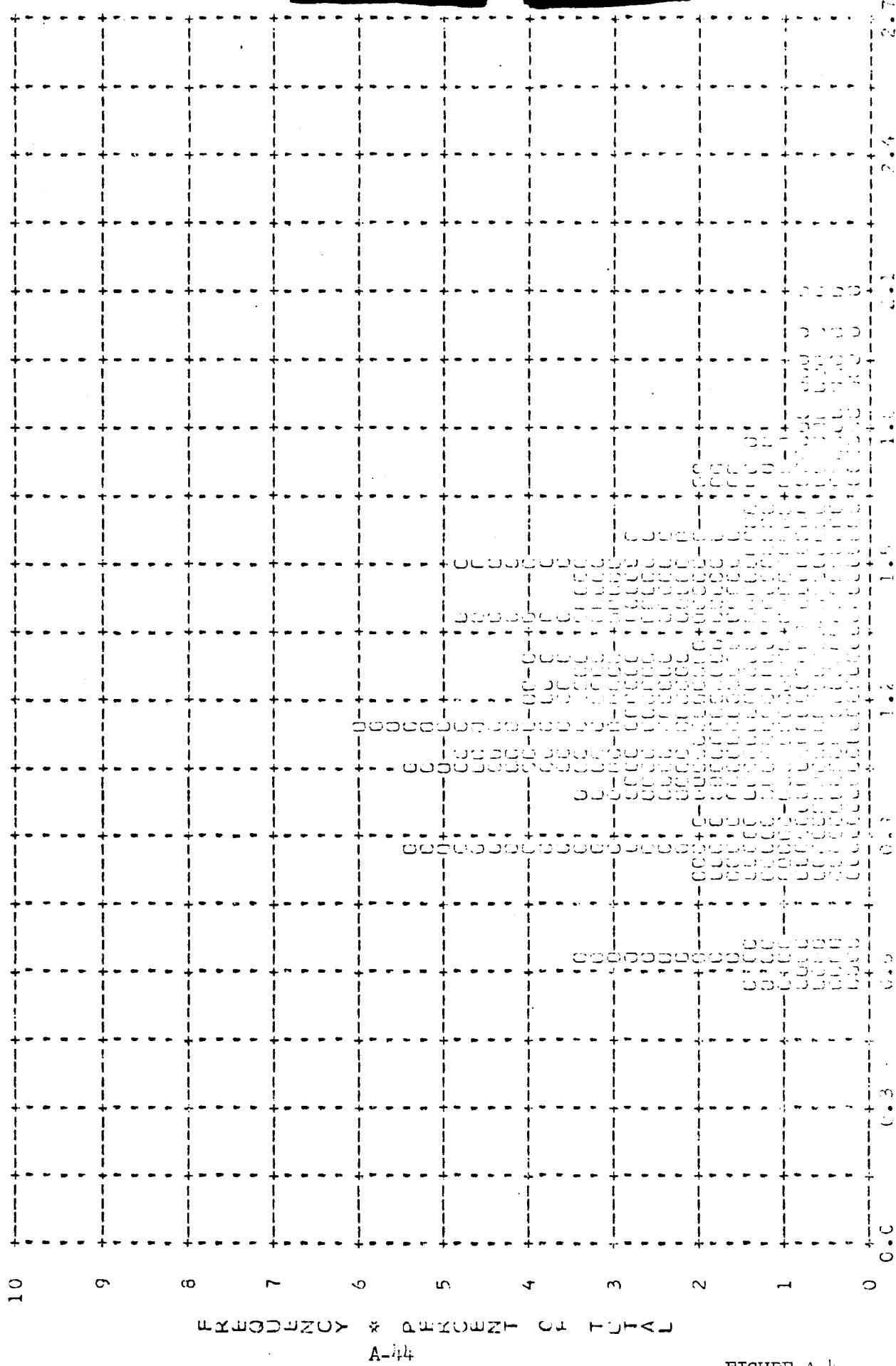


FIGURE A-4

MISSION * 1043-2 * INSTK * API * 1/9/68 PLC1 OF D MAX * CLOUD * PROCESSING * FULL
AITH MEAN * 2.07 * MEDIAN * 2.12 * STD DEV * 0.22 * RANGE * 1.35 TO 2.46 WITH 165 SAMPLES

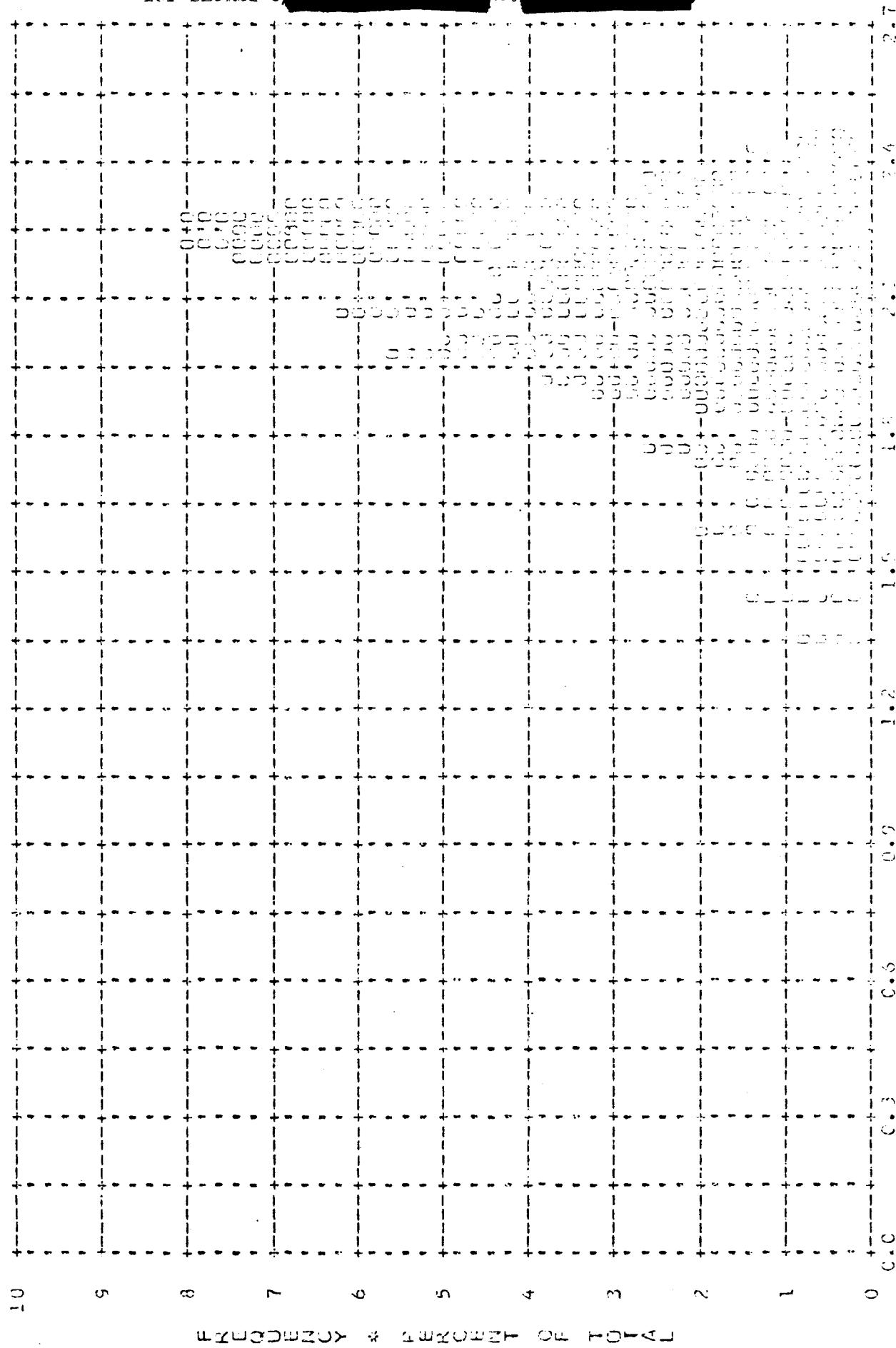


FIGURE A-4

MISSION # 1043-2 * INSTR # AFT * 1/5/68 PLCT CF D MIN * TERRAIN * PROCESSING * ALL LEVELS
ARITH MEAN # 0.54 * MEDIAN # 0.50 * STD DEV # 0.21. * RANGE # 0.25 TO 1.32 WITH 247 SAMPLES

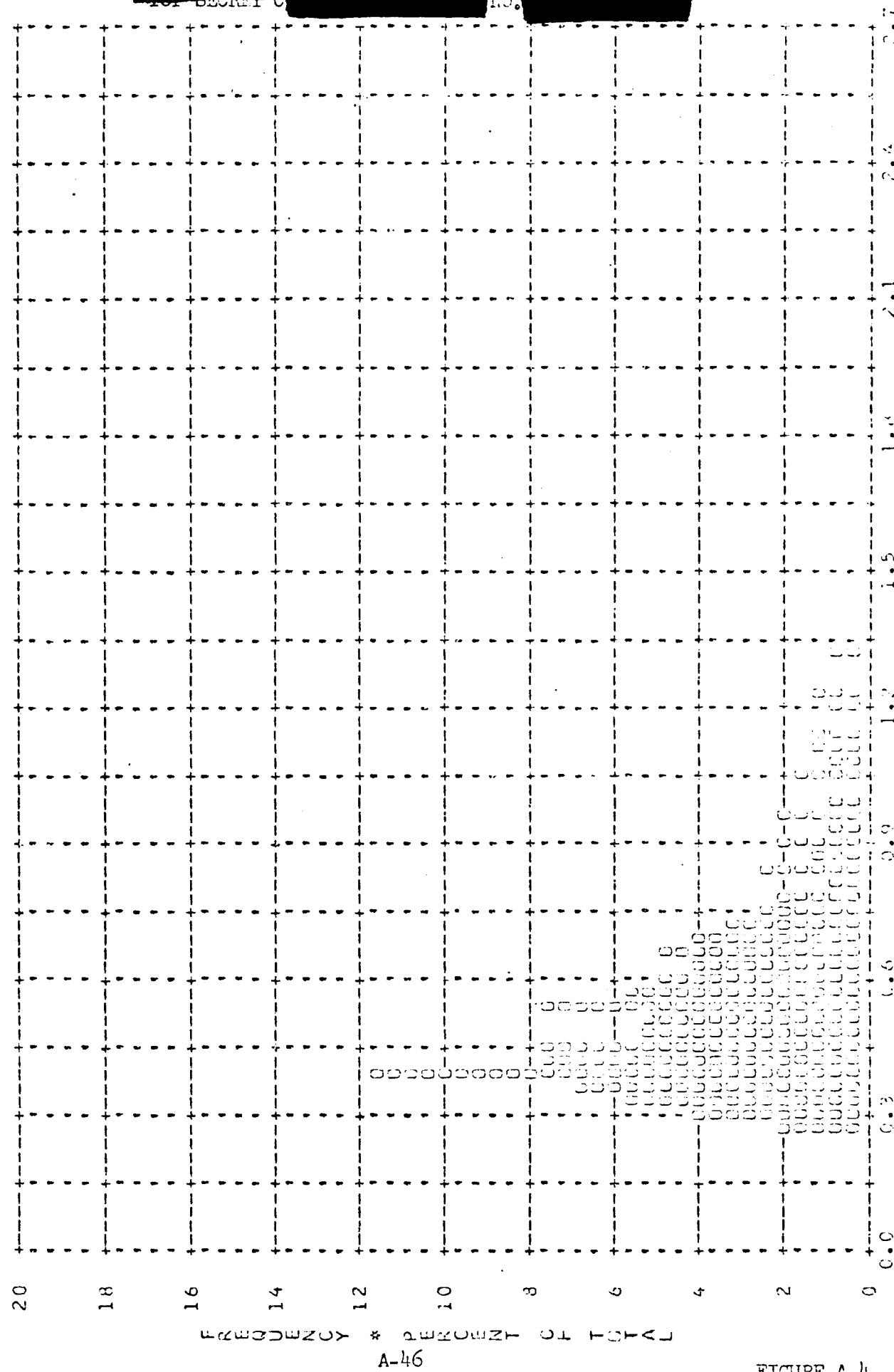
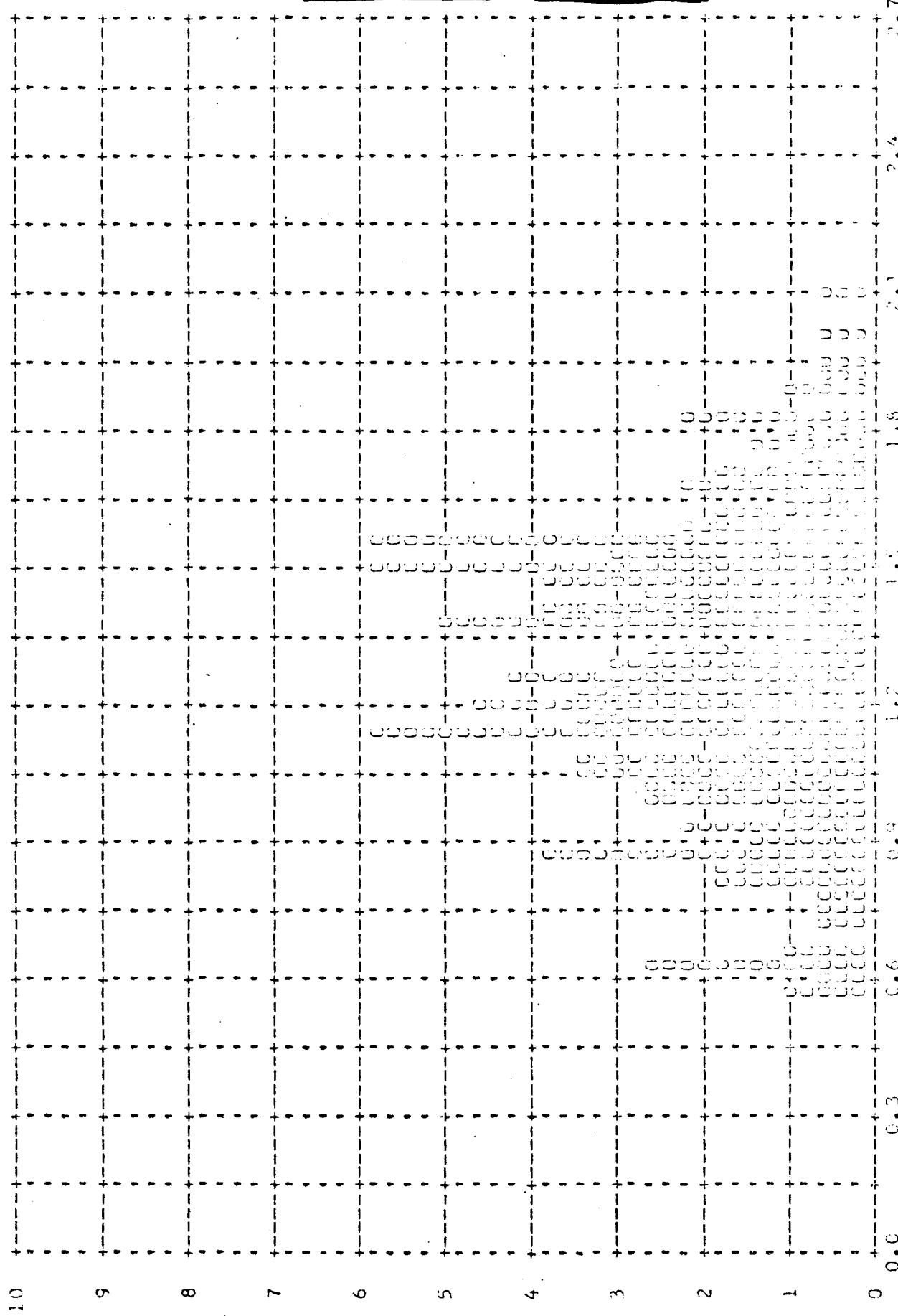


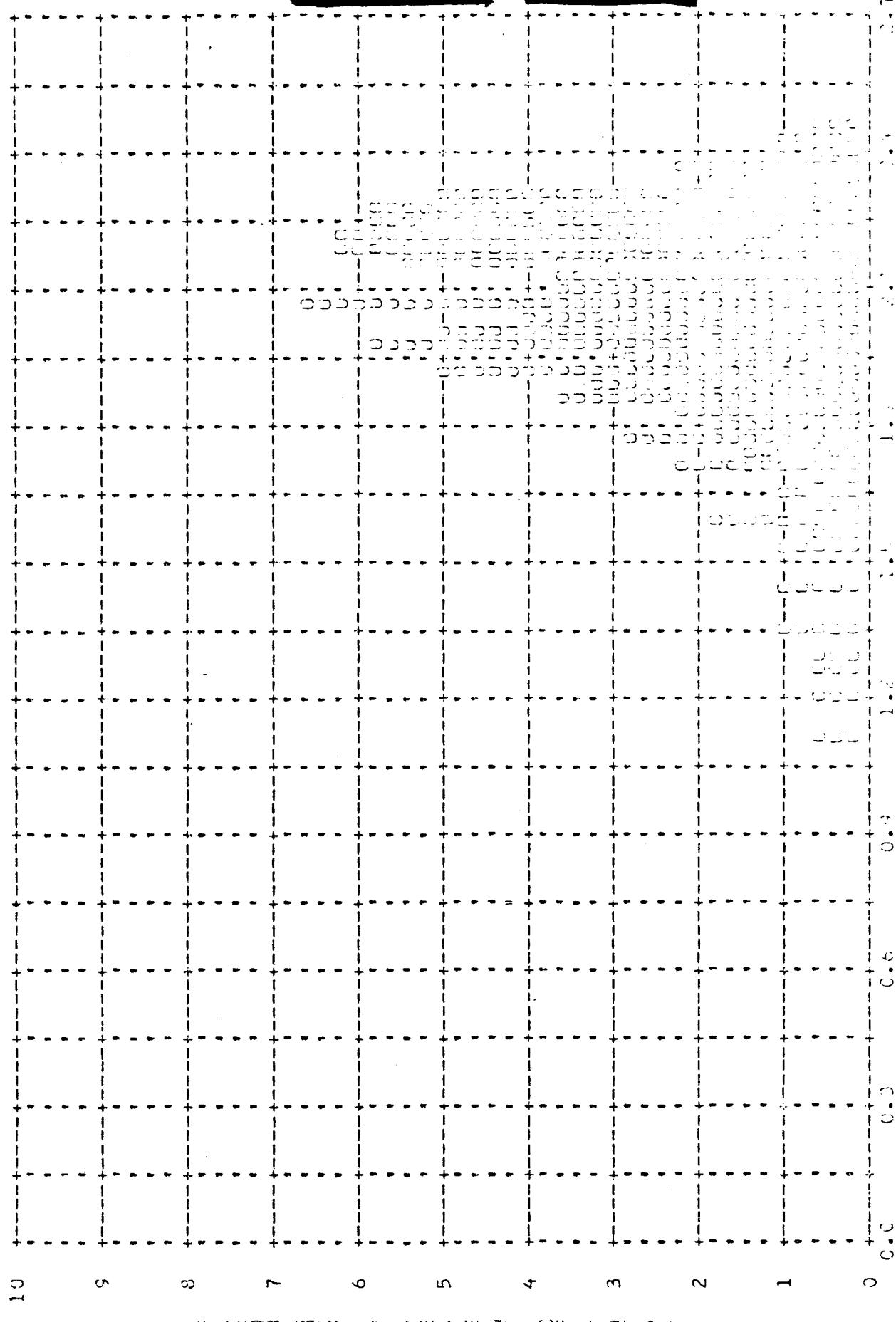
FIGURE A-4

MISSION * 1043-2 * INSTR * AFT * 1/9/68 PLCT OF D MAX * TERRAIN * PROCESSING * ALL LEVELS
ARITH MEAN * 1.27 * MEDIAN * 1.27 * STD DEV * 0.31 * RANGE * 0.55 TU 2.06 WITH 247 SAMPLES



~~TOP SECRET C~~

MISSION * 1C43-2 * INSTR * AFT * 1/9/69 PLCT OF C MAX * CLOUD * PROCESSING * ALL LEVELS
ARITH MEAN * 2.62 * MEDIAN * 2.06 * STD DEV * 0.24 * RANGE * 1.09 TO 2.46 WITH 228 SAMPLES



FREQUENCY * PERCENT C TOTAL

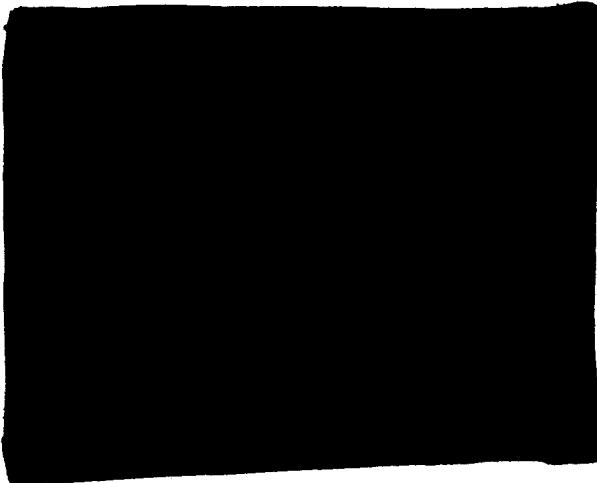
A-48

FIGURE A-4

~~TOP SECRET C~~

~~TOP SECRET C~~

Distribution:



~~TOP SECRET C~~